Coriolis mass flowmeter

TME
UMC4

Operating Manual

Please read the instructions carefully and store them in a safe place

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Introduction

I. Shipping and storage; product inspection

Shipping and storage
The device is to be safeguarded against dampness, dirt, impact and damage.

Product inspection
Upon receipt of the product, check the contents of the box and the product particulars against the information on the delivery slip and order form so as to ensure that all ordered components have been supplied. Notify us of any shipping damage immediately upon receipt of the product. Any damage claim received at a later time will not be honored.

II. Warranty

Your flowmeter was manufactured in accordance with the highest quality standards and was thoroughly tested prior to shipment. However, in the event any problem arises with your device, we will be happy to resolve the problem for you as quickly as possible under the terms of the warranty which can be found in the terms and conditions of delivery. Your warranty will only be honored if the device was installed and operated in accordance with the instructions for your device. Any mounting, commissioning and/or maintenance work is to be carried out by qualified and authorized technicians only.

III. Application domain the operating manual

The present manual applies to Coriolis mass flowmeters that are operated in conjunction with the UMC4 transmitter.

IV. Measures to be taken before sending your device to the manufacturer for repair

It is important that you do the following before shipping your flowmeter to Heinrichs Messtechnik GmbH for repair:

- Enclose a description of the problem with your device. Describe in as much detail as possible the application and the physical and chemical properties of the fluid.
- Remove any residues from the device and be sure to clean the seal grooves and recesses thoroughly. This is particularly important if the fluid is corrosive, toxic, carcinogenic, radioactive or otherwise hazardous.
- The operator is liable for any substance removal or personal damage costs arising from inadequate cleaning of a device that is sent for repair.

V. Supplementary operating instructions regarding the HART® interface

For information regarding operation of the transmitter using the HART® hand-held terminal, see “Operation of the UMC4 transmitter using the HART® hand-held terminal.”

VI. Operating manual of explosion-proof flowmeters

For installation of the sensor and transmitter within hazardous areas read „Operation manual of explosion-proof flowmeters “. It contains also all ex-relevant characteristic values for the sensors and the transmitter UMC4.

1. Steps prior to operation

It is essential that you read these operating instructions before installing and operating the device. The device is to be installed and serviced by a qualified technician only. The UMC4 transmitter is to be used exclusively to measure mass and volume flow, as well as liquid and gas density and temperature, in conjunction with a Heinrichs Messtechnik TM, TME, TMR or TMU sensor.

We plan to optimize and improve the products described and in so doing will incorporate not only our own ideas but also, and in particular, any suggestions for improvement made by our customers. If you feel that there is any way in which our products could be improved, please send your suggestions to the following address:

Heinrichs Messtechnik GmbH
HM-E (Development Department)
Headword: TME for the sensor
Headword: UMC4 for the transmitter

Robert-Perthel-Straße 9
D-50739 Köln

or:
via fax: +49 221 49708-4214
via E-mail: info@heinrichs.eu

We reserve the right to change the technical data in this manual in the light of any technical progress that might be made. For updates regarding the product, visit our website at www.heinrichs.eu, where you will also find contact information for the Heinrichs Messtechnik distributor nearest you. For information regarding our own sales operations, contact us at info@heinrichs.eu.

1.1 Safety advisory for the user

The present document contains the information that you need in order to operate the product described herein properly. The document is intended for use by qualified personnel. This means personnel who are qualified to operate the device described herein safely, including electronics engineers, electrical engineers, or service technicians who are conversant with the safety regulations pertaining to the use of electrical and automated technical devices and with the applicable laws and regulations in their own country.

Such personnel must be authorized by the facility operator to install, commission and service the product described herein, and are to read and understand the contents of the present operating instructions before working with the device.

1.2 Hazard warnings

The purpose of the hazard warnings listed below is to ensure that device operators and maintenance personnel are not injured and that the flowmeter and any devices connected to it are not damaged.

The safety advisories and hazard warnings in the present document that aim to avoid placing operators and maintenance personnel at risk and to avoid material damage are prioritized using the terms listed below, which are defined as follows in regard to these instructions herein and the advisories pertaining to the device itself.

1.2.1 Danger

means that failure to take the prescribed precautions **will result** in death, severe bodily injury, or substantial material damage.

1.2.2 Warning

means that failure to take the prescribed precautions **could result** in death, severe bodily injury, or substantial material damage.

1.2.3 Caution

means that failure to take the prescribed precaution could result in bodily injury, or a material damage.

1.2.4 Note

means that the accompanying text contains important information about the product, handling the product or about a section of the documentation that is of particular importance.

1.3 Proper use of the device

A Coriolis Mass Flow Sensor is intended for use solely for direct and continuous mass flow measurement of liquids and gases, irrespective of their conductivity, density, temperature, pressure, or viscosity. The sensor is also intended for use for the direct and continuous mass flow measurement of chemical fluids, suspensions, molasses, paint, varnish, lacquer, pastes and similar materials.

Warning
The operator is responsible for ensuring that the material used in the sensor and housing is suitable and that such material meets the requirements for the fluid being used and the ambient site conditions. The manufacturer accepts no responsibility in regard to such material and housing.

Warning
In order for the device to perform correctly and safely, it must be shipped, stored, set up, mounted operated and maintained properly.

1.4 Installation and servicing

The devices described in this manual are to be installed and serviced only by qualified technical personnel such as a qualified Heinrichs Messtechnik electronics engineer or service technician.

Warning
Before servicing the device, it must be completely switched off, and disconnected from all peripheral devices. The technician must also check to ensure that the device is completely off-circuit. Only original replacement parts are to be used.

Heinrichs Messtechnik GmbH accepts no liability for any loss or damage of any kind arising from improper operation of any product, improper handling or use of any replacement part, or from external electrical or mechanical effects, overvoltage or lightning. Any such improper operation, use or handling shall automatically invalidate the warranty for the product concerned.

In the event a problem arises with your device, please contact us at one of the following numbers to arrange to have your device repaired:

Phone: +49 221 49708-0
Fax: +49 221 49708-178

Contact our customer service department if your device needs repair or if you need assistance in diagnosing a problem with your device

1.5 Returning your flowmeter for servicing or calibration

Before sending your flowmeter back to us for servicing or calibration, make sure it is completely clean. Any residues of substances that could be hazardous to the environment or human health are to be removed from all crevices, recesses, gaskets, and cavities of the housing before the device is shipped.

Warning
The operator is liable for any loss or damage of any kind, including personal injury, decontamination measures, removal operations and the like that are attributable to inadequate cleaning of the device.

Any device sent in for servicing is to be accompanied by a certificate as specified in Section 21 *Decontamination certificate for device cleaning***.**

The device is to be accompanied by a document describing the problem with the device. Please include in this document the name of a contact person that our technical service department can get in touch with so that we can repair your device as expeditiously as possible and therefore minimize the cost of repairing it.

1.6 Replacement of the transmitter electronics

Before replacing the transmitter electronics, read the safety instructions in Section 1.4 Installation and servicing on page 12.

The data memory chip (DAB) with the calibrating data of the sensor is an integral component of the control unit (display BE4). Removal and installation is described in chapter 7.2.1 DSB data memory module on page 32.

At an exchange of transmitter electronics, all electronics board must be exchanged. That comprises all circuit boards in the electronic compartment and in the terminal compartment. The overall accuracy of the measurement up to the analogous outputs is only guaranteed in such a way. Only the control unit with the integrated memory for the calibrating data of the sensor remains in the device.

Caution
The complete insert is to be replaced with all of its printed boards (except for the memory module). This is particularly important for the explosion-proof transmitter. The specified precision and interchangeability of the electronics are only guaranteed if the complete insert is replaced.

2. Maintenance

2.1 Transmitter

The transmitter is maintenance-free.

We recommend cleaning the sight-glass in regular intervals; check the enclosure for corrosion damages and the solid seat of the cable glands.

2.2 Coriolis mass flow sensor

The sensor is generally maintenance-free. The function only is influenced by corrosion or by deposits inside the inside of the measuring pipes. Therefore both have to be avoided mandatorily. Deposits have to be removed by suitably washing up or cleaning the internal pipes and splitter. Otherwise the measuring precision cannot be obtained.

Danger

In the case of a loop breakage, e. g. due to corrosion, medium leaks, fills the enclosure. Medium can get into the mounted transmitter or terminal box also (particularly at high process pressures)!

The transmitter can stand under pressure, too.

Take care if there are:

- Visible discolourations or humidity condensation at the sight-glass of the transmitter,
- corrosion damages to the enclosure,
- deformation of the sensor enclosure.

3. Identification

Manufacturer	Heinrichs Messtechnik GmbH Robert-Perthel-Straße 9 D-50739 Köln Phone: +49 221 49708-0 Fax: +49 221 49708-178 Internet: www.heinrichs.eu E-mail: info@heinrichs.eu
Product type	Mass flowmeter for liquid and gaseous products
Product name	Sensor type TME Transmitter type UMC4, suitable for TM, TME, TMR and TMU Coriolis mass flowmeters
Version no.	3.0, dated December 20, 2010

4. The TME sensor

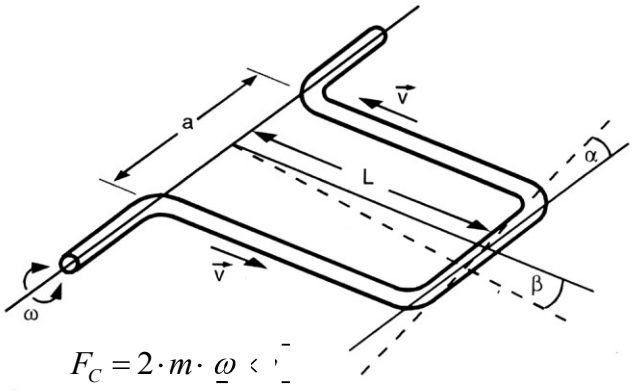
4.1 Application domain of the TME sensor

The sensor is intended for use solely for direct and continuous mass flow measurement of liquids and gases, irrespective of their conductivity, density, temperature, pressure, or viscosity. The sensor is also intended for use for the direct and continuous mass flow measurement of chemical fluids, suspensions, molasses, paint, varnish, lacquer, pastes and similar materials.

4.2 Mode of operation

4.2.1 Measuring principle

The Coriolis mass flowmeter is based on the principle whereby in a rotating system a force (known as the Coriolis force) is exerted on a mass at a rotation point that is moving towards or away from this point.



$$F_C = 2 \cdot m \cdot \underline{\omega} \times \underline{v}$$

4.2.2 System configuration

The flowmeter consists of a sensor that is mounted in a pipe, and a transmitter (see Section 6 Application domain of the UMC4 on pp. 31), that can be directly mounted on the sensor or installed separately (e.g. on a wall).

The transmitter oscillates the flow tubes in the sensor over a excitation coil and picks up, via the sensor coil, the measuring signal which is proportional to the mass flow. After being temperature compensated, the measuring signal is converted into an analog output signal that is consistent with the measuring range setting.

4.2.3 Input

Measured variables: mass flow, density, temperature; volume flow is calculated

4.3 Performance characteristics of the TME sensor

4.3.1 Reference conditions

- Established flow profile
- Inlet section has to correspond to mounting length
- Operation is to be realized in the presence of downstream control valves
- Measurement is to be realized in the absence of any gas bubbles
- Flow tubes are to be kept clean at all times
- Process temperature is to be regulated as specified in Section 4.5.1 Process temperature on page 24
- Process pressure is to be regulated as specified in Section 4.5.6 Process pressure range on page 24
- Ambient temperature is to range from + 10 °C to + 30 °C (50 °F to 86 °F)
- Warm-up period: 15 minutes
- Standard calibration is to be realized at 20 %, 50 % and 100 % (three times each)
- High-frequency interference is to be regulated as specified in Section 19.2 Ex-Approval transmitter on page 109

4.3.2 TME flow ranges

	Min. measuring range	Max. measuring range	Nominal (Δp=1bar)	Zero point stability (of range)
Model	kg/h [lbs/min]	kg/h [lbs/min]	kg/h [lbs/min]	kg/h [lbs/min]
TME008	60 [2,2]	600 [22,0]	370 [13,6]	0,06 [0,00]
TME010	250 [9,2]	2.500 [91,9]	1.250 [45,9]	0,25 [0,01]
TME020	1.200 [44,1]	12.000 [440,9]	6.000 [220,5]	1,2 [0,0]
TME025	3.000 [110,2]	30.000 [1.102,3]	19.000 [698,1]	3 [0,1]
TME080	6.000 [220,5]	60.000 [2.204,6]	60.000 [2.204,6]*	6 [0,2]

* (Δp=0,89bar)

Reference conditions: in conformity with IEC 770:
Temperature: 20 °C, relative humidity: 65 %, air pressure: 101.3 kPa
Fluid: water

4.3.3 Density measurement

The attainable accuracy depends on the selected calibration type.

Without calibration no density measurement is possible and the empty pipe recognition is not available!

	Density accuracy		
Model	without	3-Point	5-Point
TME008	not available	5 g/l	2 g/l
TME010		5 g/l	2 g/l
TME020		5 g/l	1 g/l
TME025		5 g/l	1 g/l
TME080		5 g/l	1 g/l

4.3.4 Accuracy

Mass flow	**Fluids**
Accuracy TME 008 to TME 080	± 0.15% of actual flow ± zero point stability (see Section 4.3.2 TME flow ranges)
Repeatability error	± 0.05% of actual flow (sensor with transmitter) ± ½ zero point stability (see Section 4.3.2 TME flow ranges)
Mass flow	**Gases**
Accuracy TME 008 to TME 080	± 0.5% of actual flow ± zero point stability (see Section 4.3.2 TME flow ranges)
Repeatability error	± 0.25% of actual flow (sensor with transmitter) ± ½ zero point stability (see Section 4.3.2 TME flow ranges)
Additional measured values	
Volume flow	± 0.2 % of actual value + zero point stability
Temperature	± 0.5 °C
Hysteresis	n/a
Settling time	1 to 15 seconds
Startup drift	15 minutes
Long-term drift	± 0.02 % of upper-range value per year
Influence of ambient temperature	± 0.005 % per K
Influence of fluid temperature	Compensated
Influence of fluid pressure	For fluids: too small to be relevant

4.3.5 Pressure loss TME

Model	Min. measuring range	Max. measuring range	Pressure drop [water (20°C), 1 mPas]				
TME008	60 kg/h	600 kg/h	60 kg/h	150 kg/h	300 kg/h	450 kg/h	600 kg/h
			0,04 bar	0,20 bar	0,70 bar	1,47 bar	2,50 bar
TME010	120 kg/h	2.500 kg/h	120 kg/h	625 kg/h	1.250 kg/h	1.875 kg/h	2.500 kg/h
			0,01 bar	0,28 bar	1,00 bar	2,13 bar	3,66 bar
TME020	600 kg/h	12.000 kg/h	600 kg/h	3.000 kg/h	6.000 kg/h	9.000 kg/h	12.000 kg/h
			0,01 bar	0,28 bar	1,05 bar	2,28 bar	3,98 bar
TME025	3.000 kg/h	30.000 kg/h	3.000 kg/h	7.500 kg/h	15.000 kg/h	22.500 kg/h	30.000 kg/h
			0,03 bar	0,17 bar	0,66 bar	1,46 bar	2,56 bar
TME080	6.000 kg/h	60.000 kg/h	6.000 kg/h	15.000 kg/h	30.000 kg/h	45.000 kg/h	60.000 kg/h
			0,01 bar	0,06 bar	0,23 bar	0,50 bar	0,89 bar

Model	Min. measuring range	Max. measuring range	Pressure drop [water (20°C), 1 mPas]				
TME008	2,2 lbs/min	22,0 lbs/min	2,2 lbs/min	5,5 lbs/min	11,0 lbs/min	16,5 lbs/min	22,0 lbs/min
			0,58 psi	2,90 psi	10,15 psi	21,32 psi	36,26 psi
TME010	4,4 lbs/min	91,9 lbs/min	4,4 lbs/min	23,0 lbs/min	45,9 lbs/min	68,9 lbs/min	91,9 lbs/min
			0,15 psi	4,06 psi	14,50 psi	30,89 psi	53,08 psi
TME020	22,0 lbs/min	440,9 lbs/min	22,0 lbs/min	110,2 lbs/min	220,5 lbs/min	330,7 lbs/min	440,9 lbs/min
			0,15 psi	4,06 psi	15,23 psi	33,07 psi	57,73 psi
TME025	110,2 lbs/min	1.102,3 lbs/min	110,2 lbs/min	275,6 lbs/min	551,1 lbs/min	826,7 lbs/min	1.102,3 lbs/min
			0,44 psi	2,47 psi	9,57 psi	21,18 psi	37,13 psi
TME080	220,5 lbs/min	2.204,6 lbs/min	220,5 lbs/min	551,1 lbs/min	1.102,3 lbs/min	1.653,4 lbs/min	2.204,6 lbs/min
			0,15 psi	0,87 psi	3,34 psi	7,25 psi	12,91 psi

4.3.6 Ambient temperature

− 40 °C to + 60 °C (-40 °F to 140 °F), as special version up to 80 °C (176 °F)

4.3.7 Ambient temperature range

− 40 °C to + 60 °C (-40 °F to 140 °F); a special cable and cable glands are required for temperatures below − 20 °C (-4 °F) and above 70 °C (158 °F)

4.3.8 Storage temperature

− 25 °C to + 60 °C (-13 °F to 140 °F), − 40 °C (-40°F) available as special version

4.3.9 Climatic category

In conformity with IEC 654-1. Unsheltered class D locations with direct open-air climate.

4.3.10 Ingress protection

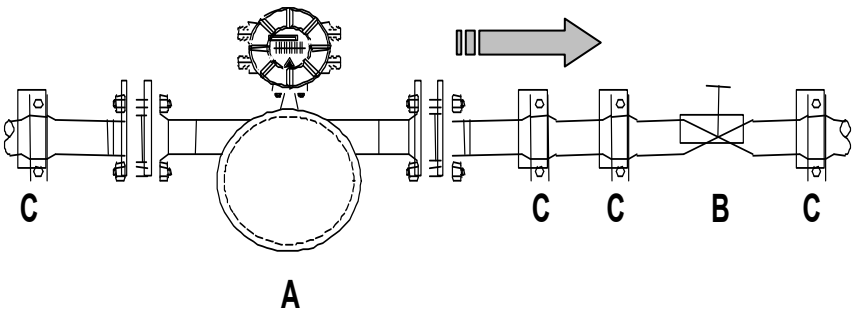
Standard version: IP 66 (NEMA 6); special version IP 68 (NEMA 6P) DIN EN 60529, if suitable and tightly screwed down cable glands are used.

4.4 Operating conditions

4.4.1 Installation

The sensor is to be protected, wherever possible, against valves, manifolds and similar fittings that generate turbulence. The sensor is to be installed in accordance with the following instructions.

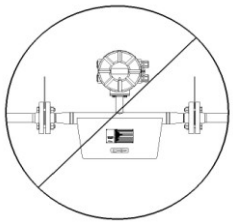
Diagram showing flowmeter installation



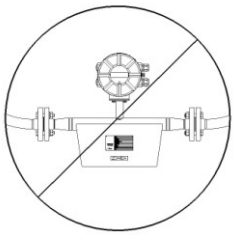
Flowmeter installation: A = sensor, B = valve, C = pipe clamps and supports

Warning:
The screw of the flanges must not be fixed by using a hammering screwdriver!
Sensor will be damaged by shocks.

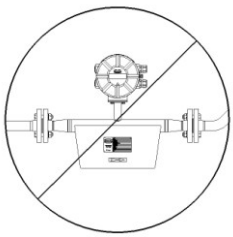
Under no circumstances is the sensor to be used to support a pipe.



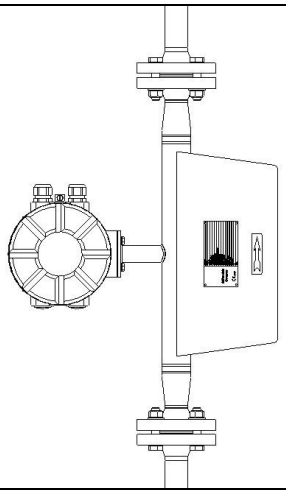
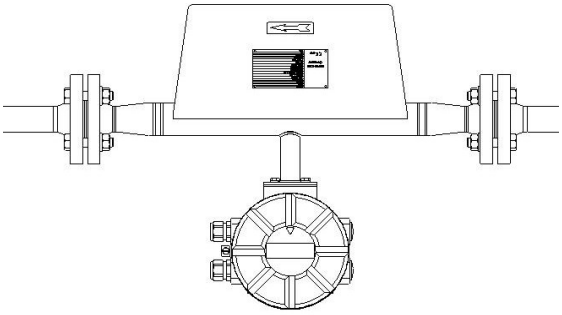
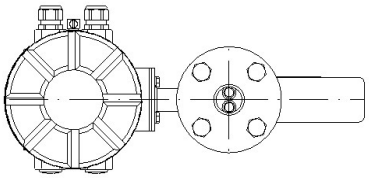
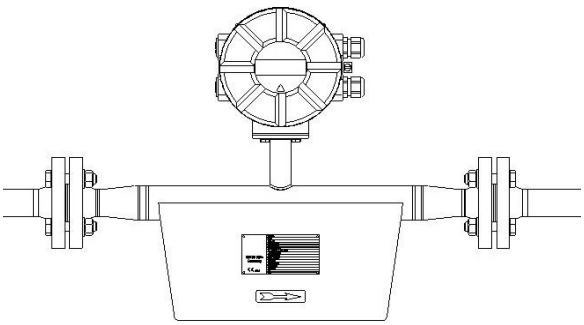
Do not install the sensor in suspended pipes.



Do not adjust the position of a pipe by pulling or grasping the sensor.



4.4.2 Installation positions

Standard installation position	
Installation position A	
Installation position B	
Installation position C	

4.4.3 Assessment of installation position

Type of fluid	Position	Assessment
Pure liquids	Standard installation position	Self-draining flow tubes
	Position A or B	OK
	Position C	Liquid residue remains in pipe
Liquids with gas bubbles	Standard installation position	Self-draining flow tubes, gas bubbles do not accumulate in flowmeter
	Position A	Not recommended owing to gas bubble accumulation in flowmeter
	Position B	Gas bubbles may accumulate in the presence of low flow velocities
	Position C	No gas bubble accumulation in flowmeter, liquid residues may remain in device after discharge
Liquids containing substances that could form deposits	Standard installation position	Self-draining flow tubes, no deposit formation
	Position A	OK
	Position B	Substances in the liquid could form deposits at low flow velocities
	Position C	Not recommended owing to presence in flowmeter of substances that could form deposits
Liquids containing gas bubbles, as well as gas bubbles containing substances that could form deposits	Standard installation position	Self-draining flow tubes, no accumulation of gases or substances that could form deposits
	Position A	Not recommended owing to gas bubble accumulation in flowmeter
	Position B	Gas bubbles or substances that could form deposits at low flow velocities
	Position C	Not recommended owing to presence in flowmeter of substances that could form deposits
Gases that do not form a condensate	Standard installation position, Position A, B or C	Any of these installations positions can be used
Gas, condensate-forming gas/liquid, moisture	Standard installation position	Flow direction should be from top to bottom so that any condensate that forms can flow out efficiently
	Position A	OK
	Position B	Condensate might form in flowmeter
	Position C	Not recommended owing to condensate accumulation in flowmeter

Type of fluid	Position	Assessment
Slurries	Standard installation position	Optimal installation position
	Position A	High density substances could accumulate in the flowmeter
	Position B	Gas bubbles could accumulate
	Position C	Gas bubbles or high density substances could accumulate in the flowmeter

4.4.4 Pressure surges

Pressure surges in a pipe could be provoked by a sudden decrease in flow caused by rapid closing of a valve or similar factors. This change in pressure can lead to underpressure downstream from a valve that has been closed rapidly, and to outgasing. If the valve is mounted directly on the inlet section of the flowmeter, a gas bubble can form in the flow tube that can cause a measuring signal disturbance that would shift the zero point of the output signal. In extreme cases, a pressure surge could cause mechanical damage to the sensors and/or flow tube.

Whenever possible, quick-closing valves should be mounted downstream from the sensor. If this is not feasible, such valves are to be mounted a minimum of 10 x DIA (Φ) from the nearest sensor. Alternatively, valve closing speed can be reduced.

4.4.5 Using the device with hazardous fluids

The sealing technology used in the standard mass flowmeter renders the device unsuitable for use with hazardous fluids. Only sensors that meet the standards for safety instruments are suitable for use with hazardous fluids.

The pathway between the sensor and transmitter must be pressure-tight so as to prevent fluid from leaking out of a sensor in the event a sensor develops a defect.

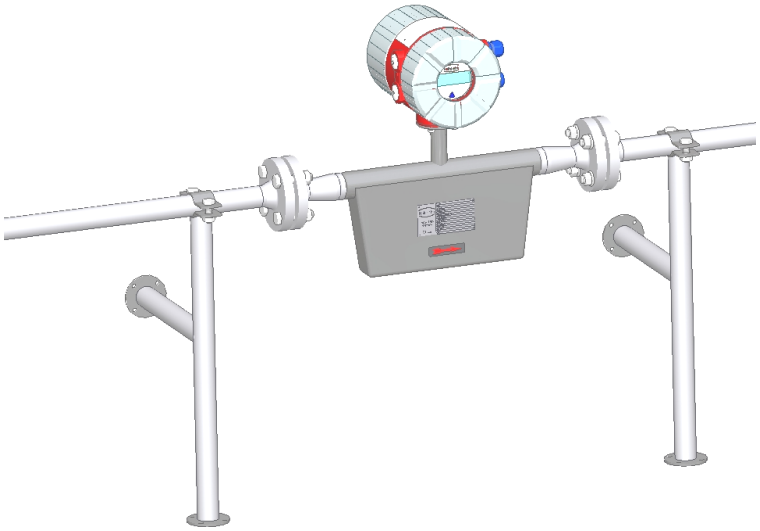
In the case of welded components, a colored liquid penetration test should be performed on the welds, or one joint (only the first one) should be x-rayed. Alternatively, an internal pressure monitoring device can be used to detect any defect.

4.4.6 Vibration stability

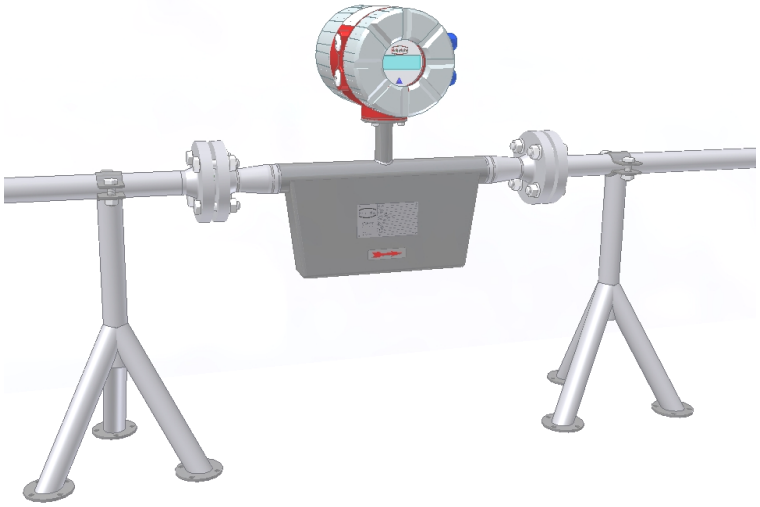
The sensors are insensitive to vibration; vibration stability has been validated in accordance with DIN IEC 68-2-6, for up to 1 g at 10 to 150 Hz.

If pipe vibration is greater than 1 g in the 5-2000 Hz range, an additional fastening is to be mounted as shown in the following drawings. This fastening will prevent vibration from affecting the device's mechanical configuration and/or measurement readings. The following drawings are valid for a sensor with a nominal size of approximately DN 040 (2”). Installation is to be realized as shown in this drawing.

Installation using wall supports



Foot-mounted installation



4.5 Process conditions

4.5.1 Process temperature

− 40 °C to + 180 °C (-40 °F to 356 °F); rating plate range must be observed

4.5.2 Physical state

Liquid product (maximum density 2 kg/l)
Gaseous product (minimum density 0.002 kg/l in operating state)

4.5.3 Viscosity

0.3 up to 50,000 mPas (0.3 to 50,000 cP)

4.5.4 Gas content

The use of products containing gas is not allowed for custody transfer operations. In other applications, the presence of gas will increase false readings. In order for the readings of products containing gas to be valid, small gas bubbles must be homogeneously distributed in the fluid. Large gas bubbles will automatically provoke extremely false readings and will shift the zero point. Thus, the extent to which readings are false is determined by the process conditions. A rule of thumb in this regard is as follows: A 1 % gas component will increase false readings by 1 %. The gas component is not to exceed 5 %.

4.5.5 Process temperature range

+ 180 °C (356 °F)

4.5.6 Process pressure range

According to PN16 pressure rating: 16 bar and PN40: 40 bar

4.5.7 Outlet pressure

Outlet pressure must be greater than the vapor pressure ps of the measured product.

4.6 Connection to the transmitter

4.6.1 Integral mount configuration

When the transmitter is mounted directly on the sensor, no cable connection between the two components is needed. This connection is integrated at the factory.

4.6.2 Remote mount configuration

If the transmitter is not mounted directly on the sensor, installation regulations and applicable legal standards are to be adhered to. The maximum cable length is 300 m (1000ft). See Section 12.5.2 Wiring diagram on page 42 for information regarding the connection and cable specifications.

4.7 Construction details

4.7.1 Dimensions and weight

Standard versions:

		A	B				C	F	G
			Integral Mount Transmitter		Remote Mount Transmitter				
			-40°C - 100°C (-40°F to 212°F)	-40°C - 150°C (-40°F to 302°F)	-40°C - 100°C (-40°F to 212°F)	-40°C - 180°C (-40°F to 356°F)			
Model	**Endconnection**	mm [inch]	mm [inch]	mm [inch]	mm [inch]	mm [inch]	mm [inch]	mm [inch]	mm [inch]
TME008	DN10 PN40 ASME ½" Cl150/300	300 [11.8]	394 [15.5]	496 [19.5]	265 [10.4]	367 [14.4]	113 [4.4]	58 [2.3]	105 [4.1]
TME010	DN15 PN40 ASME ¾" Cl150/300	300 [11.8]	394 [15.5]	496 [19.5]	265 [10.4]	367 [14.4]	113 [4.4]	58 [2.3]	105 [4.1]
TME020	DN25 PN40 ASME 1" Cl150/300	400 [15.7]	461 [18.1]	563 [22.2]	332 [13.1]	434 [17.1]	173 [6.8]	65 [2.6]	113 [4.4]
TME025	DN50 PN40 ASME 2" Cl150/300	500 [19.7]	502 [19.8]	604 [23.8]	373 [14.7]	475 [18.7]	206 [8.1]	65 [2.6]	113 [4.4]
TME080	DN80 PN40 ASME 3" Cl150/300	600 [23.6]	588 [23.1]	690 [27.2]	459 [18.1]	561 [22.1]	290 [11.4]	77 [3.0]	137 [5.4]

Weight:

		Weight	
		Sensor	**Transmitter**
Model	**DN**	kg [lbs]	kg [lbs]
TME008	10	13 [28,7]	4,5 [9,9]
TME010	15	13 [28,7]	
TME020	25	20 [44,1]	
TME025	50	27 [59,5]	
TME080	80	50 [110,2]	

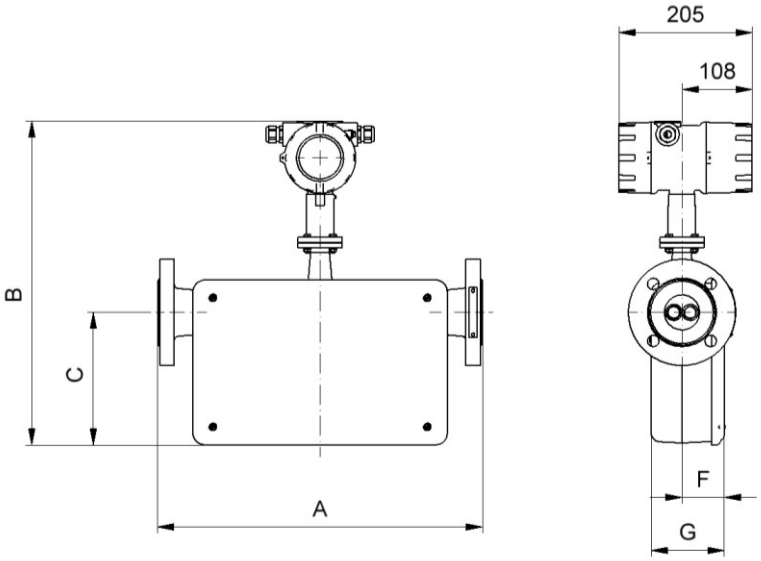
Heated versions:

	K	**L**	**M**
Model	mm [inch]	mm [inch]	mm [inch]
TME008	138 [5,4]	215 [8,5]	20 [0,8]
TME010	138 [5,4]	215 [8,5]	20 [0,8]
TME020	138 [5,4]	280 [11,0]	30,5 [1,2]
TME025	216 [8,5]	306 [12,0]	30,5 [1,2]
TME080	216 [8,5]	403 [15,9]	48 [1,9]

4.7.2 Dimension drawing for the types TME 008 to TME 080

4.7.2.1 Standard version dimension drawing

Integral mount configuration that is suitable for process temperatures up to 100 °C (212°F):



For all the dimensions and weight, see Section 4.7.1 Dimensions and weight on page 25.

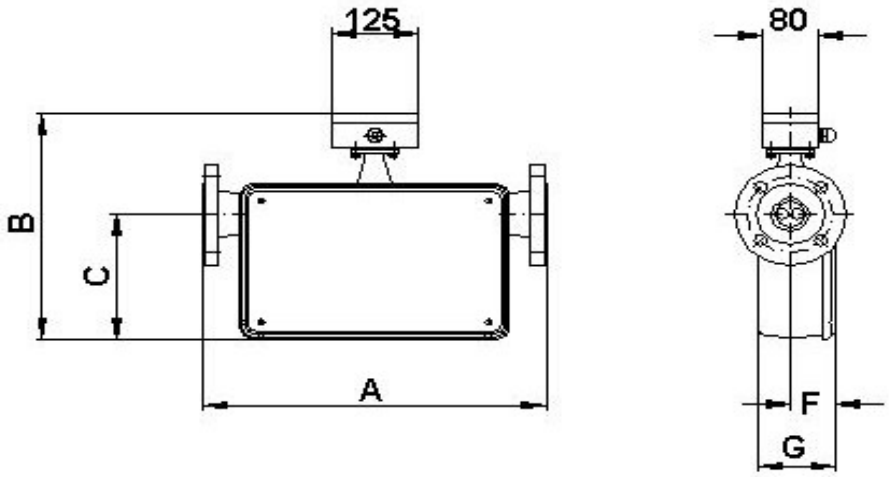
4.7.2.2 Integral mount version up to 150 °C (302 °F)

Integral mount configuration that is suitable for process temperatures up to 150 °C (302°F):

For all the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

4.7.2.3 Remote mount version dimension drawing

Remote mount configuration with junction box that is suitable for process temperatures up to 100 °C (212 °F):



For all the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

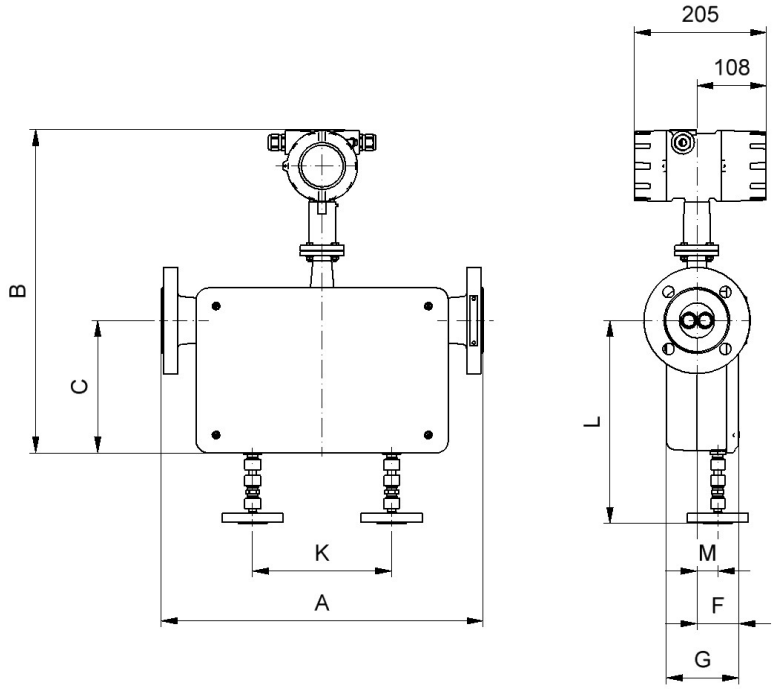
4.7.2.4 Remote mount version dimension drawing up to 180 °C (356 °F)

Remote mount configuration with junction box that is suitable for process temperatures up to 180 °C (356 °F):
For all the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

4.7.3 Heater dimension drawings for TME 008 up to TME 080

4.7.3.1 Standard Heater for integral mount version TME 008 to TME 050

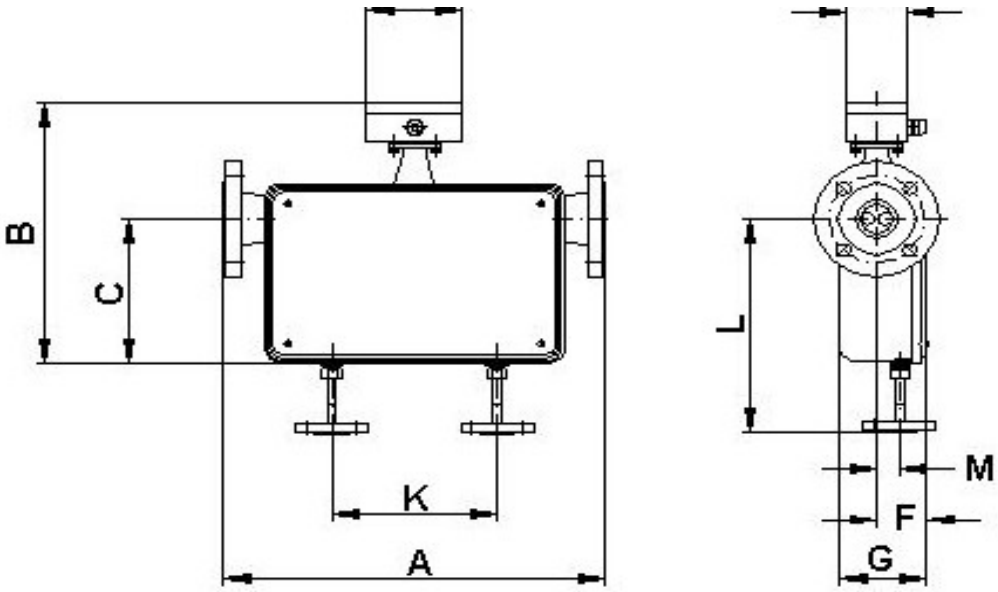
Integral mount configuration that is suitable for process temperatures up to 100 °C (212 °F):



For all the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

4.7.3.2 Heater for remote mount version TME 008 to TME 080

Remote mount configuration (with junction box) that is suitable for process temperatures up to 100 °C (212 °F):



For the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

4.7.3.3 Heater for remote mount version up to 180 °C (356 °F)

Remote mount configuration (with junction box) that is suitable for process temperatures up to 180 °C (356 °F):

For the dimensions and weights, see Section 4.7.1 Dimensions and weight on page 25.

4.7.4 Material

Sensor housing

TME up to DN080:	GGG 40.3 with stainless steel 1.4301 (304L) cover plate and plastic cover (max. 100 °C / 212 °F environment temperature)
Flow tubes:	1.4404 (316L)
Splitter:	1.4571 (316Ti)
Sealing strip	1.4404 (316L)
Flange:	GGG 40.3

4.8 Sensor TME approvals

4.8.1 Explosion protection

- Intrinsically safe sensor circuits
- DMT 01 **ATEX** E 149 X
- II 1/2G Ex ia IIC T6 – T2
- (Zone 0 permissible in flow tube)
- **FM** IS / I / 1 / A B C D / T* : CD 06100
- **CSA** IS / I / A B C D / T* : CD 06101
- **NEPSI Approval** Cert No. GYJ06476X

The explosion protection approvals are available on our website www.heinrichs.eu.

4.8.2 CE marking

See also section 20 “Declaration of conformity” on page 110

- Pressure Equipment Directive 97/23/EC
- Explosion Protection Directive 94/9/EC

4.8.3 Custody transfer operations

The declarations of conformity certifying Heinrichs Messtechnik flowmeters for custody transfer operations can be downloaded from our website at www.heinrichs.eu.

5. Commissioning

5.1 Zero point calibration

In order to ensure that precise measurements are obtained, zero point calibration is to be realized the first time the device is put into operation and before any regular operations are carried out. Zero point calibration is to be carried out using a fluid.

The zero calibration procedure is as follows:

- Install the sensor as described in the manufacturer's instructions.
- Check to ensure that the sensor is completely filled with fluid and that there are no gas bubbles in the flow tubes.
- Define the process conditions such as pressure, temperature and density.
- Close a potential shut-off device behind the sensor.
- Operate the transmitter in accordance with the instructions in Section 14.4.4 Zero point calibration on page 62.
- Make sure that sufficient time is allowed for the electronics to warm up.
- Allowing fluid to flow through the sensor during the zero calibration procedure will skew the zero point and result in false readings.

5.2 Startup conditions

The device is not subject to specific startup conditions. However, pressure surges should be avoided.

6. Application domain of the UMC4 transmitter

The microprocessor controlled UMC4 transmitter (hereinafter referred to as UMC4) for use with TM, TME TMR, and TMU sensors is a programmable transmitter that processes measurement data and displays and transmits various types of measurement results.

The UMC4 is communication enabled and supports the HART® protocol. The device can be customized using control unit BE4. Although basic configuration settings such as transmitter calibration are realized at the factory, other settings such as those for measurement data processing, analysis, display and output are user definable.

User settings are protected by a user definable password.

Settings that are essential for proper operation of the transmitter in conjunction with the sensor (e.g. calibration and initialization values) are accessible only to service technicians via a password that is not provided to customers.

7. UMC4 transmitter: mode of operation and configuration

7.1 Measuring principle

The Coriolis mass flowmeter is based on the principle whereby in a rotating system a force (known as Coriolis force) is exerted on a mass at a rotation point that is moving towards or away from this point. By configuring the sensor in a specific fashion, this force can be used to measure mass flow directly. The UMC4 transmitter evaluates the sensor signal (see Section 4.2.1 Measuring principle on page 15).

7.2 System configuration

Transmitter:
The UMC4 transmitter regulates the excitation of the sensor vibration system and processes the sensor signals. The standard model is equipped with two analog, passive 4 to 20 mA outputs, an impulse or frequency output and a status output, and is enabled for digital data transfer via the HART® protocol.

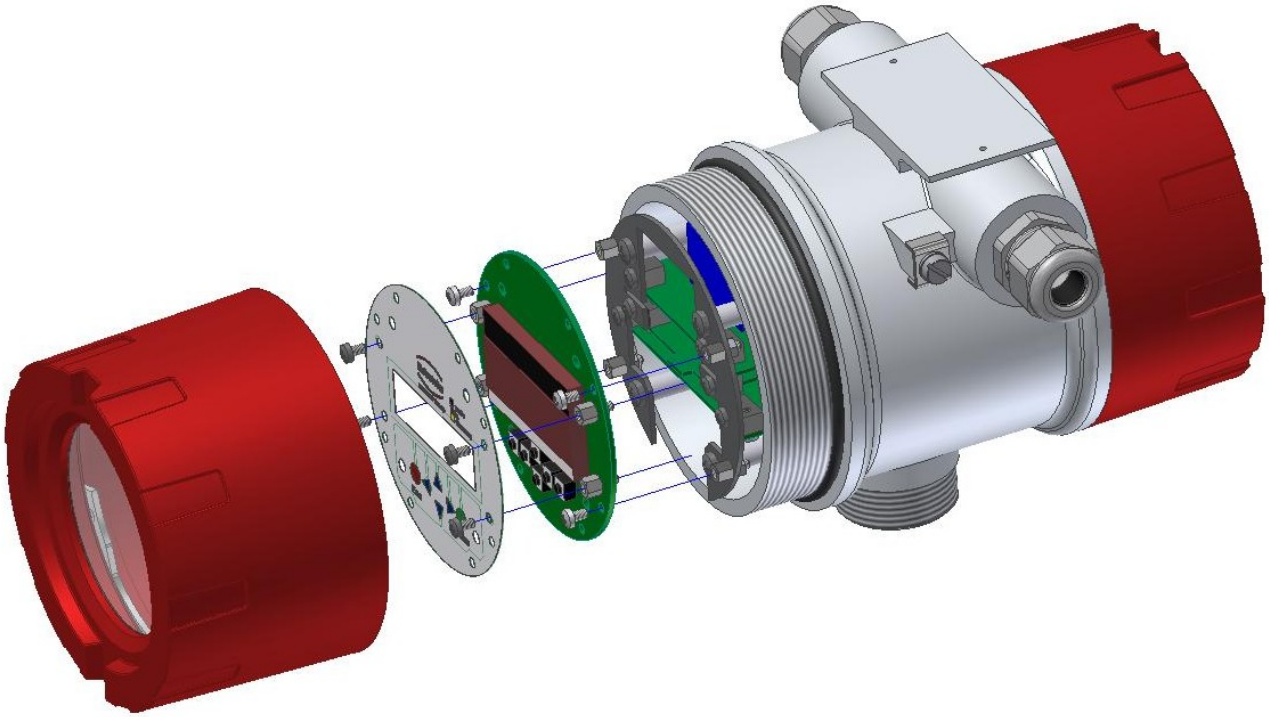
Sensor:
The TM, TME, TMR and TMU sensors measure flow, density and temperature in fluids. The device can be used to perform measurements with any liquid or gaseous product providing that the sensor material is suitable for the product being used.

7.2.1 DSB data memory module

The replaceable plug and play memory device is integrated on the printed board of the control unit and stores all sensor data such as sensor constants, model numbers, serial numbers, and so on. Consequently, the memory module is linked to the sensor. At an exchange of the transmitter's electronic, the control unit BE4 has to b e removed first and later on to be inserted into the exchanged electronic.

Warning
Make sure that you abide by the applicable standards and regulations pertaining to electrical devices, device installation and process technology when replacing the transmitter electronics. The highly integrated electronic components in the device carry the risk of ESD hazards and are only protected when installed in the device pursuant to EMC standards.

The removal and insertion of the control unit is made as in the following sketch is shown.
After removing 4 screws, the control unit with the display can be pulled out.



If the transmitter is replaced, the control unit should be transferred to the new transmitter. When the flowmeter is started up, the device continues using the values stored in the memory device. Thus, the DSB memory device provides maximum safety and comfort when device components are replaced.

The control units are not interchangeable arbitrarily between identically constructed transmitters because of the memory device. The exchange circuit boards must be ordered under equipment serial number specification at replacement demand. The calibrating data are stored with the delivery into the spare part of the manufacturer.

8. Input

8.1 Measured variable

Mass flow rate, temperature, density and volume flow (calculated from the preceding measured variables).

8.2 Measuring range

The measuring range, which varies according to which sensor (TM, TME, TMR or TMU) is used, can be found on the relevant data sheet or rating plate (see Section 4.3.2 TME flow ranges on page 16).

9. Output

9.1 Output signal

All signal outputs	Electrically isolated from each other and from ground
Analog outputs	2 x 4 to 20 mA passive (standard or Ex “i” [outputs i.s.])
	Current output 1: Mass flow, volume flow, density, temperature (when using the HART® protocol, output 1 is assigned to mass flow) Current output 2: Mass flow, volume flow, density, temperature
Pulse output (Binary output 1)	Pulse duration: default value 50 ms Pulse duration: adjustable range is 10 to 2000 ms Mark-to-space ratio is 1:1 if the set pulse duration is not reached.
	As a frequency output 1 kHz
	passive via optocoupler U_{nom} = 24 V U_{max} = 30 V I_{max} = 60 mA P_{max} = 1,8 W
Pulse value	settable in decade increments of selected pulse unit, e.g. kg or m³.
Status output	For: forward and reverse flow, MIN flow rate, MAX flow rate (Binary output 2): MIN density, MAX density, MIN temperature, MAX temperature, alarm
	Second pulse output (out of phase by 90°)
	Passive via optocoupler U_{nom} = 24 V U_{max} = 30 V I_{max} = 60 mA P_{max} = 1,8 W

9.2 Failure signal

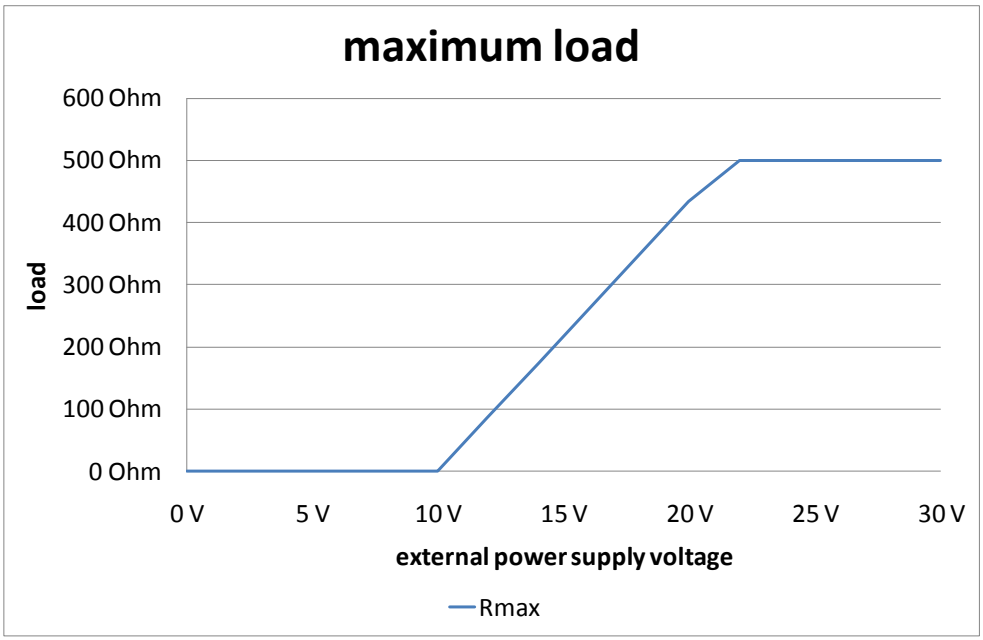
A failure in the meter can be indicated via the current outputs or the status output. The current outputs can be set to a failure signal (alarm) of I < 3.8 mA or I > 22 mA. The status output can be configured as make or brake contact.

9.3 Load

Standard version:	≤ 500 ohms
Explosion-proof version:	≤ 500 ohms
HART® minimum load:	> 250 ohms

10 V is the minimal needed voltage at passive current output terminals. The maximum voltage of 30 V must never exceed. The maximum load is calculated according to the formula:

$$R\max = \frac{U - 10V1}{23mA} \leq 500\Omega$$



9.4 Damping

Programmable from 1 to 60 seconds

9.5 Low flow cutoff

The low flow cutoff can be set to values between 0 and 20% using the software. The set value refers to the upper-range value. If the measured value is lower than the set volume, the flow rate will set to 0.0 (kg/h). This results in the analog output being set to 0/4 mA, and the pulse output will stop generating pulses.

10. UMC4 performance characteristics

10.1 Reference conditions

In conformity with IEC 770
Temperature: 20 °C (68 °F), relative humidity: 65 %, air pressure: 101.3 kPa (14.7 psi)

10.2 Measured error

Measured error and zero point stability see sensor data sheet or Section 4.3.2 TME flow ranges on page 16.

10.3 Repeatability error

± 0.05 % of actual value (sensor with transmitter)

10.4 Influence of ambient temperature

± 0.05 % per 10 K

11. UMC4 operating conditions

11.1 Installation conditions and cable glands

The integral mount version of the UMC4 transmitter in the SG4 housing is to be installed in accordance with Section 4.4.1 Installation on page 19. If the UMC4 transmitter is installed separately, a vibration-free installation site must be ensured.

	**Warning:** Additional cable glands: They are not contained in the scope of supply. The operator is responsible for the fact that according to the enclosure and ignition enclosure certified cable glands or screws are used. The kind of the thread is stamped on the rating plate. At the connection between sensor and transmitter a metalized cable gland must be used for the screen. (See 12.5.2.2 “Wiring diagram for the remote mount configuration of sensor and UMC4” page 43)

11.2 NPT cable glands

The transmitter housing SG4 is designed with M20x1.5 threads for cable glands. For cable glands with NPT thread, the manufacturer adds certified matching NPT adapters. These NPT adapters are directly mounted at the SG4 transmitter housing.

	**Danger**: NPT adapters mounted by the manufacturer may never be loosened by customer! In case of not properly tightened adapters, the protection class Ex-d is not guaranteed!

11.3 Environmental conditions

11.3.1 Ambient temperature

− 20 °C to + 60 °C (-4 °F to 140 °F), below 0 °C (32 °F) the readability of the LC display will be limited

11.3.2 Ambient temperature range

− 20 °C to + 60 °C (-4 °F to 140 °F)

11.3.3 Storage temperature

−25 °C to + 60 °C (-13 °F to 140 °F)

11.3.4 Ingress protection

Standard housing SG4, IP 68 (NEMA 6P)
Explosion-proof electronics housing
Terminal compartment: with terminals and “Increased safety” type of protection.

	**Warning:** Ingress protection IP 68 is only achieved if suitable and tightly screwed down cable glands or conduit are used. If the cable glands are only tightened manually water may leak into the terminal compartment in the housing.

	**Danger:** Particular care must be taken if the housing’s window becomes fogged or discolored because moisture, water or product might seep through the wire sheath into the transmitter’s housing.

	**Warning** Electromagnetic compatibility is only achieved if the electronics housing is closed. Leaving the enclosure open can lead to electromagnetic disturbances.

11.4 Process conditions

11.4.1 Fluid temperature

− 40 °C to + 260 °C (-40 °F to 500 °F)
The data sheet/rating plate of the connected transmitter must be observed.

11.4.2 Physical state

Liquid product (maximum density 2 kg/l (125lb/ft³))
Gaseous product (minimum density 0.002 kg/l in operating state)

11.4.3 Viscosity

0.3 to 50,000 mPas (0.3 to 50,000cP)
The data sheet of the connected transmitter must be observed.

11.4.4 Fluid temperature limit

260 °C (500 °F)
The data sheet of the connected transmitter must be observed.

11.4.5 Flow rate limit

See sensor data sheet in Section 4.3.2 TME flow ranges on page 16.

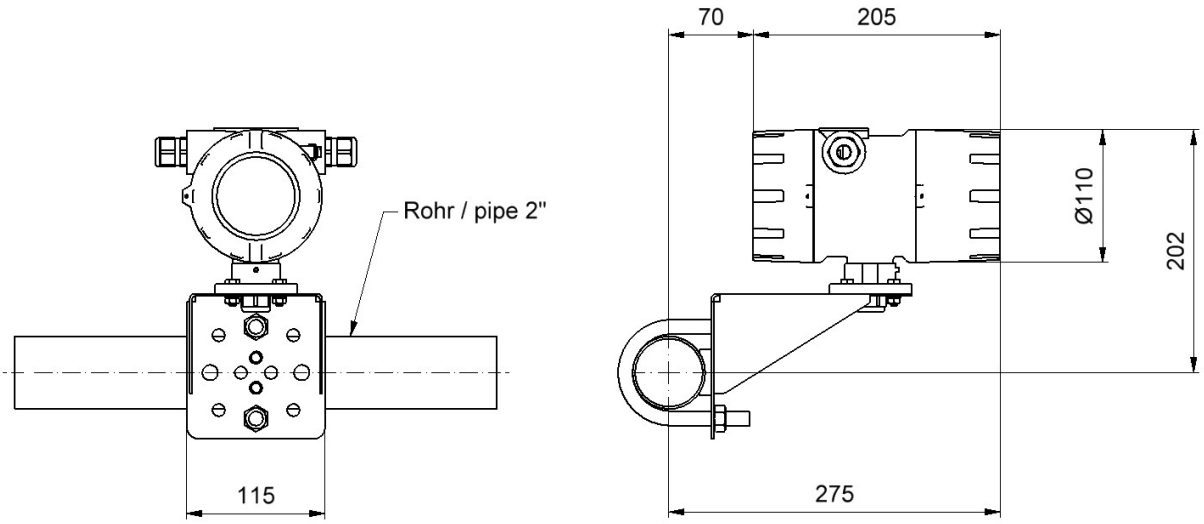
11.4.6 Pressure loss

See sensor data sheet in Section 4.3.5 Pressure loss TME on page 18.

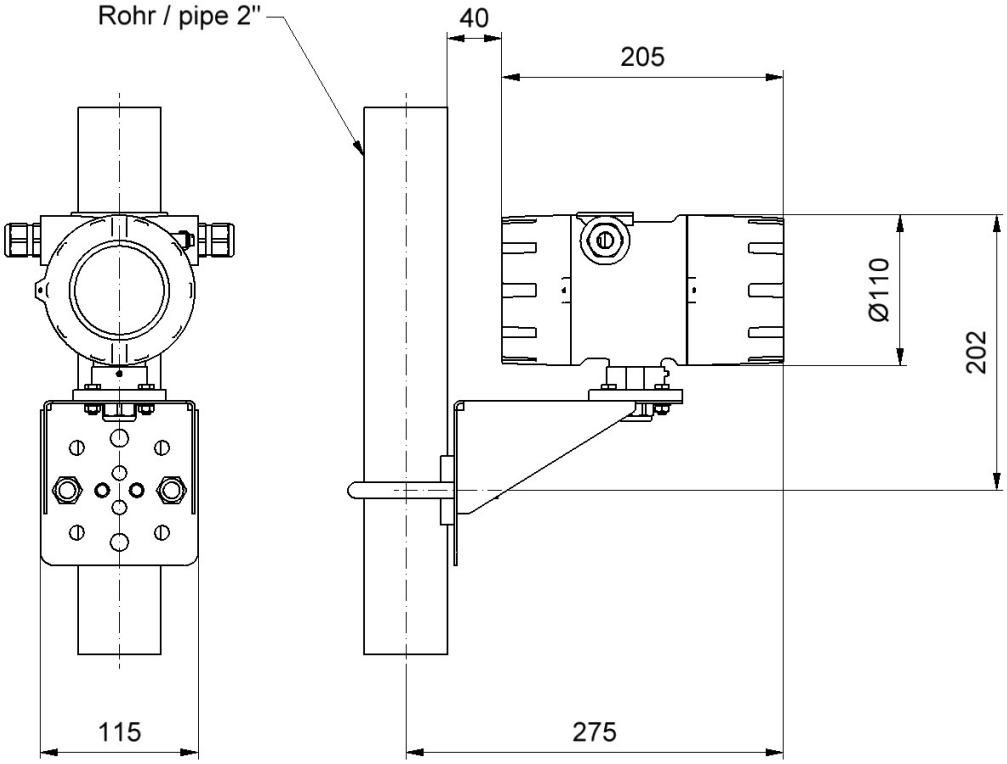
12. Construction details

12.1 Type of construction/dimensions

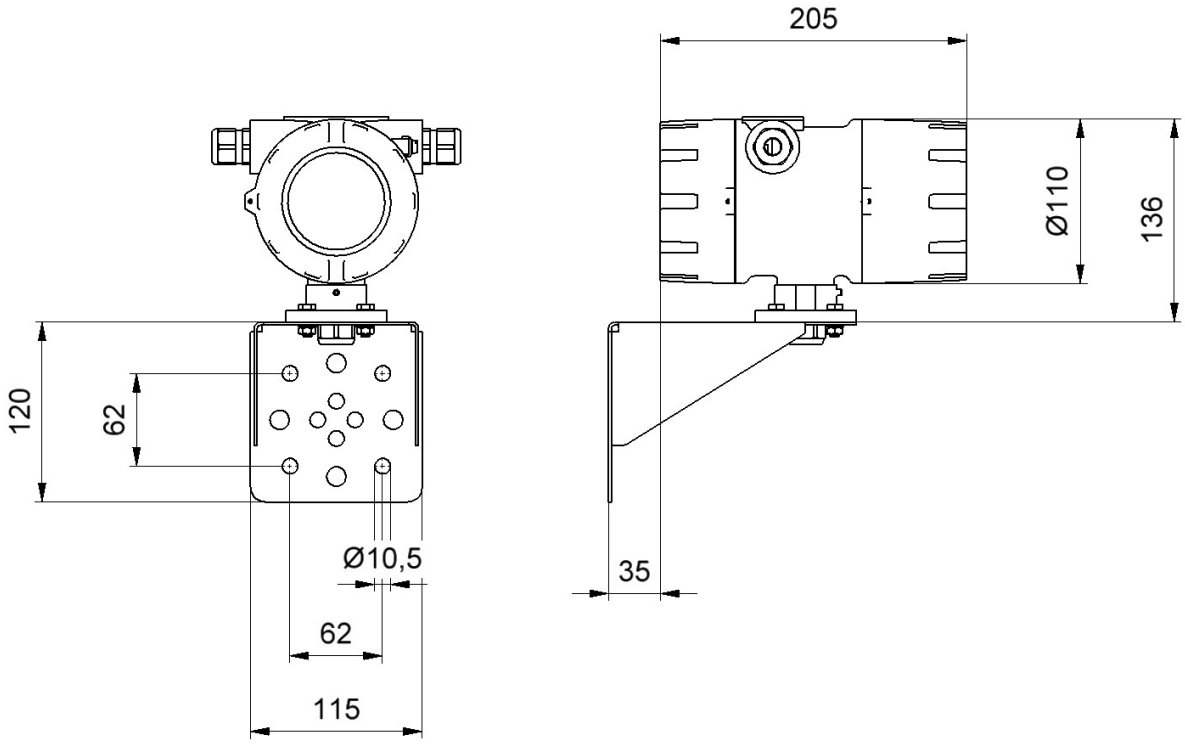
Horizontal pipe mounting – SG4



Vertical pipe mounting – SG4



Separate mounting – SG4



12.2 Weight

Aprox 2.4 kg (5.5 lbs) (separate UMC4 transmitter without mounting system)

12.3 Material

Housing: Aluminium pressure die–casting, max.0.5% Mg; yellow chromating and paint (outside only).

12.4 End connection

Integral mounted on the sensor or remote mount with cable connection.

For further details see Section 4.6 Connection to the transmitter on page 24, Section 12.5.2.1 Wiring diagram for the integral mount configuration of sensor and UMC4 on page 42 and Section 12.5.2.2 Wiring diagram for the remote mount configuration of sensor and UMC4 on page 43.

12.5 Electrical connection

Auxiliary power	90 V - 265 V AC		50/60 Hz
	24 V AC	+ 5 %, − 20 %	50/60 Hz
	19 V to 36 V DC		
Power input	4.5 VA		

Main fuse: 5x20 mm IEC 60127-2,V

Main voltage	r. Current	rated voltage	breaking capacity
90V ... 265V AC	250mA	250V AC	80A / 250V AC
24V AV	250mA	250V AC	80A / 250V AC
19V ... 36V DC	250mA	250V AC	80A / 250V AC

12.5.1 UMC4 connections

Lines

Designation	Terminal designation	Type of protection		Standard
		EEx ia		(Not Ex)

Power supply	L(+), N(-),PE			x

Sensor lines				
SENSOR1 +	1	x		x
SENSOR1 -	2	x		x
SENSOR2 +	3	x		x
SENSOR2 -	4	x		x
TIk-	5	x		x
Temperature sensor -	6	x		x
Temperature sensor +	7	x		x
TIk+	8	x		x
EXCITER1	9	x		x
EXCITER2	10	x		x
Shield	Shield	x		x

- If the sensor and transmitter are separate mounted, the following cable is to be used:
  SLI2Y (SP) CY 5 x 2 x 0.5 mm or
  SLI2Y (ST) C11YÖ 5 x 2 x 0.5 mm or
  SG [5(2 LiY 0.50)St]FStC11Y
  (blue for explosion-proof applications, grey for non-explosion proof applications).

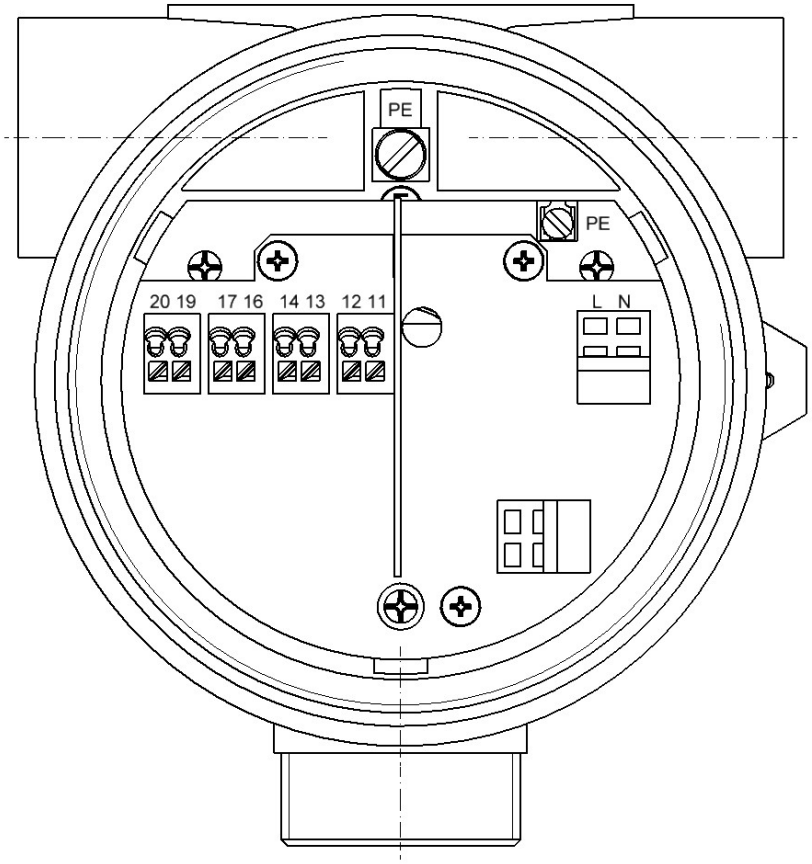
Designation	Terminal designation	Type of protection		Standard
		EEx ia	(Ex d) not Ex	(Not Ex)
Signal outputs				
Current 1, 4 to 20mA with HART®	11 and 12	x		x
	41 and 42		x	
Current 2, 4 to 20mA	13 and 14	x		x
	43 and 44		x	
Binary output 1 (passive pulse)	16 and 17	x		x
	46 and 47		x	
Binary output 2 (status or second passive pulse output)	19 and 20	x		x
	49 and 50		x	
Option Binary output 3 (status output during custody transfer operations)	33 and 34	x		x
	53 and 54		x	

- **Under no circumstances are "Increased safety" signal outputs to be combined with "Intrinsic safety" signal outputs**.

12.5.2 Wiring diagram

12.5.2.1 Wiring diagram for the integral mount configuration of sensor and UMC4

Supply and end connections
of the UMC4 transmitter



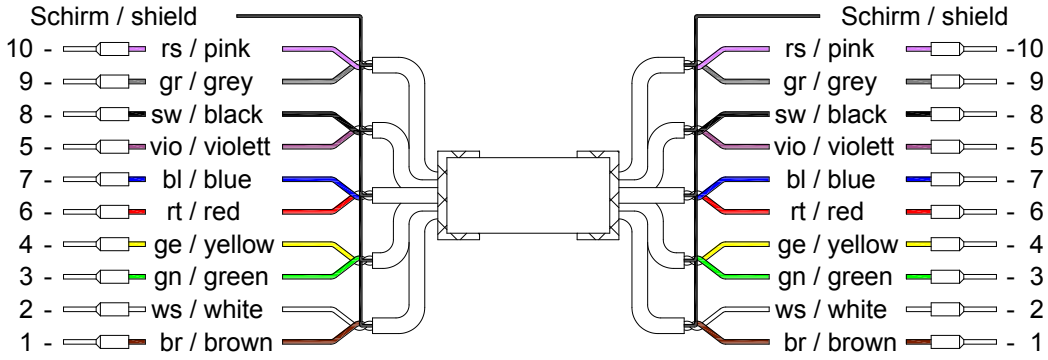
Process outputs wiring								
Standard			(Ex -d) not Ex			Ex ia		
17	+	Binary output 1	47	+	Binary output 1	17	+	Binary output 1
16	-	(pulse/frequency)	46	-	(pulse/frequency)	16	-	(pulse/frequency)
20	+	Binary output 2	50	+	Binary output 2	20	+	Binary output 2
19	-	(status output)	49	-	(pulse/frequency)	19	-	(pulse/frequency)
14	+	Current output 2	44	+	Current output 2	34	+	Binary output 3
13	-	(0/4-20 mA)	43	-	(0/4-20 mA)	33	-	(status output)
12	+	Current output 1	42	+	Current output 1	12	+	Current output 1
11	-	(0/4-20 mA HART®)	41	-	(0/4-20 mA HART®)	11	-	(0/4-20 mA HART®)

12.5.2.2 Wiring diagram for the remote mount configuration of sensor and UMC4

Cable: Non-explosion proof applications SLI2Y(ST)CY 5 x 2 x 0.5 mm² grey (max. 300 m)
Explosion-proof applications SLI2Y(ST)CY 5 x 2 x 0.5 mm² blue (max. 300 m)

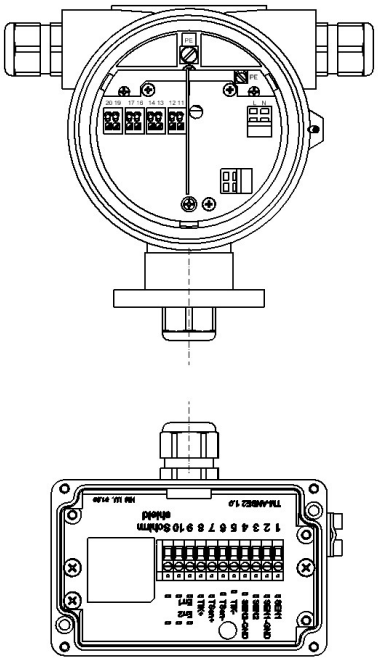
Alternative cables:
SLI2Y (ST) C11YÖ 5 x 2 x 0.5 mm or
SG [5(2 LiY 0.50)St]FStC11Y
(blue for explosion-proof applications, grey for non-explosion proof applications).

The outer shield is connected to the cable glands at both ends,
the inner shields are connected to each other and connected to the “Schirm / shield” terminal.



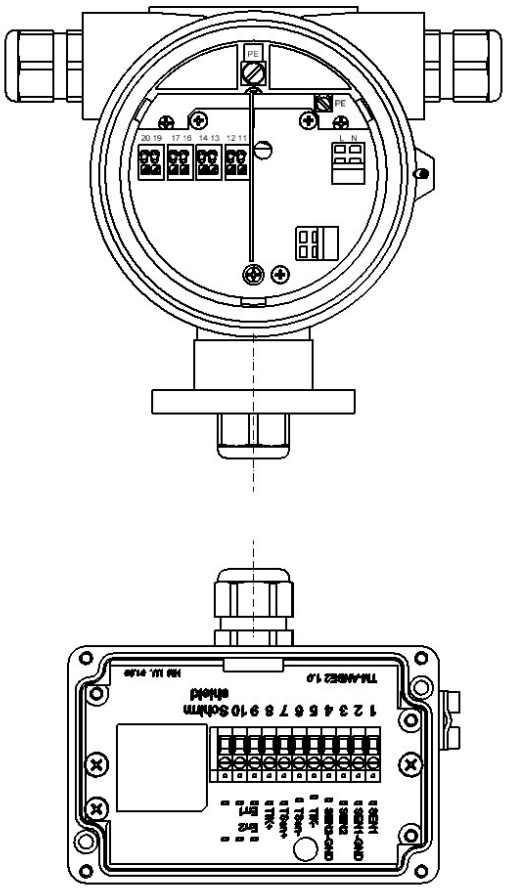
Warning:
The colors of the sensor’s wires are not identically with the colors of the connection cable’s wires between terminal box and transmitter! The colors shown in the drawing above only refers to the numbers of the terminal in the terminal box and transmitter.

TM, TME, TMR, TMU with WAGO terminals
For terminal assignment, see Section 12.5.1 UMC4 connections



Advices to cable glands: See also 11.1 “Installation conditions and cable glands” at page 35.

TM, TME, TMR, TMU with limit circuit and WAGO terminals
For the terminal assignment, see Section 12.5.1 UMC4 connections



Advices to cable glands: See also 11.1 “Installation conditions and cable glands” at page 35.

12.5.3 HART®

A number of options are available for HART® communication. However, for all these options loop resistance must be less than the maximum load specified in Section 9.3 Load (on page 34). The HART® interface is connected via terminal 11 and 12 or 41 and 42 with a minimum load impedance of 250 Ω.

For information regarding operation of the transmitter using the HART® hand-held terminal, see “Operation of the UMC4 transmitter using the HART® hand-held terminal.”

12.5.4 Communication via Siemens PDM®

PDM® is the configuration software of Siemens that is used to operate HART® or Profibus PA compatible devices.
To connect a desktop or laptop computer to the UMC4, a HART® interface is required in addition to communication software such as PDM. The HART® interface, which has two connections, converts the levels of the RS 232 interface or USB interface into an FSK signal (frequency-shift keying). These connections consist of 9-pin sockets at the interface for the RS 232 connection, as well as a two-core cable with two mini terminals for current loop 1 in the transmitter.

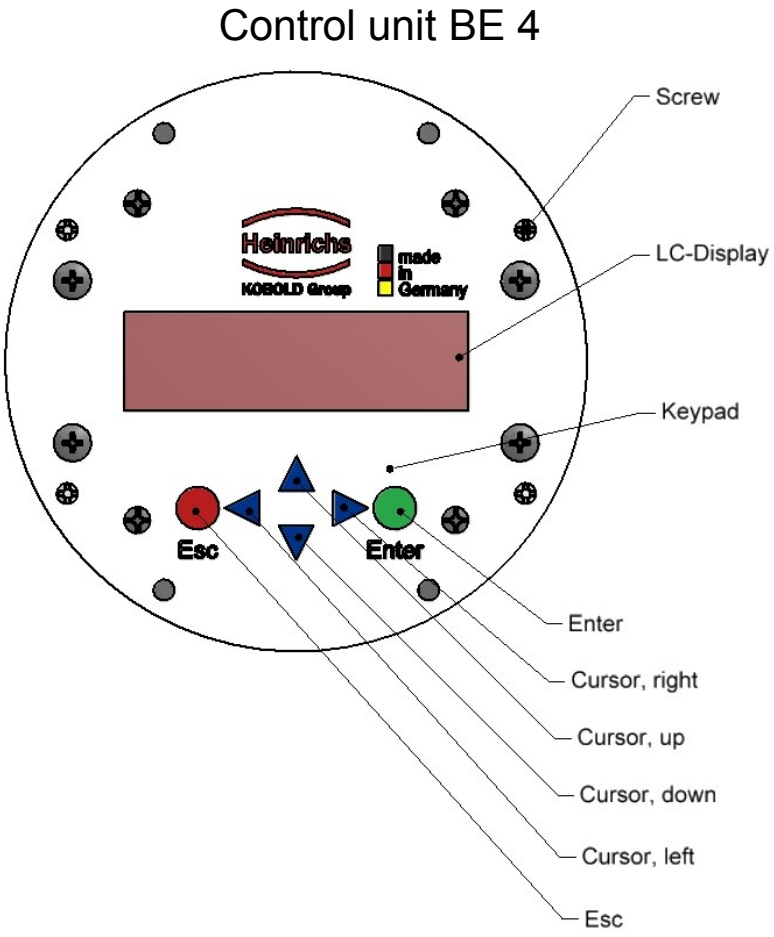
The interface can be also installed in a separate control cabinet.

13. Control unit BE4

13.1 Introduction

The UMC4 transmitter can be operated using control unit BE4, a desktop or laptop computer in conjunction with PDM® software, or via HART® Communicator.

In the following, transmitter operation and parameterization are described using control unit BE4 integrated into the electronic compartment. To use the control unit the cover window glass must be removed. **In Ex hazardous area, all relevant safety regulations have to be observed before opening the window glass.**



13.2 Display

Control unit BE4 in the UMC4 has an integrated alphanumeric display with two 16-character lines (format 15 x 52 mm). It has a backlight for the improvement in the readability of the display also at a low ambient brightness. Measurement data and settings can be read directly from this display.

The LCD display is designed be operated at temperatures ranging from − 20 °C to + 60 °C (-4° F to 140 °F) without incurring any damage. However, at freezing or near-freezing temperatures, the display becomes slow and readability of the measured values is reduced. At temperatures below − 10 C° (14 °F), only static values (parameter settings) can be displayed. At temperatures exceeding 60 C° (140 °F), contrast decreases substantially on the LCD and the liquid crystals can dry out.

13.3 Operating modes

The UMC4 can be operated in the following modes:

1. Display mode: In display mode, measured values can be displayed in various combinations and UMC4 settings can also be displayed. Parameter settings cannot be changed in this mode. Display mode is the standard (default) operating mode when the device is switched on.

2. Programming mode: In programming mode, UMC4 parameters can be redefined. After entering the correct password, changes that are permissible for the customer (customer password) or all functions (service password for technicians) can be realized.

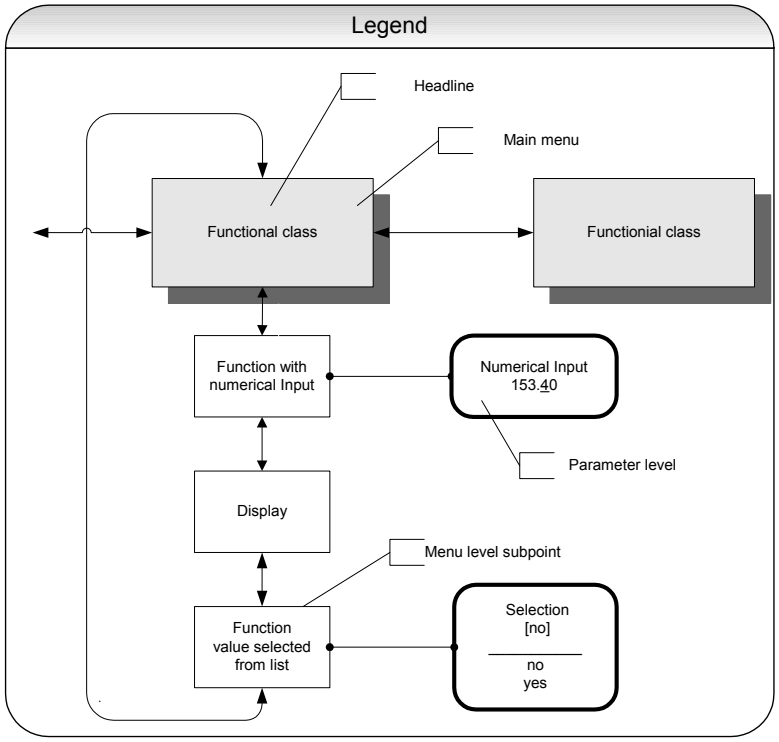
13.4 Operation

13.4.1 Operator interface

Functional classes are displayed as headings beneath which displays and parameters are shown in logical groups.

Beneath this is the **menu level**, which lists all measured value displays or the headings for their underlying parameters (**parameter level**).

All functional classes are interlinked horizontally, while all subpoints that are assigned to a functional class are displayed beneath the relevant class.



13.4.2 The keys and their functions

There are six keys to change the settings.

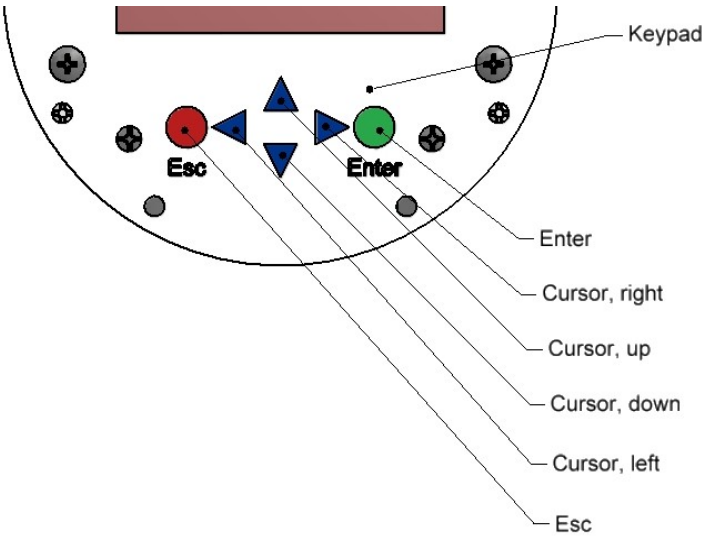
Important note
Do not press these keys with sharp or sharp-edged objects such as pencils or screwdrivers.

Cursor keys: Using the cursor keys, the operator can change numerical values, give YES/NO answers and select parameters. Each key is assigned a symbol in the following table:

Descriptor	Symbol
Cursor key, arrow to the right	▶
Cursor key, arrow to the left	◀
Cursor key, arrow to the top	▲
Cursor key, arrow to the bottom	▼

Esc key: **The "Esc" key allows you to cancel the current action.** Pressing Esc moves you to the next higher level where the operator can repeat the action. Pressing Esc twice moves you directly to the MEASURED VALUES functional class.

ENTER key: Pressing ↵ (ENTER key) moves you from the menu level to the parameter level. **You confirm all entries with the ↵ key.**



13.4.3 Functional classes, functions and parameters

Functional classes are written in all upper case letters (headings). The functions beneath each functional class are written in upper and lower case.

The various functional classes and functions are describes in Section 14 “UMC4 transmitter functions” starting on page 50.

The lower line contains the following elements:

- Informational texts
- YES/NO answers
- Alternative values
- Numerical values (with dimensions, if applicable)
- Error messages

If the user attempts to modify values for any of these parameters without entering the required password, the message “Access denied” will be displayed (see also 13.3 Operating modes on page 46 and 13.4.3.3 Pas on page 49).

13.4.3.1 Selection window/make a selection

In the selection window, the first line of the LCD always contains the heading, while the second line displays the current setting. This setting is shown in square brackets if the system is in Programming mode.

Function name
[Selection]

In Programming mode (see 13.3 Operating modes on page 46), i.e. after a password has been entered (see 13.4.3.3 Passwords on page 49), the operator can navigate to the desired setting by using the ▲ key or the ▼ key and the operator can then confirm your selection by pressing ↵ (ENTER key). To retain the current setting, press Esc.

13.4.3.2 Input window/modify a value

In the input window, the first line of the LCD always shows the heading, while the second line shows the current setting.

Example:

Function name
-4,567 Unit

These modifications can only be made in Programming mode (refer to 13.3 Operating modes on page 46), which means that a correct password (see 13.4.3.3 Passwords on page 49) must be entered. To move the cursor from one decimal place to the next, use the ◀ or ▶ keys. To increase the value of the decimal place just under the cursor by “1,” use the ▲ key, and use ▼ key to lower the number by 1. To change the minus and plus sign, place the cursor in front of the first digit. To confirm and apply the change, press ↵ . To retain the current value, press Esc.

13.4.3.3 Passwords

Programming mode is password protected. The customer password allows all changes to be made that are permissible for customers. This password can be changed when the device is first put into operation. Such changes should be kept in a safe place.

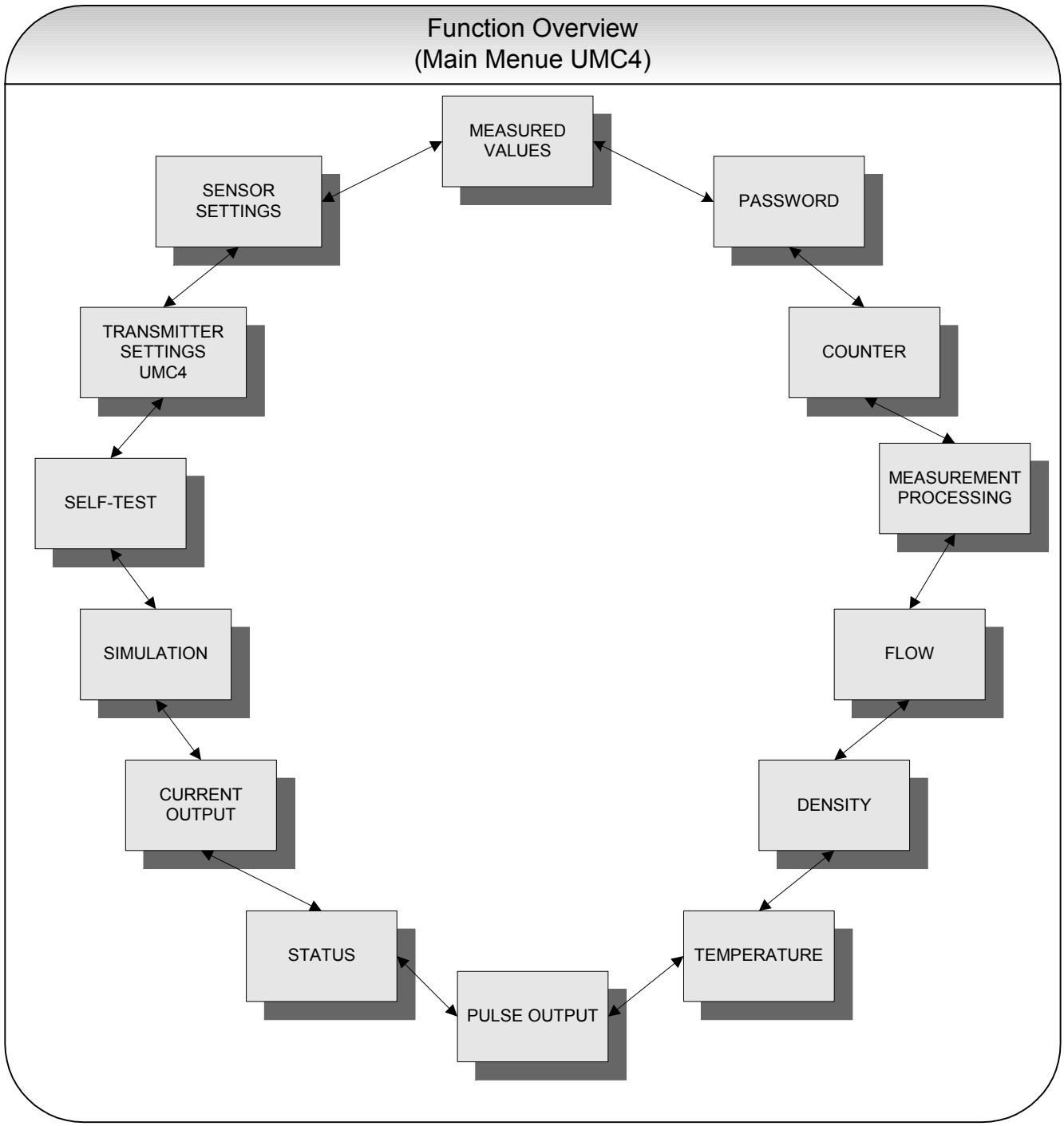
The UMC4 customer password in the device when delivered is **0002**.

The service password allows for modification of all UMC4 functions. This password is not given to customers.

For further information on customer passwords, see Section 14.2 PASSWORD functional class on page 56.

14. UMC4 transmitter functions

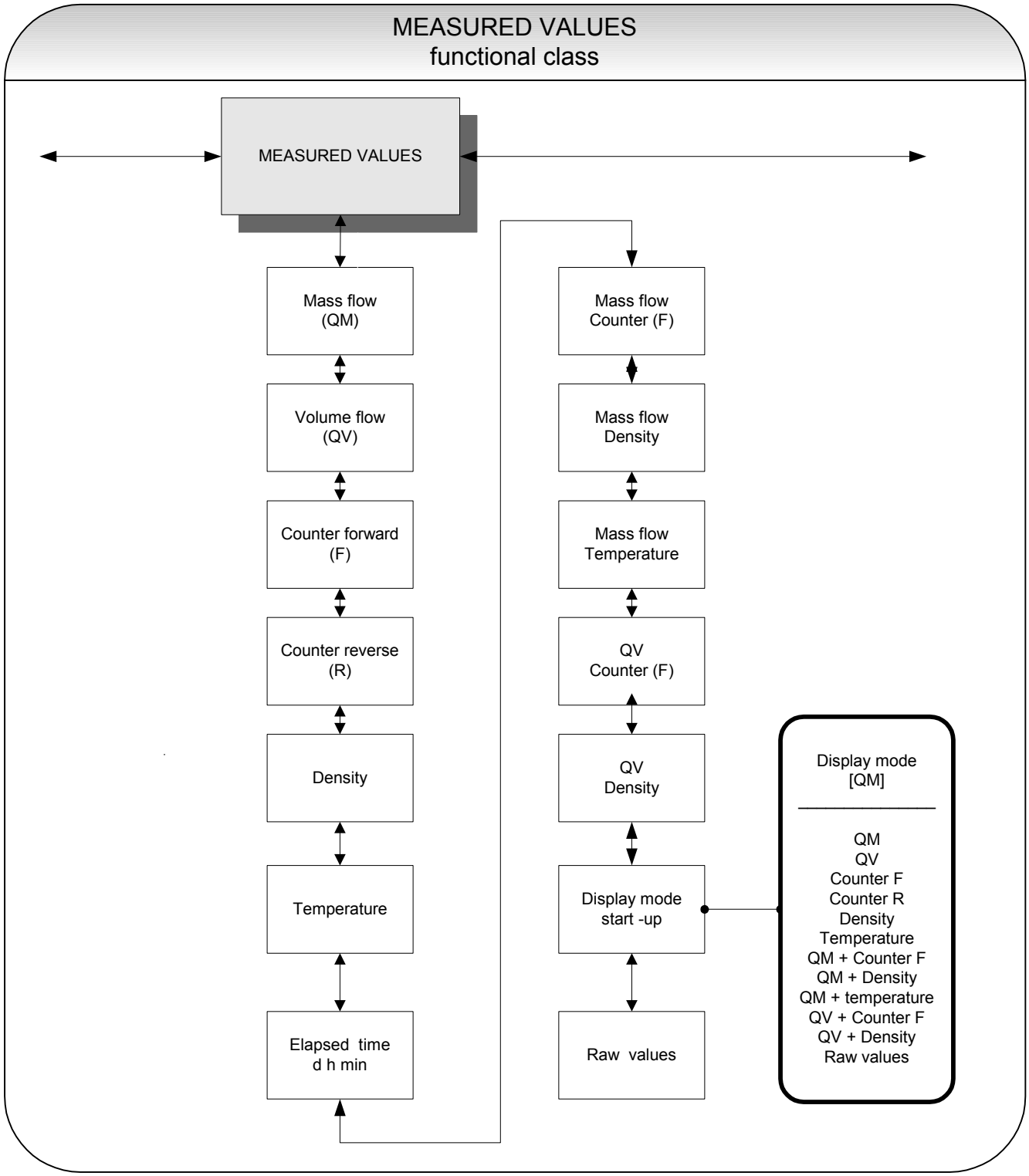
The software functions of the UMC4 transmitter are divided into functional classes, are arrayed in a circle and can be navigated by using the ◂ or ▸ cursor keys. To go back to your starting point (the MEASURED VALUES functional class) press Esc.



In the following, all software functions that can be accessed using the customer password are described. Functions that are only accessible to the vendor (service functions) are not described in the present document.

14.1 MEASURED VALUES functional class

The MEASURED VALUES functional class contains all functions for displaying the measured values.



14.1.1 Mass flow

After selecting the Mass flow function, the following will be displayed:

Mass flow
XXX.X kg/h

The LCD shows the current mass flow. The operator can define the display unit in the FLOW functional class using the *Mass flow QM unit* function.

14.1.2 Volume flow

After selecting the *Volume flow* function, the following will be displayed:

Volume flow
XXX.X m³/h

Volume flow can only be displayed if density measurement has been calibrated and activated. Otherwise, an error message is displayed. The operator can define the display unit in the FLOW functional class using the *Volume flow QV unit* function.

14.1.3 Counter forward

After selecting the *Counter forward* function, the current reading of the forward flow counter will be displayed.

Counter forward
XXXXXXXX.XX kg

The operator can define the display unit in the COUNTERS functional class using the *Unit of counters* function.

14.1.4 Counter reverse

After selecting the *Counter reverse* function, the current reading of the reverse flow counter will be displayed.

Counter reverse
XXXXXXXX.XX kg

The operator can define the display unit in the COUNTERS functional class using the *Unit of counters* function.

14.1.5 Density

Depending on the settings in the DENSITY functional class, the process or reference density will be displayed. Density can only be displayed if the sensor is suitable for density measurement and has been calibrated accordingly.

Density
XXX.X g/l

The operator can define the display unit in the DENSITY functional class using the *Density unit* function.

14.1.6 Temperature

After selecting the *Temperature* function, the following will be displayed:

Temperature
XXX,XX °C

The LCD shows the current temperature of the measured fluid in degrees Celsius, Fahrenheit or Kelvin.

14.1.7 Elapsed time

The LCD shows the operating time that has elapsed in d(ays), h(ours) and min(utes) since the system was initialized and commissioned by the vendor:

Elapsed time
256 d 18 h 06 min

14.1.8 Mass flow + Counter forward

After selecting the *Mass flow + Counter forward* function, the current mass flow will be displayed in the first line of the LCD:

XXX.X kg/h
XXXXXXXX.XX kg

The second line shows the value of the counter forward. The operator can define the display unit in the FLOW functional class using the *Mass flow QM unit* function and the counter unit using the *Unit of counters* function in the COUNTERS functional class.

14.1.9 Mass flow + Density

After selecting the *Mass flow* + *Density* function, the following will be displayed:

XXX.X kg/h
XXX.X g/cm³

The first line of the LCD shows the current mass flow and the second the density of the measured fluid. You define the display unit in the FLOW functional class using the *Mass flow QM unit* function and the density unit using the *Density unit* function in the DENSITY functional class.

14.1.10 Mass flow + Temperature

After selecting the *Mass flow* + *Temperature* function, the following will be displayed:

XXX.X kg/h
XXX °C

The first line of the LCD shows the current mass flow and the second line the temperature of the measured fluid. You define the display unit in the FLOW functional class using the *Mass flow QM unit* function.

14.1.11 Volume flow + Counter forward

After selecting the *Volume flow* + *Counter forward* function, the current mass flow will be displayed in the first line of the LCD:

XXX.X m³/h
XXXXXXXX.XX m³

The second line shows the value of the counter forward. The operator can define the display unit in the FLOW functional class using the *Volume flow QV unit* function and the counter unit using the *Unit of counters* function in the COUNTERS functional class.

14.1.12 Volume flow + Density

After selecting the *Volume flow* + *Density* function, the following will be displayed:

XXX.X m³/h
XXX.X g/cm³

The first line of the LCD shows the current volume flow and the second line the density of the measured fluid. The operator can define the display unit in the FLOW functional class using the *Volume flow QM unit* function and the unit for density measurement in the DENSITY functional class using the *Density unit* function.

14.1.13 Display mode during startup

By choosing the *Display mode during startup* function the operator can define the default display. After the operator switched the device on and did not touch any keys for a longer period of time, the defined default display will be shown:

Display mode
[QM]

According to the description in Section 13.4.3.1 Selection window/make a selection, one of the following default displays can be selected.

- QM (Mass flow)
- QV (Volume flow)
- Counter f(orward)
- Counter r(everse)
- Density
- Temperature
- QM + Counter f
- QM + Density
- QM + Temperature
- QV + Counter f
- QV + Density
- and Raw values

14.1.14 Raw values

The “Raw values display” supports fault diagnosis and trouble shooting. Please inform our service department about the clear text error messages and the contents of this “Raw values display.”

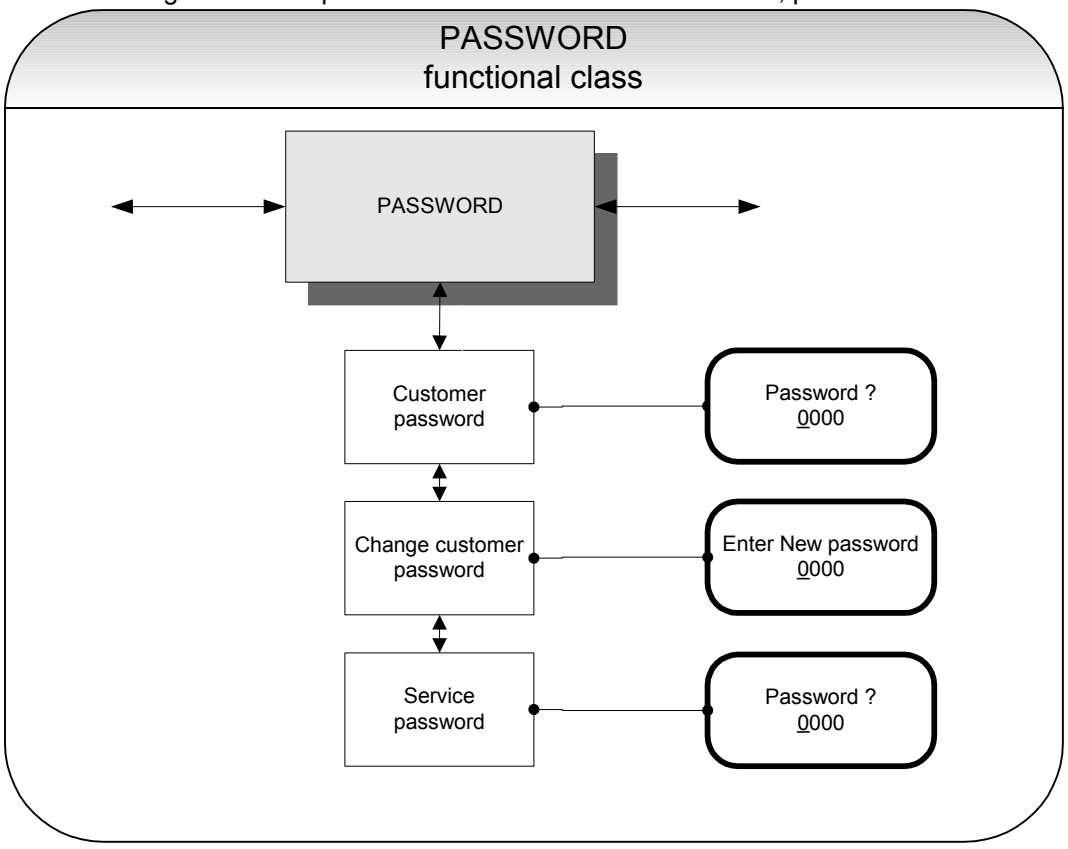
xxx.xxx	ttt.tttt
fff.ffff	eee.aaa

The displayed values have the following meaning:

xxx.xxx: Measure for the phase displacement between the sensor signals.
ttt.ttt: Indicates the measured sensor temperature.
fff.ffff: Indicates the current oscillation frequency of the system.
eee.aaa: Indicates the value of the excitation current (eee) and the sensor voltage (aaa).

14.2 PASSWORD functional class

The PASSWORD functional class is comprised of the functions for entering and changing the customer password and entering the service password. To cancel the current action, press Esc.



14.2.1 Customer password

After selecting the *Customer password* function and pressing ↵, the following will be displayed:

Password?
0000

According to the description in Section 13.4.3.2 Input window/modify a value, the password can be changed.

If the entered password is correct, the following message will be displayed:

Password
valid

If the entered password is not correct, the following message will be displayed:

Password
invalid

The customer password in the device when delivered is **0002.**

A valid customer password allows all software parameter changes to be made that are permissible for customers. After the operator switched the device off or did not touch any keys for about 15 minutes, the authorization to change settings related to password entry will automatically be canceled. If the operator does not enter a valid password, all settings can be displayed but not changed. Parameter changes via HART or Profibus PA may be carried out any time without entering password.

14.2.2 Change customer password

After entering a valid customer password, you may change the existing password and enter a new one. After selecting the *Change customer password* function and pressing ↵, the following will be displayed.

Enter New password
0000

According to the description in Section 13.4.3.2 Input window/modify a value the current value can be changed.


Press ↵ to confirm and save the new password. Make sure that you entered the desired password. **A copy of the password should be kept in a safe place.** Reactivation of a transmitter at the vendor's site due to a lost password is not part of our warranty.

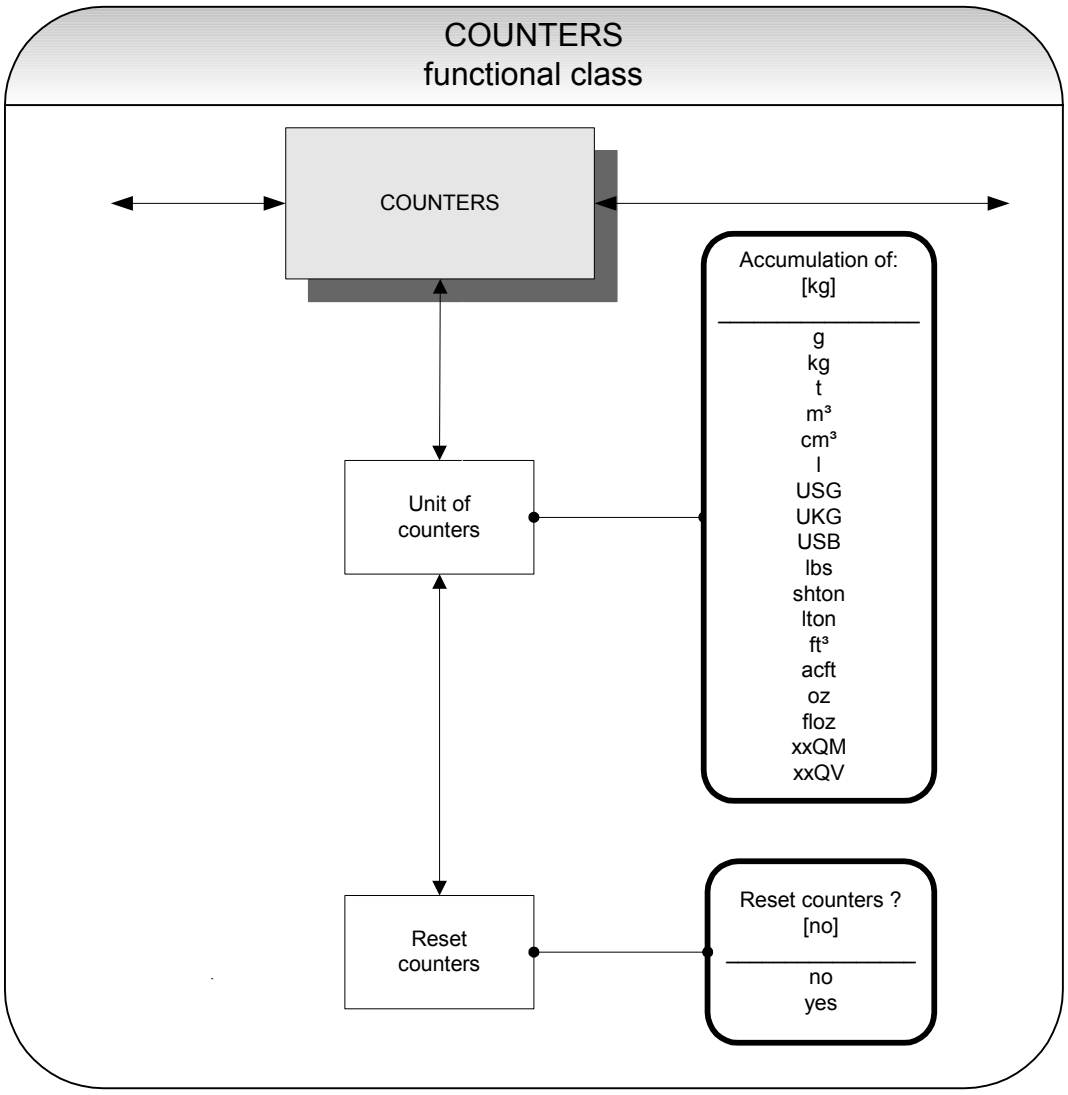
14.2.3 Service password

You do not need the service password for setting the functions necessary for operation.

The service password is reserved for service technicians and not provided to customers. Correct settings are essential for proper operation of the device (e.g. parameterization and calibration values).

14.3 COUNTER functional class

The COUNTERS functional class is comprised of the following functions:



To change the current settings, enter the customer password. Otherwise, the settings can only be displayed but not changed. To cancel the current action, press Esc.

14.3.1 Unit of counters

After choosing the *Unit of counters* function and pressing ↵, the current forward and reverse counter unit will be displayed:

Accumulation of:
[kg]

According to the description in Section 13.4.3.1 Selection window/make a selection, one of the following units can be selected.

- Mass units: g, kg and t as well as lbs, shton, lton and oz or
- Volume units: m³, cm³ and l as well as USG, UKG, USB, ft³, acf and floz
- Programable mass unit: xxQM,
- Programmable volume unit: xxQV.

When the unit is changed, the counters will be reset to 0.00 automatically.
The volume unit only makes sense if the sensor has been calibrated for density measurement. Press ↵ to confirm and save the selection. Forward and reverse counters will now show the selected unit.

The valency of the programable units are defined by the settings of the flow units described in sections 14.5.2 “Factor mass flow QM programmable unit” on page 64 and 14.5.8 “Factor volume flow QV programmable unit” on page 67.

To reset the totalizing counters, you definitely need to toggle to [yes]. Forward and reverse counters will be reset at the same time (0.00).

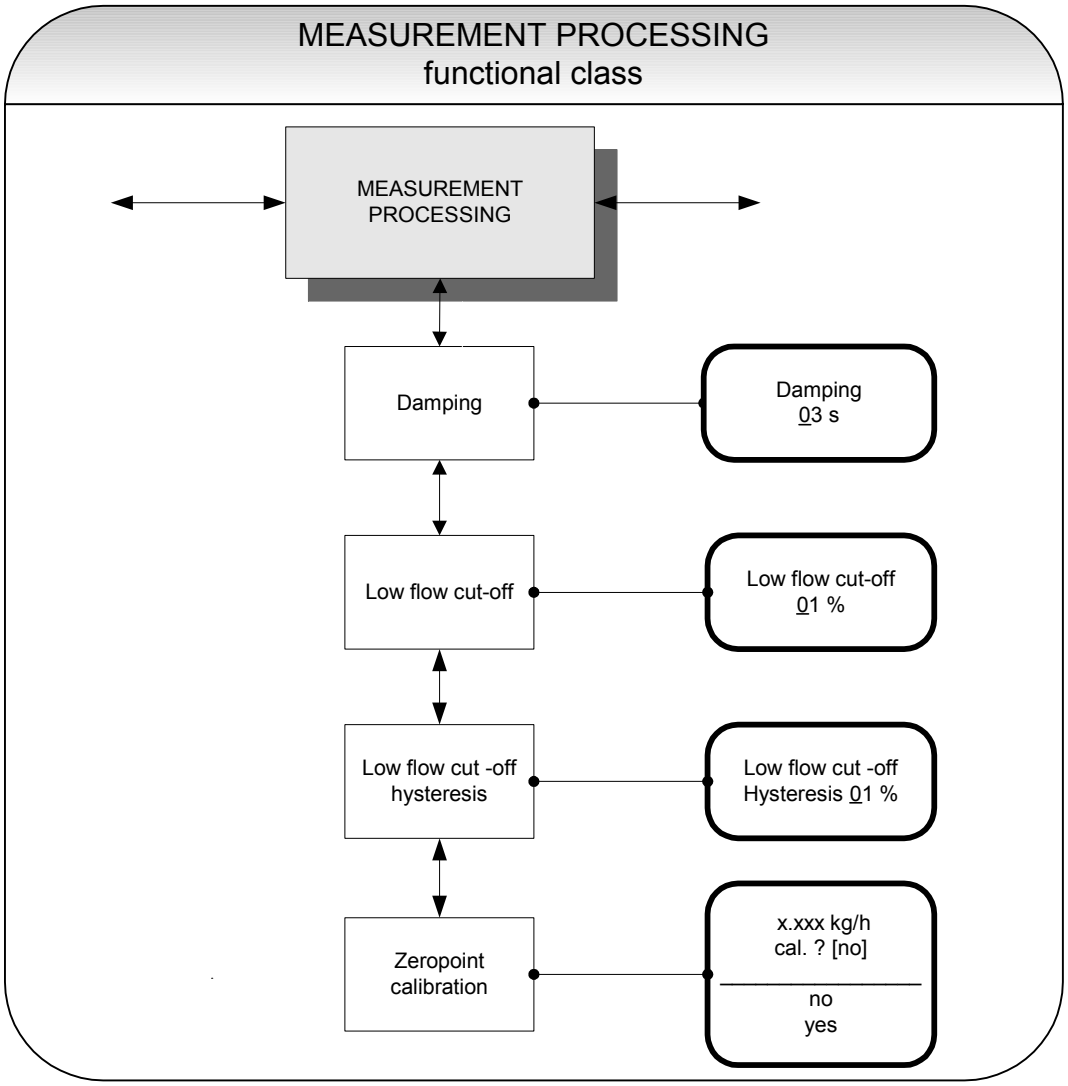
Reset counters
[no]

According to the description in section 13.4.3.1 Selection window/make a selection, one of the indicated units can be selected. By pressing Esc or toggling to [no] the operator can cancel the current action without changing the counter readings.

14.4 MEASUREMENT PROCESSING functional class

The MEASUREMENT PROCESSING functional class is comprised of all functions that affect the processing of the measured values.

To change the current settings, enter the customer password. Otherwise, the settings can only be displayed but not changed. To cancel the current action, press Esc.



14.4.1 Damping

The damping value is intended to dampen abrupt flow rate changes or disturbances. It affects the measured value display and the current and pulse outputs. It can be set in intervals of 1 second from 1 to 60 seconds. After choosing the *Damping value* function and pressing ↵, the following selection field will be displayed:

Damping
03 s

The current damping value will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed. After setting the new damping value, press ↵ to confirm your entry.

14.4.2 Low flow cut-off

The value for low flow cut-off (low flow volume) is a limiting value stated as a percentage that relates to the upper-range value of the flow rate. If the volume drops below this value (e.g. leakage), the displayed value and the current outputs will be set to "ZERO." The value for low flow cut-off can be set from 0 to 20 % in 1-percent increments. After choosing the *Low flow cut-off* function and pressing ↵, the following selection field will be displayed:

Low flow cut-off
00 %

The low flow volume will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed. After setting the new low flow volume, you confirm your entry with ↵.

For devices used in custody transfer operations, you need to deactivate the low flow cut-off function, i.e. to set this value to 0 %.

14.4.3 Low flow cut-off hysteresis

The hysteresis of the low flow volume is the flow rate expressed as a percentage of the upper range value by which the volume must fall below or surpass the set low flow volume in order to activate or deactivate the function. The hysteresis of the low flow volume can be set in 1-percent increments from 0 to 10 %. After selecting the *Low flow cut-off hysteresis* function and pressing ↵, the following selection field will be displayed:

Low flow cut-off
Hysteresis 00 %

The current hysteresis will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed. After setting the new hysteresis value, you confirm your entry with ↵.

14.4.4 Zero point calibration

Using the *Zero point calibration* function the operator can recalibrate the zero point of your meter in the measuring system. Zero point calibration is to be realized after any installation procedure or after any type of work has been performed on in the pipes near the sensor.

	**CAUTION:** This function may only be carried out if it is certain that the fluid in the sensor is not flowing. Otherwise, the flow rates measured subsequently will be incorrect. The sensor may be completely empty or filled with fluid. A partially filled sensor or air bubbles will lead to an incorrect zero point calibration.

 Calibrating a sensor filled with a fluid is better than calibrating an empty one.

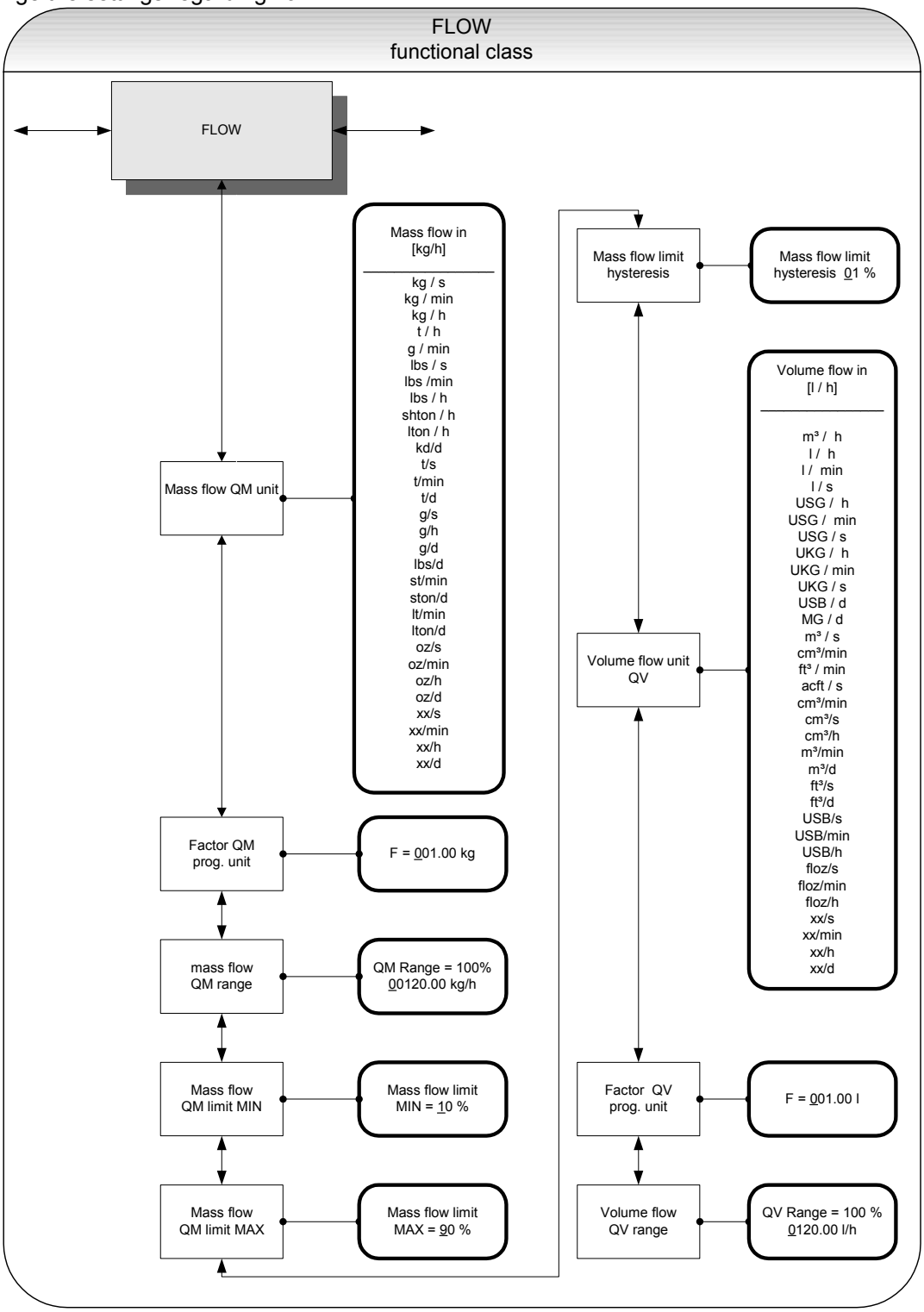
After choosing the *Zero point calibration* function and pressing ↵, the current remaining flow will be displayed:

QM = 0,00 kg/h
cal. ? [no]

According to the description in Section13.4.3.1 Selection window/make a selection, the operator can toggle between [yes] and [no]. After setting the new value, press ↵ to confirm your entry. Enter [yes] to have the zero point recalibrated.

14.5 FLOW functional class

The FLOW functional class is comprised of functions that affect lower- and upper-range values and the processing of the measured flow rates. In Programming mode (see 13.3 Operating modes), i.e. after a password has been entered (see 13.4.3.3 Passwords, 14.2 PASSWORD functional class), the operator can change the settings regarding flow.



To change the current settings, enter the customer password. Otherwise, the settings can only be displayed but not changed. To cancel the current action, press Esc.

14.5.1 Mass flow QM unit

Using this function, the operator can define the physical unit for all display functions, limit values and the upper-range value of mass flow. After choosing the *Mass flow QM unit* function and pressing ↵, the following selection field will be displayed:

Mass flow QM unit
[kg/h]

According to the description in Section 13.4.3.1 Selection window/make a selection, one of the following units can be selected:

- kg/s, kg/min, kg/h, kg/d,
- t/s, t/min, t/h,t/d,
- g/s, g/min, g/h, g/d,
- lbs/s, lbs/min, lbs/h,lbs/d,
- shton/min, shton/h, shton/d,
- lton/h, lton/min, lton/d,
- oz(s, oz/min, oz/h, oz/d,
- xx/s, xx/min, xx/h, xx/d (programmable mass flow unit)

Press ↵ to confirm and save the selection.

A conversion factor can be entered as a substitute for a not available mass flow unit as described in the after-following chapter 14.5.2 “Factor mass flow QM programmable unit” on page 64. In this case the unity xx is selected into combination with the desired time unit.

14.5.2 Factor mass flow QM programmable unit

To display another mass flow unity than one of the predefined standard units a factor can be entered for the conversion of the reading.

F = 001.0 kg

The factor always refers to the unity of kg.

According to the description in section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.3 Mass flow QM range

This function allows the operator to set the upper-range value for mass flow. The upper-range value takes on the unit defined using the *Mass flow unit* function. The upper-range value will scale the current and frequency outputs assigned to mass flow. After choosing the *Mass flow QM range* function and pressing ↵, the following selection field will be displayed:

QM range=100%
XXXXX.XX kg/h

The current upper-range value for mass flow will be displayed. According to the description in section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.4 Mass flow QM limit MIN

The MIN limiting value for mass flow can be evaluated via the status output. You enter the value as a percentage of the set upper-range value. If the mass flow is lower than that limit value, the status output will be set in case the corresponding assignment has been made. If the alarm function has also been activated for the assigned current output, the applied current will change to < 3.2 mA or > 20.5 mA / 22 mA. After choosing the *Mass flow QM limit MIN* function and pressing ↵, the following selection field will be displayed:

Mass flow limit
MIN = 10 %

The current MIN upper-range value for mass flow will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.5 Mass flow QM limit MAX

The MAX limiting value for mass flow can be evaluated via the status output. You enter the value as a percentage of the set upper-range value. If the mass flow surpasses this limit value, the status output will be set in case the corresponding assignment has been made. If the alarm function has also been activated for the assigned current output, the applied current will change to < 3.2 mA or > 20.5 mA / 22 mA. After choosing the *Mass flow QM limit MAX* function and pressing ↵, the following selection field will be displayed:

Mass flow limit
MAX = 90 %

The current MAX upper-range value for mass flow will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.6 Mass flow QM limit hysteresis

The hysteresis of the QM limiting values is the flow rate in percent based on the upper-range value and indicates the value which must fall below or surpass the set limiting values in order to activate or deactivate the function. The hysteresis of the QM limiting values can be set in 1-percent increments from 0 to 10 %. After choosing the *Mass flow QM limit hysteresis* function and pressing ↵, the following selection field will be displayed:

Mass flow limit
Hysteresis 00 %

The current hysteresis value will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.7 Volume flow QV unit

This function allows the operator to define the physical unit for all display functions and the upper-range value for volume flow. After choosing the “Volume flow QV unit” function and pressing ↵, the following selection field will be displayed:

Volume flow QV unit
in [m³/h]

According to the description in Section 13.4.3.1 Selection window/make a selection, one of the following units can be selected:

- m³/d, m³/h, m³/min, m³/s, cm³/h, cm³/min,cm³/s
- l/h, l/min, l/s,
- USG/h, USG/min, USG/s,
- UKG/h, UKG/min, UKG/s
- USB/d, USB/h, USB,min, USB/s,
- MG/d
- ft³/d, ft³/min, ft³/s
- acft/s
- floz/h, floz/min, floz/s
- xx/h, xx/min, xx/h.

Press ↵ to confirm and save the selection.

A conversion factor can be entered as a substitute for a not available mass flow unit as described in the after-following chapter 14.5.8 “Factor volume flow QV programmable unit” on page 67. In this case the unity xx is selected into combination with the desired time unit.

14.5.8 Factor volume flow QV programmable unit

To display another volume flow unity than one of the predefined standard units a factor can be entered for the conversion of the reading.

F = 001.0 l

The factor always refers to the unity of l.

According to the description in section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.5.9 Volume flow QV range

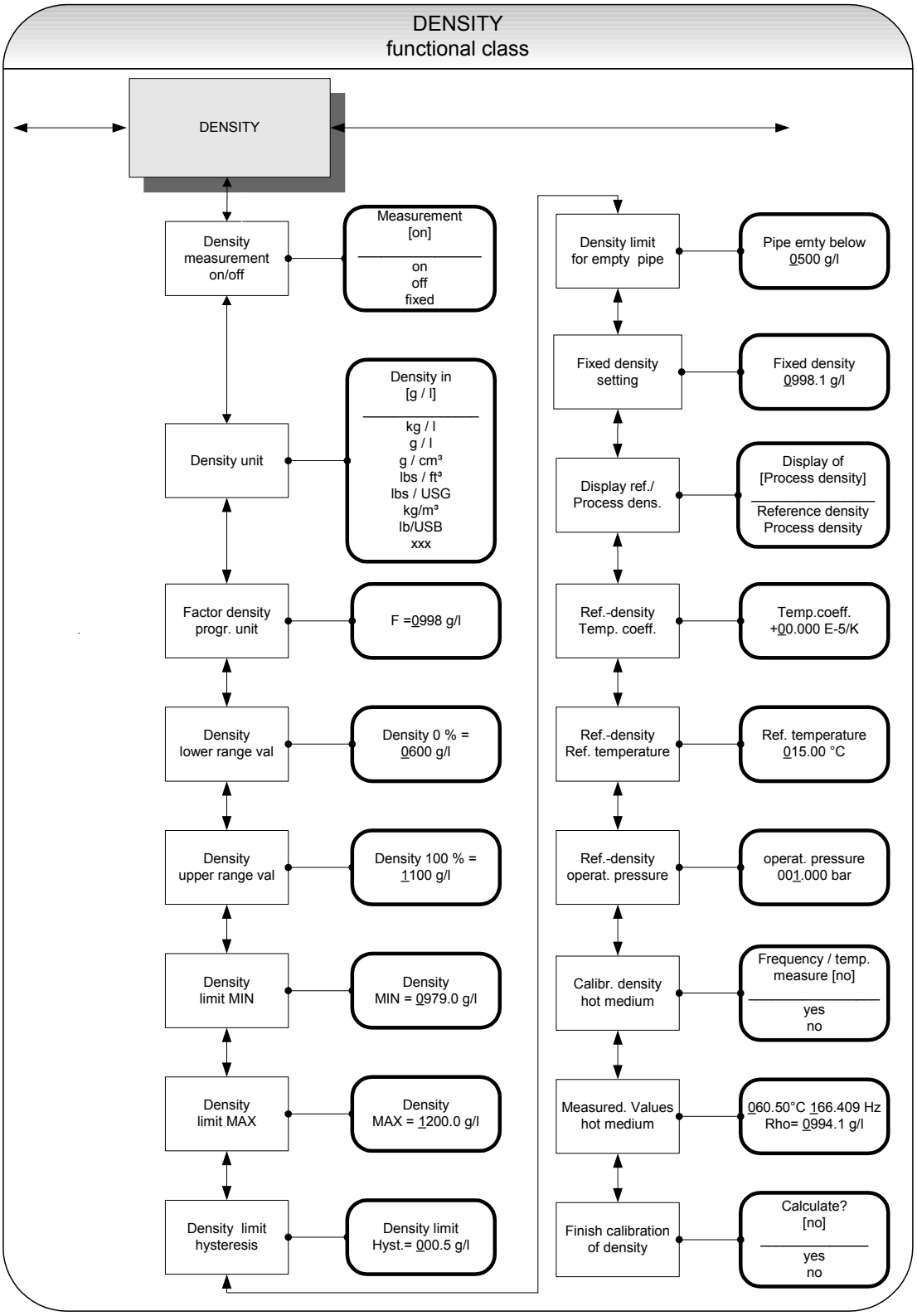
This function allows the operator to set the upper-range value for volume flow. The upper-range value takes on the unit defined using the *Volume flow QV unit* function. After choosing the *Volume flow QV range* function and pressing ↵, the following selection field will be displayed:

QV range=100 % XXXXX.XX m³/h

The current upper-range value for volume flow will be displayed. According to the description in Section 13.4.3.2 Input window/modify a value, the current value can be changed. Output and display of the measured value will only be realized for mass flowmeters for which a density calibration has been carried out.

14.6 DENSITY functional class

The functional class DENSITY is comprised of the functions that affect the lower- and the upper-range value and the processing of the measured density values. The additional service functions regarding density calibration will not be described in these instructions.



14.6.1 Density measurement on/off

This function allows the operator to activate density measurement. After selecting the *Density measurement on/off* function, press ↵ to display the following selection field:

Measurement
[on]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- on density measurement is switched on
- off density measurement is switched off
- fixed density measurement is switched off; a fixed replacement value will be displayed and used for volume flow measurement
-

To confirm and apply the selection, press ↵. If density measurement was switched on and the message “Density not calibrated” is displayed, no density calibration was carried out by the vendor.


Density measurement can only be activated if density calibration has been carried out properly. Density calibration is realized at the factory using the service password.


If no density calibration has been carried out, the density and volume flow values will be set to “0.0” in the MEASURED VALUES functional class and the message “Density unknown” will be displayed.

14.6.2 Density unit

This function allows the operator to define the physical unit for all display functions and the density lower- and upper-range value. After selecting the *Density unit* function, press ↵ to display the following selection field:

Density unit
[g/l]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following units:

- g/l, kg/m³
- kg/l
- g/cm³
- lbs/ft³
- lbs/USG, lbs/USB
- xxx

Press ↵ to confirm and apply the selection.

A conversion factor can be entered as a substitute for a not available density as described in the after-following section 14.6.3 “Factor programmable density unit” on page 70.

14.6.3 Factor programmable density unit

To display another density unity than one of the predefined standard units a factor can be entered for the conversion of the reading.

F = 0998.0 g/l

The factor always refers to the unity of g/l.

According to the description in section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.6.4 Density lower-range value

This function allows the operator to define the lower-range value for density measurement in the selected unit. If density is equal or below this value, the assigned current output will be set to its initial value of 0/4 mA.

After selecting the *Density lower-range value* function, press ↵ to display the following selection field:

Density 0 % =
XXXXX g/l

The current lower-range value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the lower-range value for density measurement.

14.6.5 Density upper-range value

This function allows the operator to define the upper-range value for density measurement in the selected unit. For this density, the assigned current output will be set 20 mA. The applied current of the current output assigned to the density value is linearly interpolated based on the ratio between the measured value and the difference between lower- and upper-range value.

After selecting the *Density upper-range value* function, press ↵ to display the following selection field:

Density 100 % =
XXXXX g/l

The current upper-range value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the upper-range value for density measurement.

14.6.6 Density limit MIN

The MIN limiting value for density can be evaluated via the status output and thus triggers an external alarm. This value is entered as an absolute value in the unit defined using the *Density unit* function.

After selecting the *Density limit MIN* function, press ↵ to display the following selection field:

Density limit
MIN = 0000.0 g/l

The current MIN limiting value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change MIN limiting value for density measurement.

14.6.7 Density limit MAX

The MAX limiting value for density can be evaluated via the status output. This value is entered as an absolute value in the unit defined using the *Density unit* function.

After selecting the *Density limit MAX* function, press ↵ to display the following selection field:

Density limit
MAX = 0000.0 g/l

The current MAX limiting value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change MAX limiting value for density measurement.

14.6.8 Density limit hysteresis

The hysteresis of the density limiting values indicates the absolute density value in the unit defined using *Density unit* function. The measured density must fall below or surpass the set limiting values by the set hysteresis value in order to activate or deactivate the function.

After selecting the *Density limit hysteresis* function, press ↵ to display the following selection field:

Density limit
Hysteresis 000.0 g/l

The current value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change hysteresis value for density measurement.

14.6.9 Density limit for empty pipe

If the measured density or the fixed value falls below this limiting value, the message “Empty pipe” will be displayed, and an alarm will be triggered.

Press ↵ to display the following selection field:

Pipe empty below
0500.0 g/l

The current limiting value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change value for density measurement.

14.6.10 Fixed density

If the operator selected the *fixed* option described in Section 14.6.1 Density measurement on/off (on page 69), density measurement will be switched off. The replacement value defined in the following selection field will be displayed.

Press ↵ to display the following selection field:

Fixed density
0998.1 g/l

The current fixed density will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change this value. The density unit can be defined for all settings and displays described in Section 14.6.2 Density unit (on page 69).

14.6.11 Reference/process density display

When measuring density in a mass flowmeter, usually process density is displayed. Process density is the density of the fluid at the measured temperature. Reference density can also be displayed as an option. In this case the measured process density will be converted based on a reference temperature. To do so, the reference temperature, the volume temperature coefficient of the fluid and the pressure at reference density (for gases) must be known and have been programmed.

Volume measurement also depends on this setting. If “Process density” is set, the measured volume flow will be displayed. If “Reference density” is set, a volume standardized to the reference density will be displayed.

Display of
[Process density]

The current operating mode for density measurement will be displayed. As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can toggle between the two modes.

14.6.12 Temperature coefficient

In order to calculate the reference density using the process density, the temperature coefficient of the fluid density must be known. In order to improve the resolution and facilitate data entry, the unit of the temperature coefficient is set to 10^{-5} 1/K.

Temp. coeffic.
00.00 E-5/K

The current value in 10^{-5} 1/K will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the density temperature coefficient of the fluid.

14.6.13 Reference temperature

In order to calculate the reference density, the temperature to which the density relates is needed. The temperature for fuel oil usually is 15 °C.

Ref. temperature
015.00 °C

The reference temperature will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the value.

14.6.14 Operating pressure

This function has been prepared for the consideration of gas equations for the measurement of reference density and volume for gases. In this software version, it will not be used for calculations.

operat. pressure
001.00 bar

The current value process pressure will be displayed in bar. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the value.

14.6.15 Density calibration hot medium

A single point density calibration can be made with a suitable mass flow sensor by the operator. The procedure is described in detail in chapter 15 “Density calibration” at page 101.

With this function the necessary measurement of the resonant frequency and the medium temperature is made. The sensor must be filled with a liquid medium. At a temperature of e.g. 60 °C hot water can be used as harmless medium or better use the usual medium under normal operating conditions.

Frequency/temp.
measure? [no]

According to the description in chapter 13.4.3.1 “Selection window/make a selection” the selection can be switched to “yes” and the measurement is executed.

14.6.16 Measured values hot medium

The values of the function “Density calibration hot medium” above are displayed in the upper line. Pressing 2 times the green Enter-key (↵) confirms them without any change. Afterwards the density of the measured medium has to be entered as reference in the lower line.

60.50°C 166.409 Hz
Rho = 0994,1 g/l

The density is always entered in the unit g/l (equivalently too kg/m³). According to the description in chapter 13.4.3.2 “Input window/modify a value” the value can be entered.

14.6.17 Finish density calibration

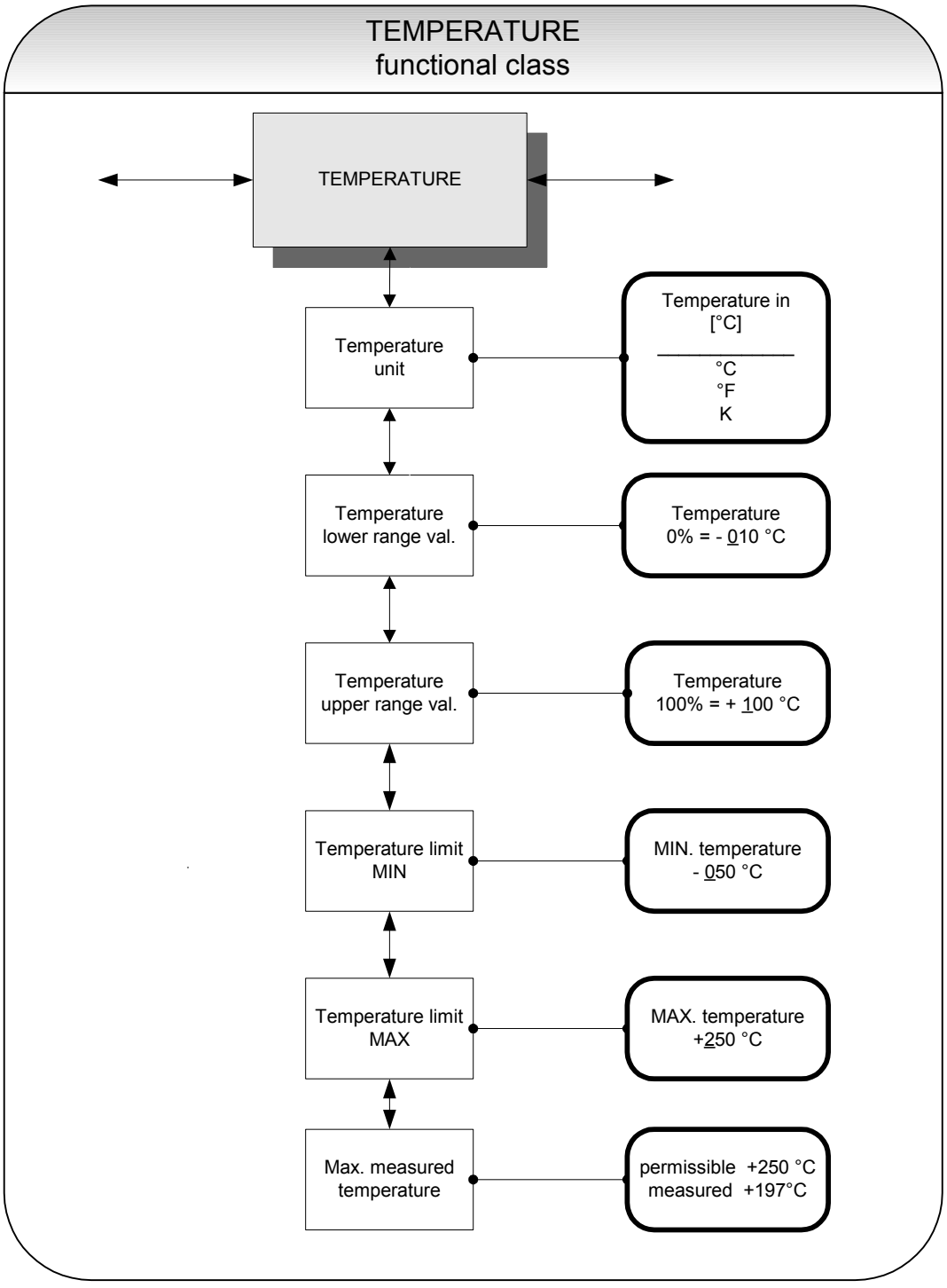
In order to accomplish and store the density calibration by both preceding functions it is necessary to complete some internal calculations.

Calculate?
[no]

According to the description in chapter 13.4.3.1 “Selection window/make a selection” the selection can be switched to “yes” and the reference values for the density measurement are taken over. Thereupon to activate density measurement it must be switched on as described in 14.6.1 “Density measurement on/off” on page 69.

14.7 TEMPERATURE functional class

The TEMPERATURE functional class is comprised of the functions that affect the lower- and the upper-range value and the processing of the measured temperature. The additional service functions will not be described in these instructions. Modifications can only be made in Programming mode (see 13.3 Operating modes), which means that a correct password (see 13.4.3.3 Passwords, 14.2 PASSWORD functional class) must be entered.



14.7.1 Temperature unit

This function allows the operator to set the unit for temperature measurement. Press ↵ to display the following selection field:

Temperature in
[°C]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between °C, °F and K. All display windows, measuring ranges and limiting values refer to the selected unit.

14.7.2 Temperature lower-range value

This function allows the operator to define the lower-range value for temperature measurement. Lower temperatures will set the assigned current output to the minimum value of 0/4 mA. The temperature is entered in the set temperature unit. After selecting the *Temperature lower-range value* function, press ↵ to display the following selection field:

Temperature
0% = + 005 °C

The current lower-range value for temperature measurement will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the value. After setting the new lower-range value, press ↵ to confirm and apply the change.

14.7.3 Temperature upper-range value

This function allows the operator to define the upper-range value for temperature measurement. For this temperature, the assigned current output will be set to the upper-range value of 20 mA. The applied current of the current output assigned to the temperature value is linearly interpolated based on the ratio of the measured value to the difference between lower- and upper-range value.

The temperature is entered in the set temperature unit. After selecting the *Temperature upper-range value* function, press ↵ to display the following selection field:

Temperature
100 % = +090 °C

The current upper-range value for temperature measurement will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the value. After setting the new upper-range value, press ↵ to confirm and apply the change.

14.7.4 Temperature limit MIN

The MIN limiting value for temperature can be evaluated via the status output. This value is entered in the set temperature unit.

After selecting the *Temperature limit MIN* function, press ↵ to display the following selection field:

MIN temperature
-010 °C

The current MIN limiting value will be displayed. If the measured value falls below the limiting value, the “Alarm” status message will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the MIN limiting value for temperature measurement.

14.7.5 Temperature limit MAX

The MAX limiting value for temperature can be evaluated via the status output. This value is entered in the set temperature unit.

After selecting the *Temperature limit MAX* function, press ↵ to display the following selection field

MAX temperature
+ 250 °C

The current MAX limiting value will be displayed. If the measured value falls below the limiting value, the “Alarm” status message will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the MAX limiting value for temperature measurement.

14.7.6 Max. measured temperature

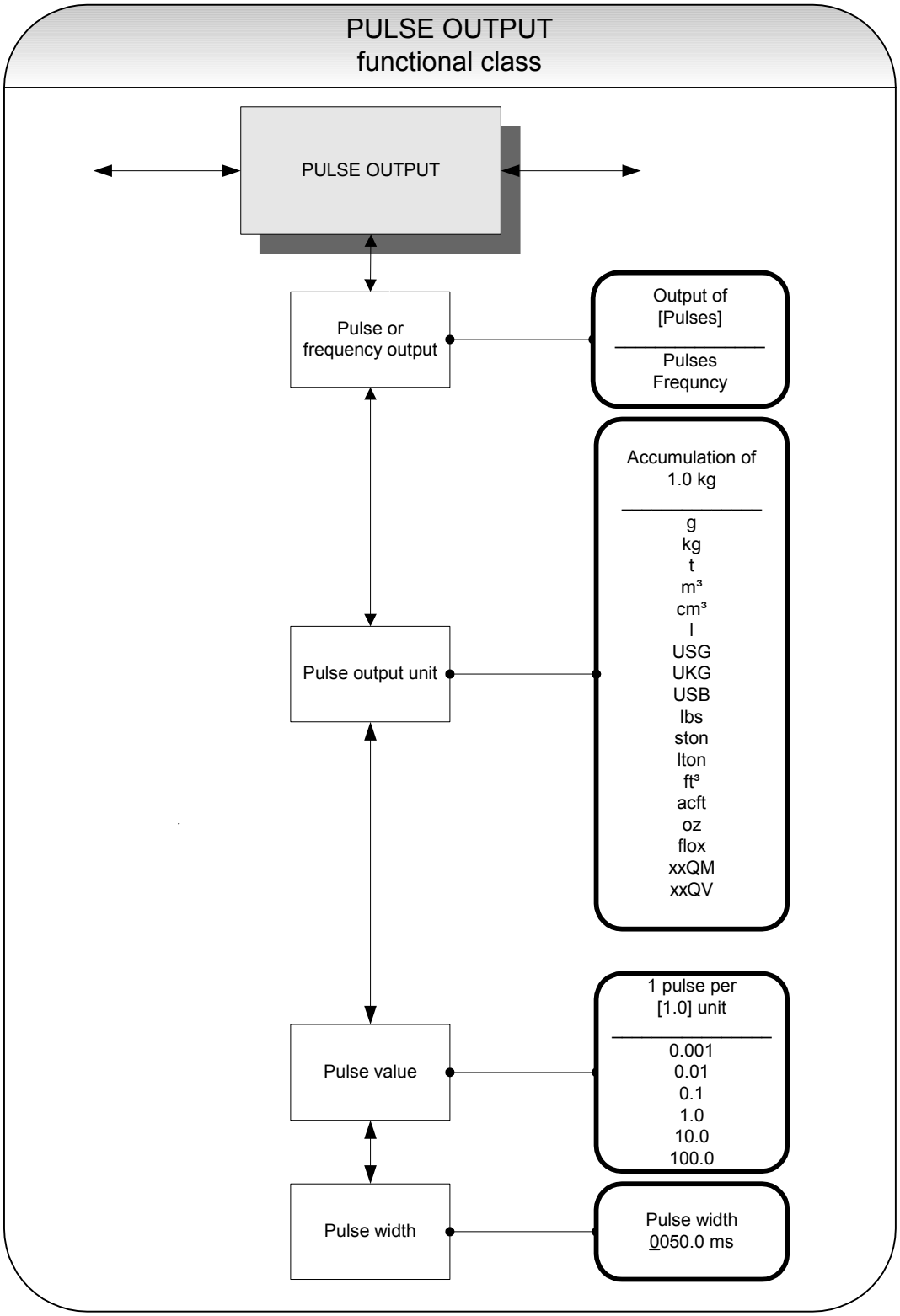
After selecting this display, the largest measured temperature will be displayed. For comparison, the set maximum limiting value will be displayed in the first line.

permissible	+250 °C
measured	+197 °C

This value cannot be reset since it stores the maximum measured process temperature.

14.8 PULSE OUTPUT functional class

The PULSE OUTPUT functional class is comprised of the functions regarding the pulse output.



14.8.1 Pulse or frequency output

The *Pulse or frequency output* function allows the operator to define whether pulses per represent a unit of flow or a frequency between 0 and 1 kHz that represents an analog output over the measuring range.

After selecting the frequency setting, the maximum frequency of 1 kHz will be generated when the upper-range value for mass or volume flow is reached (depending on the selected pulse unit). If the flow rate falls below the low flow volume, the actual frequency is 0 Hz.

After selecting the pulse setting, pulse value and unit the transmitter will determine the number of pulses per flow volume. When choosing a combination of these settings that cannot be fulfilled in real time for the upper-range value (e.g. the number of pulses per time unit cannot be generated due to the pulse width which is too large), the error message “Pulse width too large” or “Inconsistent parameter” will be displayed.

Press ↵ to display the current setting:

Output of
[Pulses]

According to the description in Section 13.4.3.1 Selection window/make a selection, the operator can toggle between frequency and pulse output (default setting).

14.8.2 Pulse output unit

This function allows the operator to define the unit to be counted. After selecting the *Pulse output unit* function, press ↵ to display the following selection field:

Accumulation of
1.0 kg

The current value will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can choose between the following units:

- Mass units:
  - g, kg, t, lbs, ston, lton, oz
- Volume units
  - m³, cm³, l, USG, UKG, USB, ft³, acft, floz
- progr. mass unit:
  - xxQM
- prog. volume unit
  - xxQV

The valency of the programable units are defined by the settings of the flow units described in sections 14.5.2 “Factor mass flow QM programmable unit” on page 64 and 14.5.8 “Factor volume flow QV programmable unit” on page 67.

14.8.3 Pulse value

This function allows the operator to define how many pulses will be output per unit counted. After selecting the *Pulse value* function, press ↵ to display the current unit:

1 pulse per
[1.0] unit

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following pulse values:

Values:

0.001, 0.01, 0.1, 1.0, 10.0, 100.0

14.8.4 Pulse width

This function allows the operator to change the width of the output pulse to be output. If the pulse width is too large for the actual pulse number, it will be reduced automatically. In this case the warning “Pulse output saturated” will be displayed.

After selecting the *Pulse width* function, press ↵ to display the following selection field:

Pulse width
0050.0 ms

The current pulse width will be displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the current value.

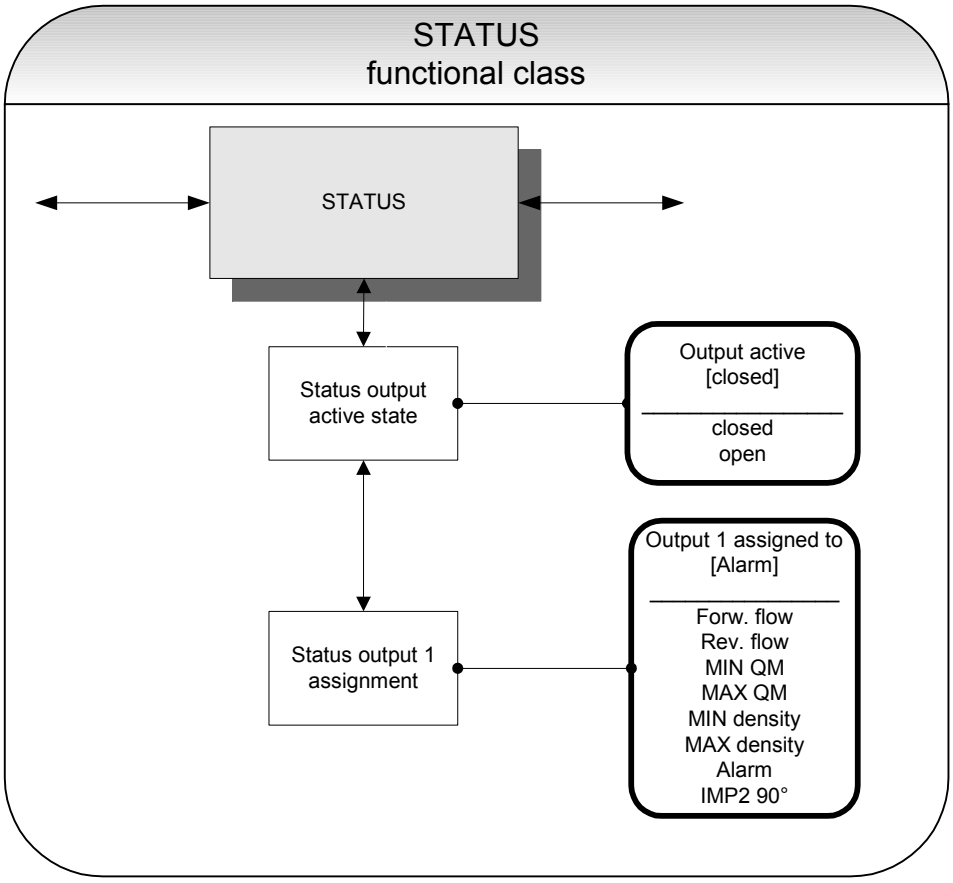
The maximum output frequency can be calculated from the following formula:

$$f = \frac{1}{2 * pulsewidth[ms]} \leq 1000\,Hz$$

If connecting to electrical counter relays, we recommend pulse widths greater than 4 ms; for electromechanical counter relays the preset value should be 50 ms.

14.9 STATUS functional class

The functional class STATUS is comprised of the functions for setting the status output.



14.9.1 Status output active state

The status output can be compared to an electrical relay that can function as make or break contact. For safety-relevant applications, the operator will choose the break contact setting so that a power failure or failure of the electronics can be detected like an alarm. In standard applications, the output is used as make contact.

The *Status output state active state* function allows the operator to define the behavior of the status output.

Status output active
[closed]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- closed
- open

14.9.2 Status output 1 assignment

This function allows the operator to define to which event the status output is to be assigned. The most general assignment is the alarm assignment because all set limiting values and the self-test function are then monitored via the status output.

After selecting the *Status output assignment* function, press ↵ to display the current assignment.

Output 1 assigned to
[Alarm]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- Flow direction recognition
  - Forward flow
  - Reverse flow
- Limiting values:
  - MIN QM
  - MAX QM
  - MIN density
  - MAX density
- All limiting values and error detection
  - Alarm
- Pulse output 2 for custody transfer operations
  - IMP2 90°,

When selecting the IMP2 90° setting, a second pulse output will be realized via the status output that can be used for custody transfer operations.

14.9.3 Status output 2 assignment

Instead of current output 2 there is another status output available for custody transfer operations.
It has the same assignment possibilities as status output 1. However, it cannot be used as pulse output.

After selecting the *Status output assignment* function, press ↵ to display the current assignment.

Output 2 assigned to
[not available]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- Standard setting
  - Not available
- Flow direction recognition:
  - Forward flow
  - Reverse flow
- Limiting values
  - MIN QM
  - MAX QM
  - MIN density
  - MAX density
  - Alarm all limiting values and error detection

14.9.4 Binary input assignment

For the custody transfer operations version, instead of current output 2 there is an additional input available for connecting an external pushbutton.

This pushbutton is assigned the following functions:

- Pressing the button for a short moment: display test
- Pressing the button for more than 5 seconds: error reset

Input assigned to
[Reset error]

The pushbutton may be assigned other functions for non-custody transfer operations. After selecting the Input is released function, press ↵ to display the current assignment.

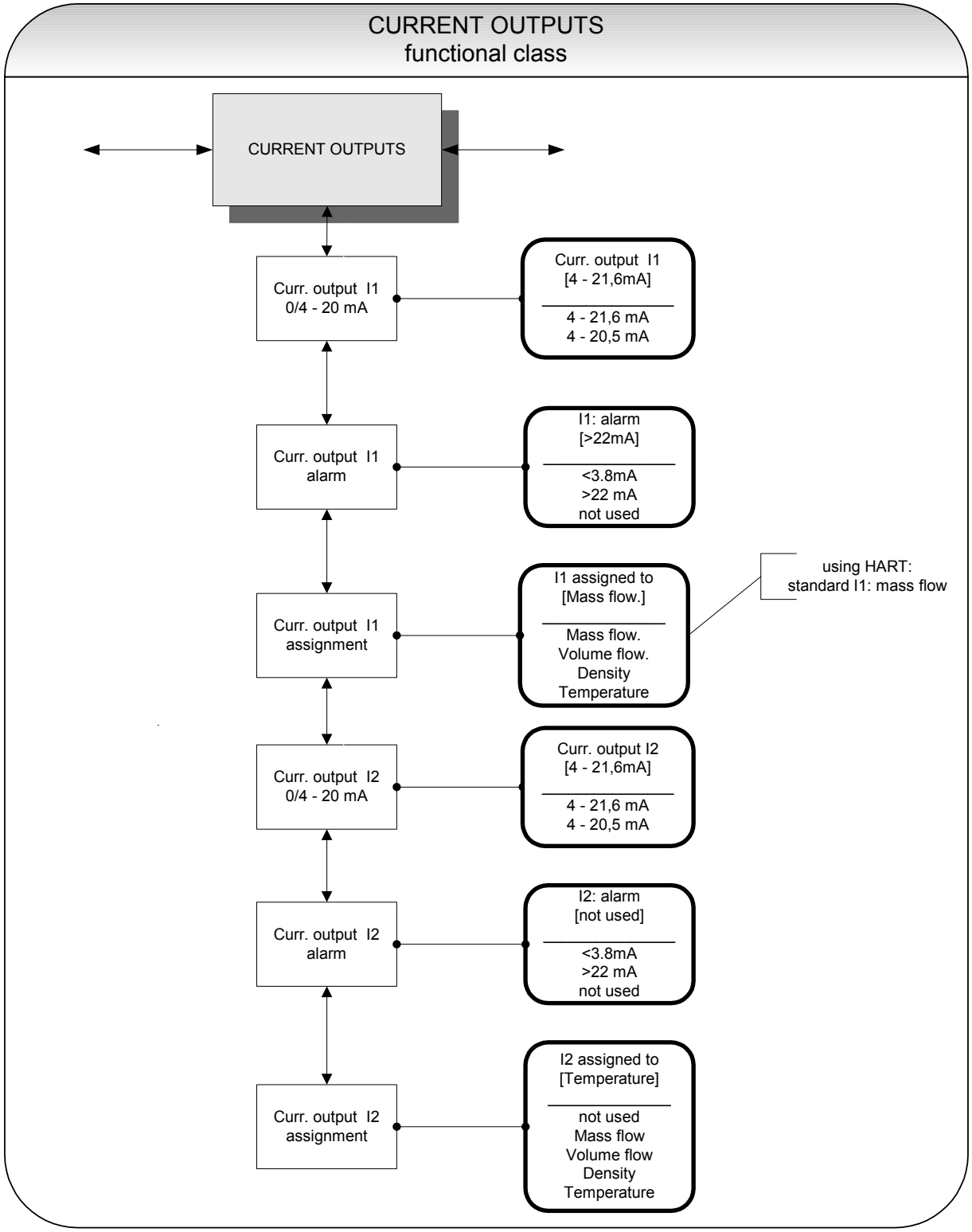
Input assigned to
[Not available]

According to the description in Section 13.4.3.1 Selection window/make a selection, one of the following assignments can be selected:

- Standard setting:
  - Not available
- Others:
  - Counters = 0, i.e. reset counters to zero.
  - Zero point, i.e. carry out zero point calibration
  - Reset error, i.e. acknowledge error messages

14.10 CURRENT OUTPUTS functional class

The CURRENT OUTPUT functional class allows the operator to perform the settings for the current outputs of the transmitter.



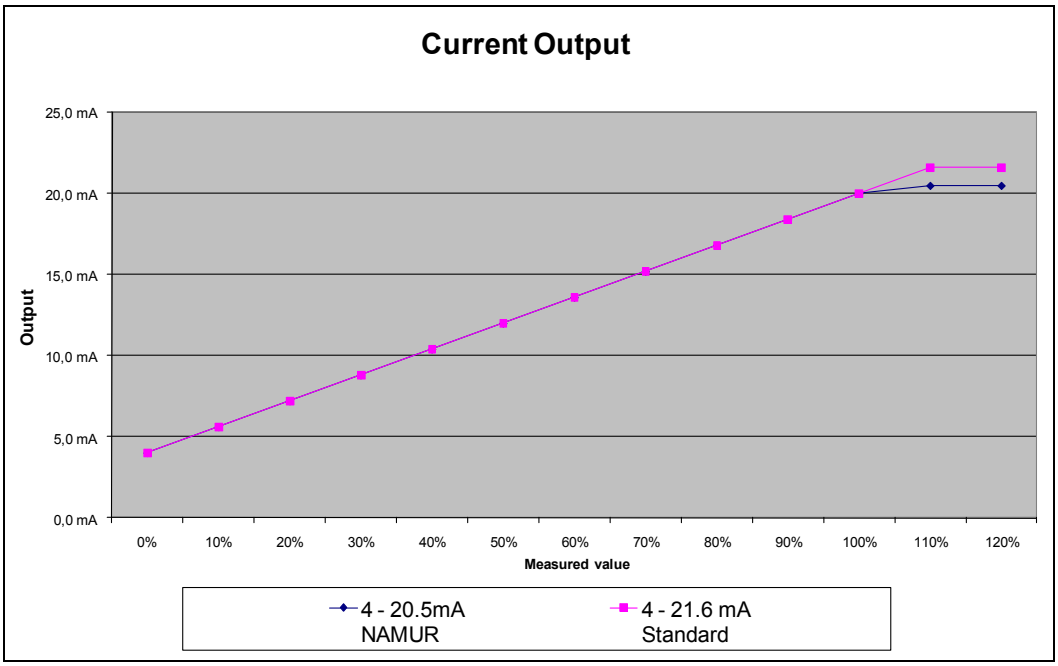
14.10.1 Current output I1 4 to 20 mA

The “Current output I1 4 to 20 mA” function allows the operator to define the range in which the current output is to be operated. Within the range from 4 to 21.6 mA (= 0 ... 110 %) HART® communication is not possible. The range from 4 to 20.5 mA follows the NAMUR recommendation and covers the range from 0 to 104 % of the measuring range. The standard range from 4 to 21.6 mA allows for a control of the measuring range of up to 110 %.

Press ↵ to display the current setting.

Current output I1
[4] – 21.6 mA

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:



14.10.2 Current output I1 alarm

This function allows the operator to define the state taken on by the current output when a state of alarm is detected. This information can be analyzed in the control system. Press ↵ to display the current setting:

I1 : alarm
[>22mA]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- not used — no alarm function
- > 22 mA — current rise in the case of an alarm
- < 3.8 mA — current reduction in the case of an alarm

14.10.3 Current output I1 assignment

This function allows the operator to define the measured value to be output as an analog signal via current output I1. When devices with HART® communication capabilities are used, current output I1 is usually assigned to mass flow. Press ↵ to display the current setting.

I1 assigned to
[Mass flow]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- Mass flow
- Volume flow
- Density
- Temperature

14.10.4 Current output I2 4 to 20 mA

The “Current output I2 4 to 20 mA” function allows the operator to define the range in which the current output is to be operated. The range from 4 to 20.5 mA follows the NAMUR recommendation and covers the range from 0 to 104 % of the measuring range. The standard range from 4 to 21.6 mA allows for a control of the measuring range of up to 110 %.

Press ↵ to display the current setting.

Current output I2
[4] – 21.6 mA

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

14.10.5 Current output I2 alarm

This function allows the operator to define the state taken on by the current output when a state of alarm is detected. This information can be analyzed in the control system. Press ↵ to display the current setting.

I2 : alarm
[not used]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- not used — no alarm function
- > 22 mA — current rise in the case of an alarm
- < 3.8 mA — current reduction in the case of an alarm

14.10.6 Current output I2 assignment

This function allows the operator to define the measured value to be output as an analog signal via current output I2. Press ↵ to display the current setting.

I2 assigned to
[Temperature]

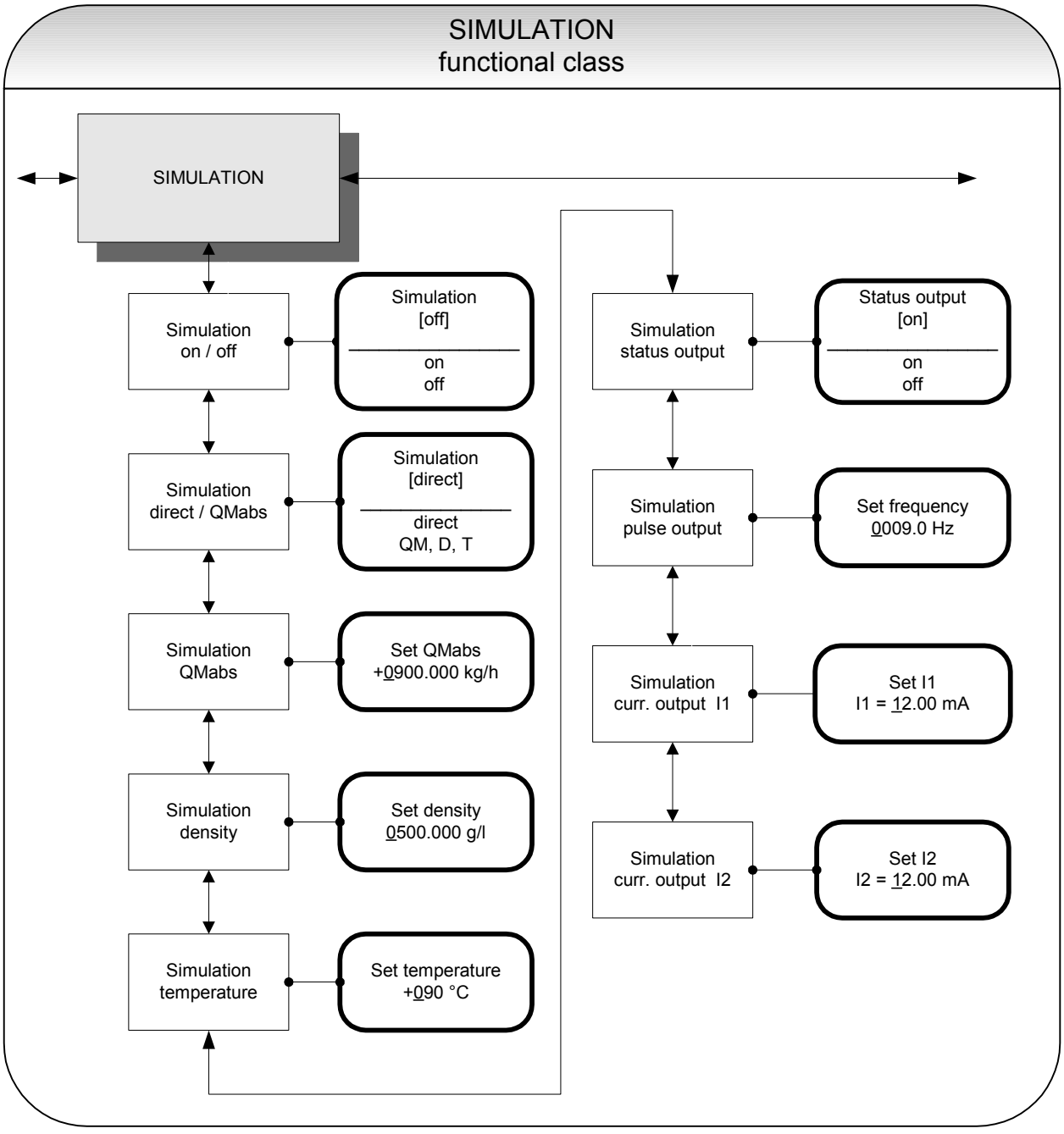
As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- Mass flow
- Volume flow
- Density
- Temperature
- not available (in this case the vendor setting must not be changed)

14.11 SIMULATION functional class

The functional class SIMULATION is comprised of the functions for simulating the outputs. If simulation is activated, all output signals will be generated based on the selected type of simulation. The peripherals connected to the device can be tested without a flowing product.

Simulation will be deactivated automatically if the operator switched the device off or did not touch any control unit keys for about 10 minutes. Simulation can also be activated and controlled via HART® commands.



14.11.1 Simulation on/off

The *Simulation on/off* function allows the operator to activate or deactivate simulation. If simulation is activated, all output signals will be generated based on the selected type of simulation. The peripherals connected to the device can be tested without a flowing product. Press ↵ to display the current status.

Simulation
[off]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator toggle between the "on" and "off."

Simulation will be deactivated automatically if the operator switched the device off or did not touch any control unit keys for about 10 minutes.

14.11.2 Direct simulation

This function allows the operator to define whether simulation is comprised of the measurement of the three physical values mass flow, density and temperature or whether the outputs will be set directly. Press ↵ to display the selected type of simulation.

Simulation
[direct]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can choose between the following settings:

- Direct — pulse and current outputs are programmed directly
- QM, D, T — a measurement is simulated

If "direct" simulation is activated, any output will perform based on the settings described in Sections 14.11.4.1 Status output simulation to 14.11.4.4 Simulation current output I2. It is therefore recommended that the settings be defined before starting simulation. They can then be purposefully changed during simulation.

The status of the outputs during measured value simulation based on the setting "QM, D, T" depends on the selected simulation values of these three variables, the measuring range settings and the assignment of the outputs. If, for example, the pulse output is assigned to volume measurement, it will be affected by all three simulation values at the same time [V ≈ QM (T) / D (T)].


Simulation will be deactivated automatically if the operator switched the device off or did not touch any control unit keys for about 10 minutes.

14.11.3 Measured value simulation

If the operator selected the setting “QM, D, T” described in Section 14.11.2 on page 89, the following three possible settings will affect the output behavior during measured value simulation, where all measured values are simulated at the same time.

14.11.3.1 Simulation mass flow QM abs

In order to simulate mass flow, the operator can define a “measured value.” The flow rates will be simulated in both directions. All outputs will perform based on the simulated measured value.

Set QM abs
±0900.0 kg/h

The simulation value is entered as described in Section 13.4.3.2 Input window/modify a value.

14.11.3.2 Density simulation

In order to simulate density/volume measurement, the operator can define a “density measured value.” If volume measurement is assigned to an output, it will change depending on mass flow and density simulation. All outputs will perform based on the simulated measured value.

Set density
0500.0 g/l

The simulation value is entered as described in Section 13.4.3.2 Input window/modify a value.

14.11.3.3 Temperature measurement simulation

In order to simulate a temperature, the operator can define a “measured value.” All outputs will perform based on the simulated measured value.

Set temperature
+090 °C

The simulation value is entered as described in Section 13.4.3.2 Input window/modify a value.

14.11.4 Direct simulation of outputs

If the operator selected the setting “Direct simulation” described in Section 14.11.2 Direct simulation on page 89, the following four possible settings will affect the output behavior during measured value simulation, where all measured values are simulated at the same time.

14.11.4.1 Status output simulation

The *Status output simulation* function allows the operator to purposefully activate the status output. Press ↵ to display the current state.

Status output
[off]

As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can toggle between “on” and “off.”

14.11.4.2 Pulse output simulation

The *Pulse output simulation* function allows the operator to define a frequency to be assigned to the pulse output. After selecting this function and pressing ↵, the following selection field will be displayed:

Set frequency
0210.0 Hz

This field shows the current frequency. As mentioned in Section 13.4.3.2 Input window/modify a value, the definable frequency ranges from 6 Hz to 1100 Hz.

14.11.4.3 Simulation current output I1

This function allows the operator to define a current for current interface 1. Press ↵ to display the set current.

Set I1
I1 = 10.50 mA

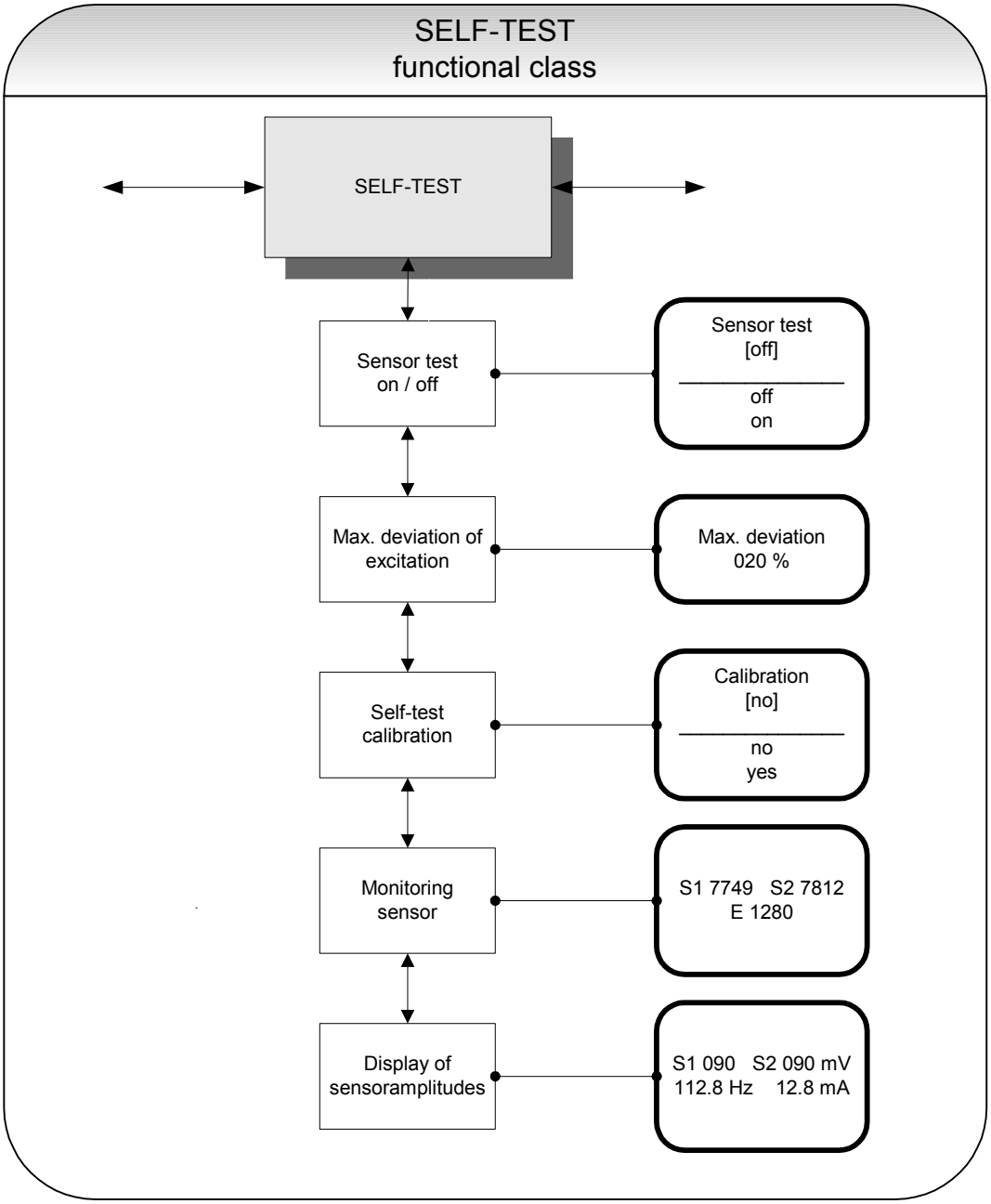
As mentioned in Section 13.4.3.2 Input window/modify a value, the current value can be changed.

14.11.4.4 Simulation current output I2

As described in Section 14.11.4.3, current output 2 can also be configured.

14.12 SELF-TEST function class

The SELF-TEST function class is comprised of the functions relating to the self-test of the sensor.
The diagnostic functions of the transmitter, which monitor the proper functioning of the electronics and the software, are always active and cannot be switched off. The excitation current can be monitored in addition.



The excitation current of each sensor in the system individually depends on the sensor itself, the fluid and the installation conditions. If the excitation currents changes while the fluid remains the same, conclusions may be drawn for e.g. potential wear and tear, viscosity changes or air bubbles. The operator has the possibility of defining a “normal state” (“Self-test calibration”) and setting the limit for a permissible deviation. This function is deactivated in the device when delivered.

14.12.1 Sensor test on/off

The *Sensor test on/off* function allows the operator to activate or deactivate the monitoring function of the excitation current.

Sensor test
[off]

According to the description in Section 13.4.3.1 Selection window/make a selection, the operator can toggle between “on” and “off.” The standard factory setting is “off.”

14.12.2 Max. deviation of excitation

This function allows the operator to define a limiting value in the form of a percentage deviation from the normal value. The excitation current is electronically limited to 50 mA (display value 500) and may take on larger values for only a limited period of time (transient reactions).

Max. deviation
020 %

The current limiting value is displayed. As mentioned in Section 13.4.3.2 Input window/modify a value, the value can be changed taking into account permissible fluctuations.

14.12.3 Self-test calibration

Since the quantity of the excitation current does not only depend on the sensor itself but also on the installation conditions and the viscosity and density of the fluid, the normal value can only be calculated on site during operation using the *Self-test calibration* function.

Calibration
[no]

If the operator toggles to [yes] according to the description in Section 13.4.3.1 Selection window/make a selection, the normal value will be calculated automatically. No additional information is needed for this function.

14.12.4 Monitoring of sensor amplitude and excitation current

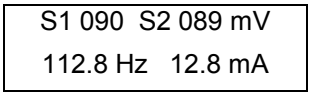
The first line of this window contains the amplitudes of the sensor signals S1 and S2 in 10 µV. Both values should be close to each other or identical (ideal case). The second line shows the excitation current in 10 µA units.

S1 7749 S2 7812
E 1280

Example: The sensors have amplitudes of 77.49 mV and 78.12 mV. The excitation current is 12.8 mA. These values are used as reference values for the self-test function. They are measured by using the function 14.12.3 Self-test calibration on page 93. Afterwards they can be displayed or edited by this function.

14.12.5 Display of sensor amplitudes

The first line of this window contains the actual measured amplitudes of the sensor signals S1 and S2. Both values should be close to each other or identical (ideal case). The second line shows the excitation frequency and current.

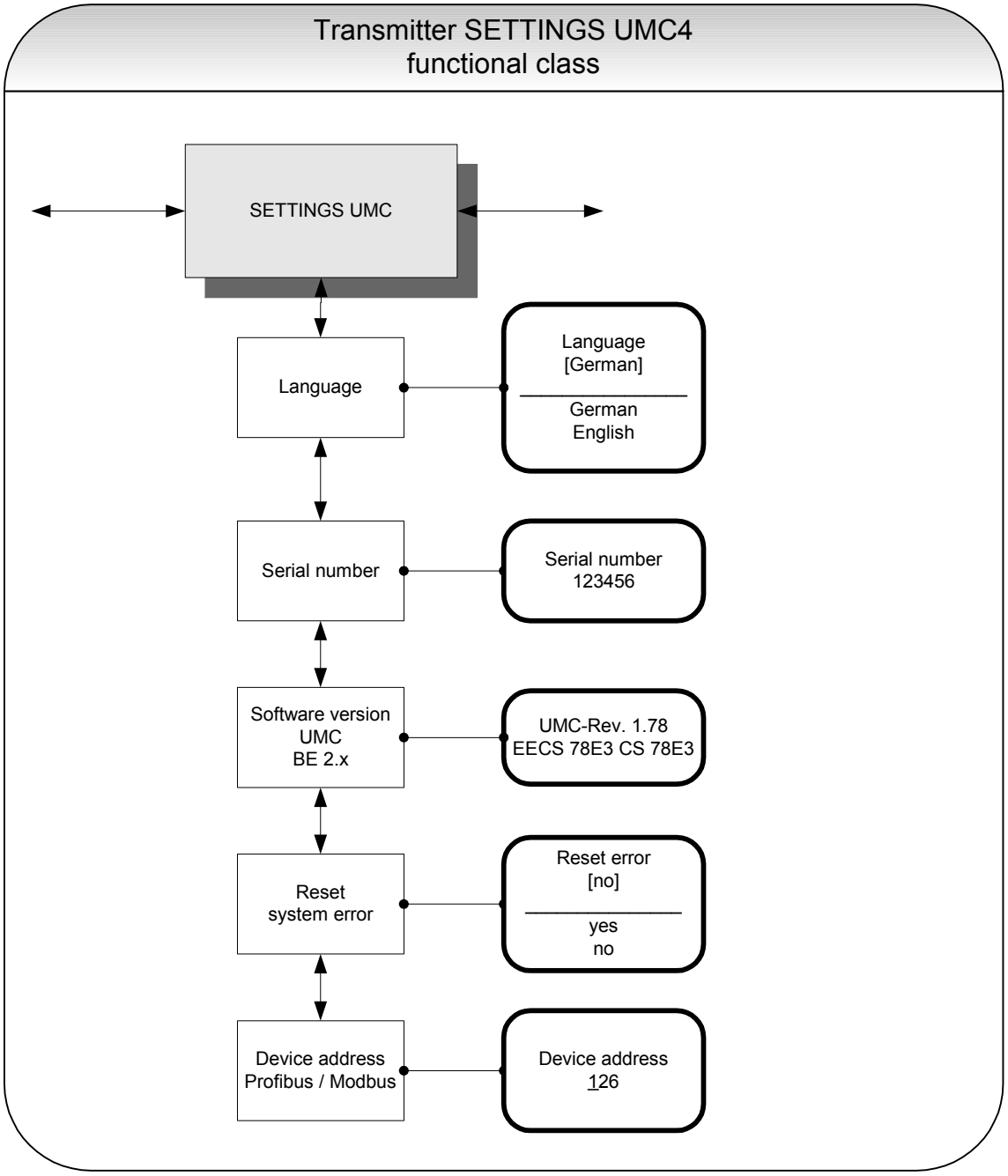


Example: The sensors have amplitudes of 90 mV and 89 mV. The excitation current is 12.8 mA and the actual resonance frequency is 112.8 Hz.

The combination with the raw value display (see chapter 14.1.14 Raw values on page 55) supports the analysis of all electrical signals between mass flow sensor and transmitter.

14.13 UMC TRANSMITTER SETTINGS functional class

This functional class is comprised of the general settings (e.g. language) affecting the behavior of the transmitter.



14.13.1 Language

Two languages are available in the control unit BE4: German and English. As mentioned in Section 13.4.3.1 Selection window/make a selection, the operator can toggle between these languages.

Language
[English]

Other languages such as French, Italian or Spanish will be available in a special version of the control unit BE4.

14.13.2 Serial number

With the help of the *Serial number* function, the transmitter is assigned to an order. This number provides access to internal vendor data if the device needs servicing. The serial number is printed on the rating plate of the transmitter. After selecting this function, press ↵ to display the following information field:

Serial number:
123456

This entry should never be changed so as to ensure that the sensor, the transmitter and the documents created within quality management are assigned correctly.

14.13.3 Software version

When the function *Software version* is displayed, the software version of the control unit BE will be shown. Example: Version 2.0:

UMC Software
Version BE 2.0

After selecting this function, the version of the transmitter software will be shown (example: 1.78).

UMC Rev.: 1.78
EECS 78E3 CS 78E3

The second line contains the hexadecimal checksum that was calculated via the program storage created during program development and the microcontroller checksum of the same storage. Both checksums must be identical, when the program storage has not been damaged.

14.13.4 Reset system error

The integrated diagnostic system of the UMC4 transmitter distinguishes between two types of errors (see also Section 17 UMC4 transmitter error messages). Self-test errors such as problems with a sensor line or inconsistent parameter inputs are displayed as textual error messages. Once the error has been eliminated, the message automatically disappears from the display. For further information, see Section 17.3.1 Display of self-test errors.

Errors that are attributable to system memory or software, division by zero, or a fault in the electronics unit are designated as system errors. These error messages are not reset automatically after the error (usually of very brief duration) is eliminated. **Before resetting a system error manually, we advise that you**

contact our technical service department. For further information, see Section 17.3.1 Display of self-test errors.

Reset error
[no]

If the operator toggles to [yes] and confirms the action according to the description in Section 13.4.3.1 Selection window/make a selection, the error messages disappears from the display. If the message reappears shortly after, do contact our technical service department.

14.13.5 Profibus/Modbus device address

Before connecting fieldbus devices to a bus system, the operator must define a device address. This address is a unique assignment to a participant device in a bus system (similar to a street number).

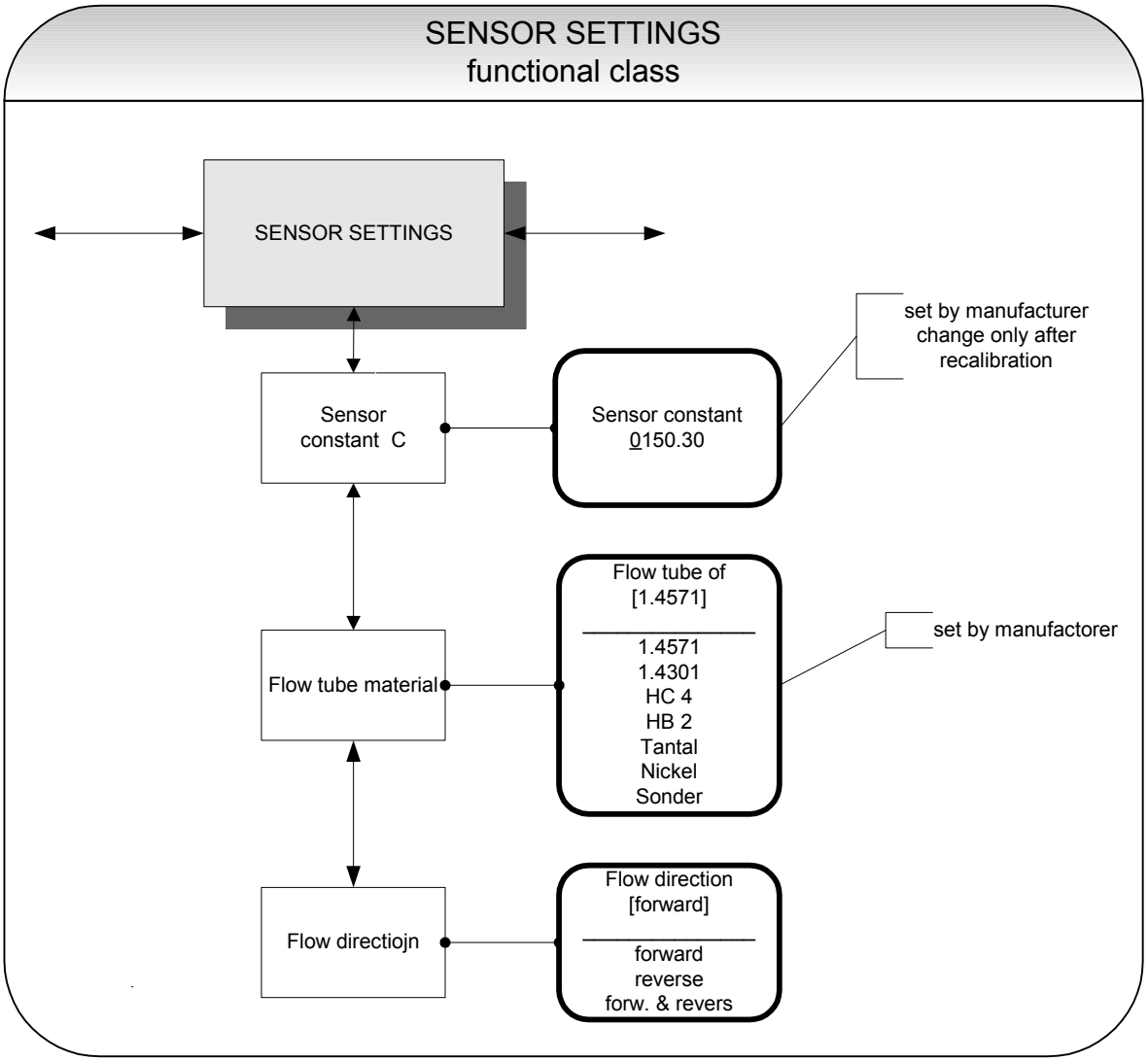
After selecting the *Profibus/Modbus device address*, press ↵ to display the set address:

Device address
126

As mentioned in Section 13.4.3.2 Input window/modify a value, the operator can change the displayed value. After setting the new device address, press ↵ to confirm and apply the change.

14.14 SENSOR SETTINGS functional class

The SENSOR SETTINGS functional class is comprised of the settings regarding the mass flow sensor.



14.14.1 Sensor constant C

Sensor constant C is the sensor calibration value for mass flow. This constant is defined when the flow-meter is calibrated at the factory and can be found on the rating plate.

Sensor constant
+0150.00 kg/h

	**CAUTION:** Changing sensor constant C to a value that differs from the value on the rating plate of the sensor connected to the flowmeter will result in false readings.

Normally, the sensor constant is changed only when the device is calibrated, e.g. for a validation measurement for a custody transfer operation.

Note:
The sensor constant must always be preceded by a plus or minus sign. The delivery default setting is a plus sign. If inlet and outlet section are interchanged when the device is installed (the flow direction is indicated by an arrow on the sensor), the transmitter will display a “forward flow” negative measurement value. If the (plus or minus) sign of the sensor constant is then changed without changing the actual value, a plus sign will again be displayed. No changes need be made in the disposition of the electrical connections (wires).

14.14.2 Sensor material

The *Sensor material* function allows the flow tube material code to be entered. This material code can be found on the sensor rating plate. This setting is defined by the vendor when the device is first put into operation at the factory.

Flow tube material
[1.4571]

This field is for the operator’s information only.

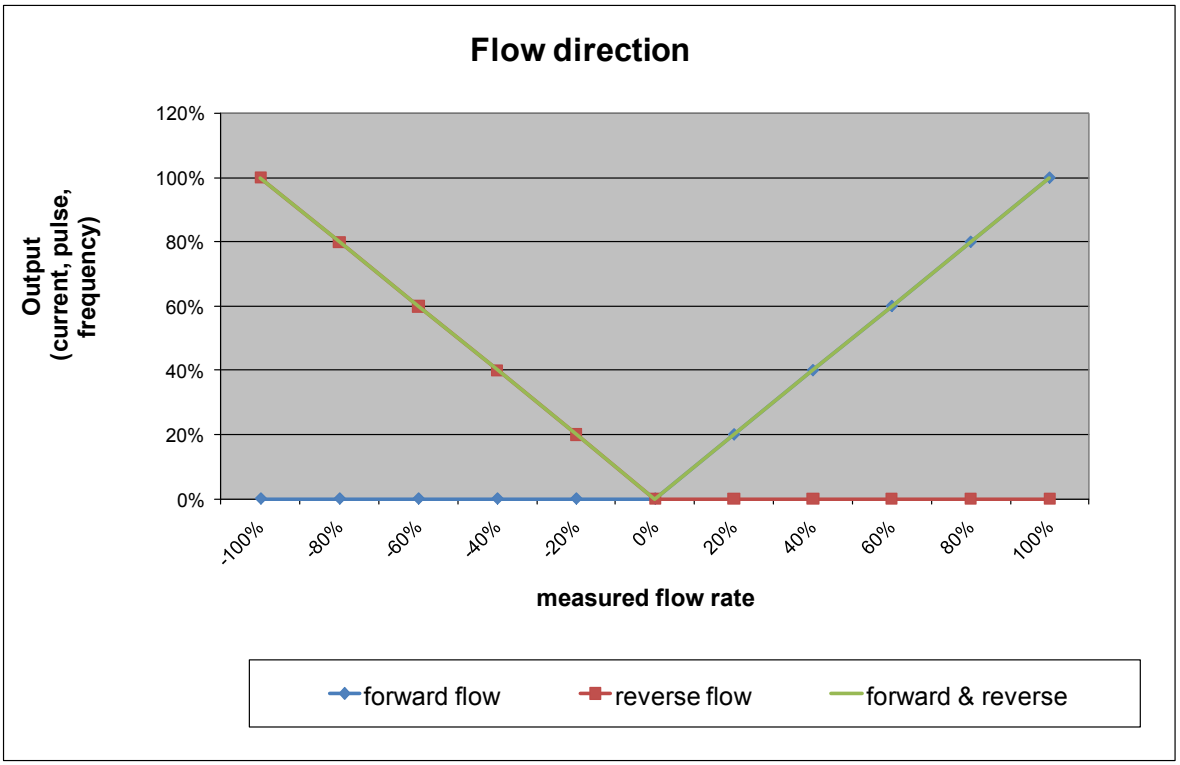
14.14.3 Flow direction

This function allows the operator to define the flow direction that the transmitter will evaluate. Only “forward” should be selected so as to prevent reverse flow from being measured. The standard factory setting is “forward & reverse.” After selecting the *Flow direction* function, press ↵ to display the current setting.

Flow direction
[forward]

As mentioned in Section 13.4.3.1 Selection window/make a selection the operator can choose between:

- forward
- reverse
- forward & reverse



15. Density calibration

For continuous processes, which process only small variations in temperature and liquid media of comparable density, a density calibration can be accomplished locally.

15.1 Conditions

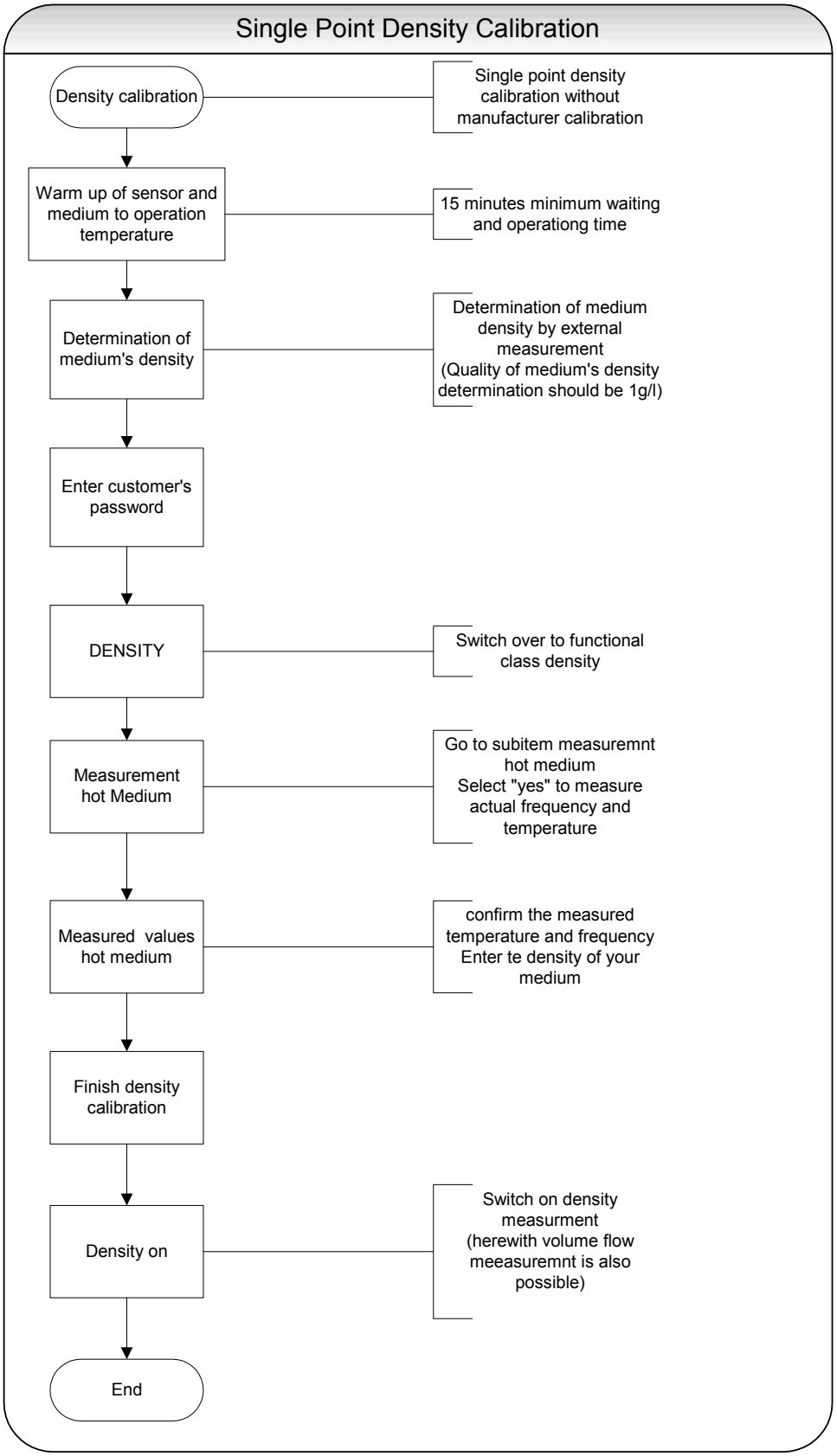
For a local density calibration the following conditions must be fulfilled:

- The sensor must be suitable for a density measurement. For all these sensors the manufacturer offers a 3-point calibration with an accuracy of at least 5 g/l. Sensors, for which the manufacturer calibration is not offered, are not suitable also for the local single point calibration.
- For the local calibration must the medium's density be known or by a suitable procedure be determined exactly at the temperature in the sensor.
- The medium must be liquid. For gaseous media the density calibration is not suitable.

15.2 Procedure

The procedure of the density calibration is represented in the following diagram:

- First the transmitter is switched on and the sensor is filled with the medium under operating conditions.
- So that the sensor including housings and flanges can take the operating temperature a waiting period of at least 15 minutes is to be kept.
- After the input of the customer's password select functional class DENSITY and "density calibration hot medium". (See also chapter 14.6.15 on page 73.)
- Independently of the kind of the liquid medium and its temperature the beginning of the calibration is confirmed by selecting "yes". Thereupon the transmitter measures medium temperature and current resonant frequency of the sensor.
- In the following the function "measured values hot medium" has to be selected The displayed measured values of temperature and frequency are confirmed by 2 times pressing the Enter-key. In the next field the density of the medium has to be entered in unit of g/l or kg/m³. (See also chapter 14.6.16 on page 73.)
- Subsequently, the function "finish density calibration" is used to finish density calibration. (See also chapter 14.6.17 on page 74.)
- Finally the function "density measurement on/off" activates the density measurement. (See also chapter 14.6.1 on page 69.)
- Now the measured density and also volume flows can be indicated or assigned to one of the outputs e.g. current output 2.


Single Point Density Calibration
Density calibration
Single point density calibration without manufacturer calibration
Warm up of sensor and medium to operation temperature
15 minutes minimum waiting and operationg time
Determination of medium's density
Determination of medium density by external measurement (Quality of medium's density determination should be 1g/l)
Enter customer's password
DENSITY
Switch over to functional class density
Measurement hot Medium
Go to subitem measuremnt hot medium Select "yes" to measure actual frequency and temperature
Measured values hot medium
confirm the measured temperature and frequency Enter te density of your medium
Finish density calibration
Density on
Switch on density measurment (herewith volume flow meeasuremnt is also possible)
End

16. Use of the UMC4 for custody transfer operations

The transmitter UMC4 is not certified for custody transfer applications. The transmitter fulfills the requirements regarding the measuring accuracy and repeatability. However for this application additional inputs and outputs are demanded, which the transmitter UMC4 has not available.

17. UMC4 transmitter error messages

The integrated UMC4 transmitter distinguishes between two types of errors. Self-test errors such as problems with a sensor line or inconsistent parameter inputs are displayed as text error messages. Once the error has been eliminated, the message automatically disappears from the display. For further information, see Section 17.3.1 Display of self-test errors.

Errors that are attributable to system memory or software, division by zero, or a fault in the electronics unit are designated as system errors. These error messages are not reset automatically after the error (usually of very brief duration) is eliminated. **Before resetting a system error manually, we advise that you contact our technical service department.** For further information, see Section 17.3.2 Display of system error.

If the cause of any of the error messages described below cannot be eliminated, contact the device vendor.

17.1 Standard operating mode

The transmitter operates as described above. After the cause of the error message has been eliminated, the message automatically disappears. The self-test for monitoring the excitation current can be activated or deactivated via the “Sensor test” function.

17.2 Custody transfer mode

The transmitter UMC4 is not certified for custody transfer applications.

17.3 List of error messages

17.3.1 Display of self-test errors

Self-test errors are displayed as plain text in the set language (German or English) on the second line of the LCD.

Display (German)	Display (English)	Description	Possible cause of error and remedy
Rohr leer	empty pipe	Empty-pipe detection has been activated. Fluid density is below the limit value for density; empty-pipe detection, pipe is empty.	Product contains air bubbles/pipe is empty. Bubble-free filling must be ensured.
Teilfüllung?	Partially filled?	Exciter current large and sensor signal small	Gas bubbles in the medium or sensor only part-filled.
Netzausfall?	Power fail?	Will detect the interruption of the supply voltage for transmitters approved for custody transfer operation if the flow rate is > 0.5 % of upper-range value.	Check power supply
Bruch/Schluß T	malfunction T	Interruption/short circuit in the temperature sensor measuring circuit	Check the lines between temperature sensor and transmitter. Measure resistance of PT1000

Display (German)	Display (English)	Description	Possible cause of error and remedy
Bruch/Schluß S1	malfunction S1	Interruption/short circuit in the connection of sensor coil 1	Check the lines between sensor coil and transmitter. Measure coil resistance.
Bruch/Schluß S2	malfunction S2	Interruption/short circuit in the connection of sensor coil 2	Check the lines between sensor coil and transmitter. Measure coil resistance.
Erreger zu groß	exc. too large	A excitation current exceeding the limit will be detected.	Asymmetric filling of the flow tubes, air bubbles when measuring liquids or: condensate in the flow tube when measuring vapor or gases Electrical cause: Check the lines between excitation coil and transmitter. Check for bonding. Check the excitation coil and the magnet.
Erreger zu klein	exc. too small	A excitation current exceeding the limit will be detected in the case of transmitters approved for custody transfer operations.	Check the lines between excitation coil and transmitter.
Messkreis überst.	meas. circ. sat.	The instrument transformer for phase metering is overloaded. The measured phase displacement is too large.	Mass flow rate is too high.
QM > 110 %	QM > 110 %	The mass flow rate exceeds the set upper-range value for the flow rate by more that 10 %.	Reduce the flow rate and adjust the measuring range if necessary.
OVERFLOW !	OVERFLOW !	Forward or Revers flow counter overflow	Reset counter; possibly change to a bigger counter unit
Strom1 Überst.	curr. 1 saturated	The output of current interface 1 is overloaded. Based on the selected settings and the currently assigned measured variable, the current to be output is > 21.6 mA.	Check the upper-range value and the flow rate settings.
Strom2 Überst.	curr. 2 saturated	The output of current interface 2 is overloaded. Based on the selected settings and the currently assigned measured variable, the current to be output is > 21.6 mA.	Check the upper-range value and the flow rate settings.
IMP übersteuert!	pulse out satur.	The pulse output is overloaded. The current measured value requires a pulse rate, which can no longer be generated with the help of the set pulse duration and pulse value.	Check pulse duration, pulse value, and measuring range. Check the flow rate.

Display (German)	Display (English)	Description	Possible cause of error and remedy
Temperatur>MAX	Temperature > MAX	The measured temperature exceeds the set upper-range value for temperature.	Product temperature is too high; adjust the temperature range and the limit values if necessary.
Temperatur<MIN	Temperature < MIN	The measured temperature is below the set lower-range value for temperature.	Product temperature is too low; adjust the temperature range and the limit values if necessary.
Parameter inkons.	params inconsist	Parameter is inconsistent.	Check the parameter settings. The set parameters are contradictory. Example: Upper-range value, pulse value and pulse duration must be matched in such a way that the combination fits for all measured values.
ext EEPROM fehlt	missing EEPROM	The data memory module (DSB) with the calibration data of the sensor and the customer-specific settings of the transmitter is not plugged-in.	Insert the data storage module (DSB/UMF33) in the corresponding receptacle on the CPU printed board UMC-30.
falsches EEPROM	wrong EEPROM	EEPROM of a former model (e.g. UMC2 or UMF) has been plugged-in as memory module.	
interne Kommunikation gestört	internal communication faulty	Communication between control unit and transmitter is faulty.	Contact the device vendor/customer service department.

Information:

Error message: “Parameter is inconsistent” (system error 0x0400)?

To generate a list of the inconsistencies, first enter a valid password and then an invalid password. The control unit will show a list of current errors (only once). The operator can then correct the inconsistent settings after entering a valid password.

17.3.2 Display of system error

System errors consist of the message text “system error” and a 5-digit number in hexadecimal code. The meaning of the individual error codes is described in the following table. If several errors occur at the same time, the hexadecimal sum of the individual errors will be displayed. The errors are coded in such a way that the individual errors can be easily identified. The sums are unique.

Descriptor label (never displayed)	**Constant/ display**	**Description**
SystemfehlerDiv0	0x00001	Arithmetical error/division by zero
SystemfehlerIntEEProm	0x00002	Transmitter data checksum is faulty; reinitialization is necessary.
SystemfehlerPruefsumme	0x00004	Sensor data checksum is faulty.
SystemfehlerLeeresEEPROM	0x00008	Ext. EEPROM is present but empty (no content).
SystemfehlerEEPROM	0x00010	Value could not be stored/read out.
SystemfehlerPhase	0x00020	Phase measurement/mass flow is faulty.
SystemfehlerFrequenz	0x00040	Frequency measurement/density measurement is faulty.
Systemfehler DSP Version	0x00080	DSP firmware is outdated (not adjusted to the transmitter operating system)
SystemfehlerZeitkonstante	0x00100	Initialization of time constants failed.
SystemfehlerMesswert	0x00200	Faulty calculation of measured value
SystemfehlerParameter	0x00400	Settings are inconsistent.
SystemfehlerRAMPrüfsumme	0x00800	Defective main memory, inconsistent checksum (custody transfer operation)
SystemfehlerFlashPrüfsumme	0x01000	Defective program memory, inconsistent checksum
SystemfehlerDSPPrüfsumme	0x02000	Defective program memory, inconsistent checksum
SystemfehlerZähler	0x04000	Custody transfer operation: count differs from corresponding back-up copy
SystemfehlerWDG	0x08000	Internal watchdog: time limit has been exceeded.

SystemfehlerSchreibfehler	0x10000	Defective memory location in the main memory
SystemfehlerDSPKommu	0x20000	Faulty communication between DSP and microcontroller, no processing of measured values

18. Certificates and approvals

CE marking: The measuring system complies with the legal requirements of the Electromagnetic Compatibility Directive 89/336/EC and the Explosion Protection Directive 94/9/EC.
The CE mark indicates that the device complies with the aforementioned directives.
See also section 20 “Declaration of conformity” on page 110

Ex approval: **UMC4 transmitter**:
BVS 10 **ATEX** E 110 X
II(1)2G Ex d [ia Ga] IIC T4 - T3 Gb

19. Standards and authorizations

19.1 General standards and directives

EN 60529 Ingress protection class (IP code)
EN 61010 Safety requirements for electrical metering, control and laboratory devices
NAMUR guideline NE21, Version 22/08/2007

19.2 Ex-Approval transmitter

Explosion Protection Directive 94/9/EEC

EN 50014 General guidelines	EN 60079-0:2004
EN 50018 Flameproof enclosures “d”	EN 60079-1:2004
EN 50019 Increased safety “e”	EN 60079-7:2003
EN 50020 Intrinsic safety “i”	EN 60079-11:2007
EN 50284 Group II Category 1G	EN 60079-26:2004

19.3 Electromagnetic compatibility

EMC Directive 2004/108/EC
EN 61000-6-2:1999 (immunity for industrial environments)
EN 61000-6-3:2001 (emissions residential environments)
EN 55011:1998+A1:1999 group 1, class B (emitted interference)
DIN EN 61000-4-2 to DIN EN 61000-4-6
DIN EN 61000-4-8
DIN EN 61000-4-11
DIN EN 61000-4-29
DIN EN 61326

20. Declaration of conformity

CE

K o n f o r m i t ä t s e r k l ä r u n g
Declaration of conformity

Heinrichs Messtechnik GmbH, Robert-Perthel-Straße 9, 50739 Köln

erklärt in alleiniger Verantwortung, dass das Produkt
declares in sole responsibility that the product

Coriolis Massedurchflussmesser
Coriolis mass flowmeter
Typ / type **TM* / UMC4**

mit den Vorschriften folgender Europäischer Richtlinien übereinstimmt:
conforms with the regulations of the European Directives:

EMV-Richtlinie 2004/108/EG, EMC Directive 2004/108//EC
Niederspannungsrichtlinie 2006/95/EG, Low Voltage Directive 2006/95/EC
Druckgeräterichtlinie 97/23/EG, Pressure Equipment Directive 97/23/EC

Angewandte harmonisierte Normen oder normative Dokumente:
Applied harmonised standards or normative documents:

EMV- Richtlinie 2004/108/EG, EMC Directive 2004/108//EC
EN 61000-6-2:2005 (Störfestigkeit Industriebereich / immunity industrial environmen)
EN 61000-6-3:2007 (Störaussendung Wohnbereich / emission residential, commercial)
EN 55011:2007 Gruppe 1, Klasse B (Gruppe 1, Klasse B, Funkstörungen / ISM ratio-frequency equipment)
EN61326-1:2006 EMV-Anforderungen / EMC requirements

Niederspannungsrichtlinie 2006/95/EG, Low Voltage Directive 2006/95/EC
EN 61010-1: 2004 Sicherheitsbestimmungen für elektrische Mess-, Steuer-, Regel- Laborgeräte
Safety requirements for electrical measuring, control and laboratory devices

Druckgeräterichtlinie 97/23/EG, Pressure Equipment Directive 97/23/EC
AD 2000-Merkblätter Auslegung und Berechnung von Druckbehältern
Regulations for pressure vessel calculations

Name und Anschrift der benannte Stelle der QS-Überwachung, Name and address of the Notified Body
(RL 97/23/EG)
Identifikationsnummer: 0036

TÜV SÜD Industrie Service GmbH
Dudenstraße 28
D-68167 Mannheim

Köln, 08.03.2010

Frank Schramm
(Geschäftsführung / General Management)

21. Decontamination certificate for device cleaning

Company name: ..... Address: .....

Department: ..... Name of contact person: .....

Phone: .....

Information pertaining to the enclosed Coriolis flowmeter

Model TM.....

was operated using the following fluid:.....

In as much as this fluid is water-hazardous / toxic / corrosive / combustible / a health hazard / environmentally hazardous

we have done the following:

- Checked all cavities in the device to ensure that they are free of fluid residues*
- Washed and neutralized all cavities in the device*
- Cleaned all seals/gaskets and other components that come into contact with the fluid*
- Cleaned the housings and all surfaces*

*cross out all non-applicable items

We hereby warrant that no health or environmental hazard will arise from any fluid residues on or in the enclosed device.

Date: ..... Signature .....

Stamp

Version / printed: **20.12.2010 / 20.12.2010**

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