

# Operating Instructions for Guided Wave Radar Level Transmitter (TDR)

## Model: NGM



We don't accept warranty and liability claims neither upon this publication nor in case of improper treatment of the described products.

The document may contain technical inaccuracies and typographical errors. The content will be revised on a regular basis. These changes will be implemented in later versions. The described products can be improved and changed at any time without prior notice.

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### 2. Note

Please read these operating instructions before unpacking and putting the unit into operation. Follow the instructions precisely as described herein.

The devices are only to be used, maintained and serviced by persons familiar with these operating instructions and in accordance with local regulations applying to Health & Safety and prevention of accidents.

When used in machines, the measuring unit should be used only when the machines fulfil the EC-machine guidelines.

This quick installation guide gives instructions for mounting, wiring, and basic configuration of NGM. This will be sufficient to achieve a fully functional sensor in most applications. For further details and advanced configuration of NGM, please contact your local distributor or KOBOLD directly.

## 3. Instrument Inspection

Instruments are inspected before shipping and sent out in perfect condition. Should damage to a device be visible, we recommend a thorough inspection of the delivery packaging. In case of damage, please inform your parcel service / forwarding agent immediately, since they are responsible for damages during transit.

#### Scope of delivery:

The standard delivery includes:

- Guided Wave Radar Level Transmitter model: NGM
- Operating Instructions

## 4. Regulation Use

Any use of the Guided Wave Radar Level Transmitter, model: NGM, which exceeds the manufacturer's specification may invalidate its warranty. Therefore, any resulting damage is not the responsibility of the manufacturer. The user assumes all risk for such usage.

## 5. Operating Principle

NGM uses TDR (Time Domain Reflectometry) technology, which is also known as Guide Microwave or Guided Wave Radar. This means that low-energy and high-frequency electromagnetic impulses, generated by the sensor's circuitry, are propagated along the probe which is immersed in the liquid or solid to be measured.

When these impulses hit the surface of the media, part of the impulse energy is reflected back up the probe to the circuitry which then calculates the level from the time difference between the impulses reflected.

The sensor can output the analysed level as 4...20 m analogue output, or it can convert the values into freely programmable switching output signal.

## 6. Mechanical Connection

#### 6.1 Mounting

In case NGM is delivered with a detached probe, attach the probe onto the small threaded stud below the hexagon. Ensure that you mount the counter nut first to secure the probe connection: it has to be interlocked against the probe, NOT against the plastic of the feedthrough (this would result in sheering off the small threaded stud; permanently damaging the sensor).

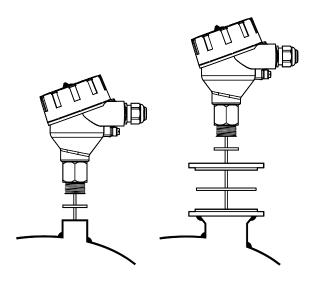


Figure1: mounting

NGM is mounted vertically to the tank via its connection thread, which is screwed directly into a standard threaded tank connection, i.e. weld-in socket, or it can be screwed into a flange, which is then connected to a tank nozzle.

NGM should not be welded directly into the tank. Neither should flanges be welded onto NGM. Welding on the metal parts of NGM will cause serious damage to the sensor.

Do not lift or handle NGM by its probe; this can cause excessive stress on the probe connection. NGM should be handled by the hexagon or the lower section of the housing. Do not screw in NGM by its housing; it should be tightened only via its hexagon (wrench size 32mm).

Tighten the coaxial probe only at its lower hexagon; the upper hexagon of the coaxial probe is not needed for mounting.

The customer has to ensure proper sealing of the sensor connection; based on his process conditions like temperature, pressure and resistance against his process liquids and atmosphere.

G thread connections require a suitable gasket for pressure-tight joints.

The G3/4A connection thread of NGM is supplied with a gasket made of Klingersil C-4400, thickness 2mm. The suggested tightening torque for this thread size, this type of gasket, and a process pressure of max. 40bar is 25Nm (maximum permissible torque: 45 Nm).

For NPT thread connections, pressure-tight joints require a sealant directly on the threads.

#### 6.2 Extended temperature range

NGM with the extended temperature option must be properly included into the tank insulation to prevent excessive temperatures at the sensor housing due to thermal radiation or convection, as well as prevention of condensate formation. However, the insulation layer should not reach higher than the hexagon nut; the cooling fins of the radiator-style temperature extension have to be outside the insulation in order to function properly. If necessary, adjust the height of the mounting socket or nozzle accordingly.



Figure 2: extended temperature option

#### 6.3 PTFE coated single rod probe

PTFE coated probes must be handled carefully to prevent damage to the coating. For detailed instruction show to mount a PTFE coated NGM, please contact your local distributor or KOBOLD directly.



Figure 3: single rod probe, PTFE coated

#### 6.4 Mounting considerations

The probes should be installed so that they are not directly impacted by liquids flowing out of the filling inlet.

They should neither touch nor sway towards other objects inside the tank or the tank/nozzle walls; e.g. by agitator swirls. In applications with very strong fluid movements, which can also cause excessive lateral force on the probe, it is recommended to anchor the probe. The anchoring fixtures are customer supplied.

For further details about mounting NGM or if you would like to anchor the probes, please contact your local distributor or KOBOLD directly.

single rod / wire rope	probe	
coaxial probe	•	
nozzle diameter	_1	>50mm
nozzle height	-	<300mm
clearance to tank wall or other internal objects	-	>100mm
clearance between probe end and tank bottom	-	>2mm
diameter of bypass chamber / stilling well	_2	>25mm

- = no restrictions

<sup>1</sup> enough diameter to fit in the coaxial tube (Ø17,2mm)

<sup>2</sup> enough diameter to fit in the coaxial tube (Ø17,2mm) and enough room around the probe for the liquid to flow in and out of the bypass chamber / stilling well

#### Figure 4: mounting considerations

The single rod probe is suitable for a very wide range of applications in liquids, but the signal has a wider detection radius around the rod. Thus, it is more responsive for measurement signal disturbances which can be easily overcome by observing a few mounting considerations (see Fig.4) and making simple configuration adjustments to the sensor.

Caution! While using single rod or wire rope probes, activating the powerful disturbance signal suppression feature is strongly recommended.

However, those work most efficiently on stationary interference targets like tall and narrow nozzles or close-by objects. In case that non-stationary interference targets close to the single rod probe, like slowly rotating agitator blades, cause problems with the measurement, it is recommended to use the coaxial probe. The single rod probe is also the recommended probe type for mounting NGM into bypass chambers or stilling wells. In this case, plastic centering disks are needed to prevent the probe from contacting the wall. Please contact your local distributor or KOBOLD directly for further details.

					covered Probe	e length			
	6m				12m			20m	
					Tank Ø	j -			
materia I	3m	6m	9m	3m	6m	9m	3m	6m	9m
Wheat	0,7	0,8	0,9	2	2,7	3	4,1	-	-
Corn	0,6	0,7	0,8	1,8	2,4	2,7	3,7	-	-
Rice	0,5	0,7	0,7	1,5	2,1	2,4	2,8	4,5	
Flour	0,3	0,4	0,4	1,1	1,3	1,5	2,4	3,3	3,7
Sugar	0,7	1	1	1,9	2,8	3,4	3,4	-	-
Silica sand	1,1	1,4	1,5	3,2	4,5	-	-	-	-
Cement	1,2	1,5	1,7	3,2	4,7	-	-	-	-
Alumina	0,9	1,1	1,3	2,3	3,5	4,2	4,3	-	-
Phosphate fertilizer	1,8	2,3	2,6	5	-	-	-	-	-
Fly ash	1	1,3	1,4	2,5	3,9	4,7	4,7	-	-
Coal dust	0,7	0,9	1	1,8	2,7	3,3	3,3	-	-
Plastic pellets	0,4	0,5	0,5	1	1,5	1,7	1,9	3,2	4

- = exceeds the max. tensile load of NGM: 5kN.

#### Figure 5: approx. pulling forces [kN]

Above figures are guidelines to estimate the approx. pulling forces from freeflowing solids acting on a suspended 4mm wire rope probe without any anchoring in a metal tank with smooth walls

The wire rope probe is recommended for installations in solids, tall tanks and where limited headroom is available. Its performance characteristics and mounting considerations are similar to the single rod probe.

In addition, please consider the following advice when using NGM in solid applications:

The bulk solid inside the tank or silo can exert a considerable tensile load on the wire rope probe, depending on properties of the bulk solid, tank dimension sand covered probe length (see Fig. 5). This can lead to considerable downwards pulling forces on the tank roof, which has to be able to withstand the max. tensile load of NGM: 5kN

It is recommended that the tank be empty during installation. This ensures that the probe hangs down straight and does not get entangled. After installation also regularly check if the wire rope probe got entangled or unbraided

Some bulk solids easily form build-up on the tank wall or on internal structures. This will interfere with the measurements. Choose a mounting position where the wire rope probe is not in contact with, or close to, such product build-up

For anchoring the wire rope probe in solid applications, please contact your local distributor or KOBOLD directly

The coaxial probe does not have restrictions regarding mounting position, tank connection, and proximity to the tank wall or other objects inside the tank.

The coaxial probe is recommended for installing NGM into a non-metallic tank or open pit. If that is not possible, single rod or wire rope probes can be used when NGM is mounted into at least a DN50 metal flange or screwed into a metal sheet with at least Ø150mm.

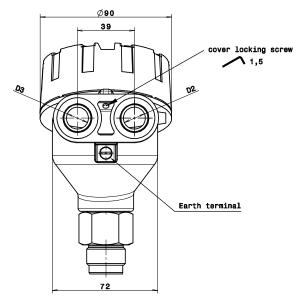


Figure 6: cable entries

#### 6.5 Cable entries and cable glands

The housing has two cable entries and can be ordered with assembled standard screw plugs and cable glands. Nevertheless, the customer has to confirm the suitability of those cable glands for his specific application requirements and cabling; and replace them when necessary.

Both cable entries can be fitted with cable glands or suitable conduit systems. If only one cable gland is fitted, it is recommended to use cable entry D2 (see Fig. 6). Then cable entry D3 has to be closed with a suitable screw plug.

IP68-rated screw plugs and cable glands have to be properly sealed and have to be properly tightened around cable of suitable type and diameter to ensure the IP68 rating of the housing.

Cable entries with metric threads can be sealed by mounting the suitable screw plug or cable gland with matching rubber washers underneath.

Cable entries with NPT threads require a sealant directly on the thread of the screw plug or cable gland.

For M20x1,5 cable entries, NGM comes assembled with:

1 x cable gland M20x1,5, IP68, nylon PA66, for non-armoured cable Ø5...9mm, with EPDM washer, max. tightening torque 6Nm on all hexagons, wrench size 24mm. For protection during shipment it is closed with an EPDM sealing plug which has to be removed for cabling

1 x screw plug, IP68, M20x1,5, nylon PA66, with EPDM washer

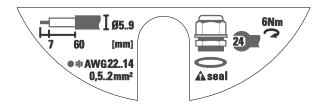
For ½" NPT cable entries, NGM comes assembled with:

2 x screw plug, 1/2" NPT, PE-LD. They are not IP68 and are only for housing protection during shipment. They have to be replaced by the customer

When wiring with shielded or armoured cable, suitable cable glands have to be used. The contact between the metal housing and the shielding of the cable is made by using a suitable EMC-type cable gland. Ground the shielding of the cable only on the sensor side; not on the supply side.

## 7. Electrical Connection

#### 7.1 Wiring



#### Figure 7: lower sticker on the black plastic cartridge

Verify that the power supply for the sensor is switched off.

Establish an equipotential connection (potential equalization) between the external earth terminal of NGM and the closest ground potential terminal of the tank.

Open the housing cover by turning it counter clockwise. It may be necessary to loosen the cover locking screw with an allen key size 1,5mm. The cover has a safety chain to prevent it from falling to the ground after being unscrewed.

The lower sticker on the black plastic cartridge inside the housing gives instructions for the standard M20x1,5 cable gland (Fig. 7). When other cable glands are being used, their details have to be observed instead.

Loosen the cable gland and pull the cable through the cable gland into the housing. Pull it far enough to have a convenient length for stripping and handling the cable.

Install cable with a drip loop outside the housing where the bottom of the loop must be lower than the cable entry of the housing.

Dismantle the cable carefully and strip the wires as indicated on the sticker.

The stripped wire ends are connected to the sensor electronic via the green screw less, cage clamp terminal block. It can accommodate stranded and solid wires 0,5...2mm<sup>2</sup> / AWG 22...14. The usage of cable end sleeves with insulation collar is not recommended.

Simply press an orange lever straight down with a small flat tip screwdriver, insert a stripped wire end into the terminal hole, and release the orange lever; the wire is now connected.

The upper sticker inside the housing illustrates the inputs and outputs if the sensor. Connect all wires accordingly, as indicated in Fig. 8.

Pull the cable back, but make sure its mantle does not retract into the cable gland.

Tighten the cable gland to ensure proper sealing function.

Switch on the power supply for the sensor.

The sensor LED should start blinking green within 6 seconds after connecting the power (during this start-up time the LED is solid green). The blinking green LED indicates that the sensor is in measuring mode and working correctly.

Do not tighten the housing cover yet. Some basic configuration is still to be done...

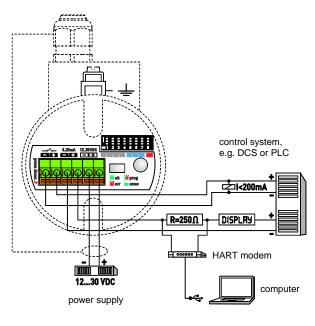
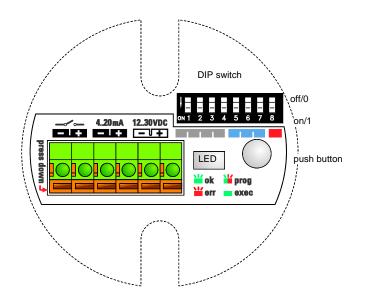


Figure 8: wiring

## 8. Operation / Configuration / Adjustments

#### 8.1 Control Elements



**Figure 9: Control Elements** 

Basic configuration of NGM can be done directly on the device via three control elements: a DIP switch, a single push button and a LED for visual feedback. All settings required to get NGM fully operational can be performed directly on the device; or NGM can be ordered completely pre-configured.

All three control elements are enclosed in the black plastic cartridge inside the housing.

The DIP switch has 8 small white levers. Small numbers from 1 to 8 are printed underneath the levers: they indicate the DIP switch positions and correspond to the ones in Fig.9.

The upper position of a lever is off/0 and the lower position is on/1. On the left side of the DIP switch is also a small indication of the on/1 state.

The off/0 and on/1 states of the DIP switch correspond to the 0/1 indications in Fig.9.

The upper sticker on the black plastic cartridge shows three colour segments close to the DIP switch: red, grey, and blue; they correspond to the coloured rows in Fig.10.

red: indicates DIP switch position 8 which switches between measuring and configuration mode. Only when DIP switch position 8 is on/1, NGM can be configured; configuration mode is indicated by the LED blinking alternately green and red.

When DIP switch position 8 is off/0, NGM is in measuring mode; indicated by the LED blinking green.

It is only possible to enter the configuration mode when DIP switch positions 1 to 7 are off/0 before setting DIP switch position 8 to on/1; otherwise the LED is blinking red to indicate an error

blue: indicates the DIP positions through which groups of functions are selected, e.g. all functions related to the analog current output or the switching output

grey: indicates the DIP positions through which individual functions/configuration settings are selected

When entering into configuration mode, always start from DIP switch position 8 and move towards position 1.

When exiting configuration mode, always set back all the DIP switch positions to 0, starting from position 1 and move towards position 8.

After setting all DIP switch positions to represent the 0/1 sequence of the desired function (as described in Fig.10), the push button has to be pressed to execute the desired function. Execution of the function is indicated by the LED remaining green until the function has been properly executed, in which case the LED returns to blinking alternately green and red.

DIP switch Position						
1 2 3 4 5 6 7 8						
	-					
DIP switch settings	description					
0 0 0 0 0 0 0	measuring mode					
0 0 0 0 0 0 0 1	configuration mode					
function group 1	analog current output					
0 0 0 1	lower range value [4mA]; span 0%					
0 0 1 0	upper range value [20mA]; span 100%					
0 1 0 0 0 1 1	response time 0,5s[default]					
0 1 0 1	response time 2s					
0 1 1 0	response time 5s					
function group 2	switching output					
0 0 1 0	lower threshold					
	upper threshold					
	NC [default]					
0 1 0 1	NO					
function group 3	disturbance signal suppression					
0 0 0 1	perform disturbance signal scan					
0 0 1 0	disturbance signal scan: do not utilize					
0 0 1 1	disturbance signal scan: utilize[default]					
	upper dead band: short [default] <sup>2</sup>					
0 1 0 0	rod probe: 30 mm <sup>3</sup>					
	coaxial probe: 0 mm <sup>3</sup>					
	upper dead band: medium					
0 1 0 1	rod probe: 190 mm <sup>3</sup>					
0 1 1 1	coaxial probe: 160 mm <sup>3</sup>					
	upper dead band: long					
0 1 1 0	rod probe: 390 mm <sup>3</sup>					
	coaxial probe: 360 mm <sup>3</sup>					
	amplitude threshold: low[default]					
	amplitude threshold: medium					
	amplitude threshold: high					
1 1 0 0 1 1 0 1	coaxial probe single rod / wire rope probe					
function group 4	reset					
	reset to delivery configuration					
function group 5	measure probe length					
0 0 0 1 1 0 1 1	measure probe length					

<sup>1</sup> for single rod and wire rope probes with a probe length [L] >5.500mm only the top 5.500mm of the probe get scanned for disturbance signals

<sup>2</sup> for single rod and wire rope probes with a probe length [L] >3.000mm the default setting is upper dead band: long <sup>3</sup> determined at reference point (sealing surface of connection thread, see dimensional drawing)

Function groups 4 and 5 require the push button to be pressed and held for at least 10 seconds for the functions to be executed.

#### Figure 10: DIP switch settings

#### 8.2 Configuration single rod probe or wire rope probe

For most standard applications, executing the three basic configuration steps below issufficient to achieve a fully functional sensor; providing a continuous level measurement through its analog current output.

For further details and advanced configuration of NGM, please contact your local distributor or KOBOLD directly.

#### 8.2.1 perform disturbance signal scan

- NGM has to be mounted in its final position and the tank has to be completely empty in order to perform a disturbance signal scan
- set the DIP switch positions to the 0/1 sequence in Fig. 11on the left; start from position 8 and move towards position 1!
- LED will blink alternately green and red
- press the push button
- LED will remain green for a few seconds while the disturbance signal scan is being performed
- once the scan is completed successfully, the LED will return to blinking alternately green and red

DIP switch Position	
1 2 3 4 5 6 7 8	
DIP switch settings	description
0 0 0 1 0 1 1 1	perform disturbance signal scan

 $\langle -----$ 

#### Figure 11: perform disturbance signal scan

#### 8.2.2 lower range value [4MA]; span 0%

- fill the liquid into the tank up to the level where you want to position the lower range value [4mA]; span 0%.
- It is recommended that the lower range value stays within the measuring range [M]
- change DIP switch position 6 to off/0
- press the push button
- LED will remain green briefly while the lower range value setting is being executed
- once it has been executed successfully, the LED will return to blinking alternately green and red

		DII Po		sw on	vito	h	
1	2	3 4	5	6	7	8	
		DII set		sw gs	vito	h	description
0	0	0 1	0	0	1	1	lower range value [4mA]; span 0%

Figure 12: lower range value [4mA]; span 0%

#### 8.2.3 upper range value [20MA]; span 100%

- raise the liquid inside the tank up to the level where you want to position the upper range value [20mA]; span 100%.
- It is recommended that the upper range value stays within the measuring range [M]
- change DIP switch position 3 to on/1
- change DIP switch position 4 to off/0
- press the push button
- LED will remain green briefly while the upper range value setting is being executed
- once it has been executed successfully, the LED will return to blinking alternately green and red
- set all the DIP switch positions to 0 as indicated in Fig.14on the left; start from position 1 and move towards position 8!
- the LED will change to blinking green

DIP switch Pos	sition
1 2 3 4 5 6 7	8
DIP switch setti	tings description
0 0 1 0 0 0 1	1 upper range value [20mA]; span 100%

#### Figure 13: upper range value [20mA]; span 100%

Tighten the housing cover properly by turning it clockwise; make sure the cover safety chain does not tangle up. If desired, tighten the cover locking screw with an allen key size 1,5mm.

DIP switch Position	
1 2 3 4 5 6 7 8	
DIP switch settings	description
0 0 0 0 0 0 0 0	measuring mode
_	

Figure 14: measuring mode

#### 8.3 Configuration Coaxial probe

The coaxial probe has a very robust and reliable measurement performance in almost any application without further configuration. For basic configuration only the range values for the analogue current output have to be set.

For further details and advanced configuration of NGM, please contact your local distributor or KOBOLD directly.

#### 8.3.1 lower range value [4MA]; span 0%

- set the DIP switch positions to the 0/1 sequence in Fig.15on the left; start from position 8 and move towards position 1!
- lower the liquid inside the tank down to the level where you want to position the lower range value [4mA]; span 0%.
   It is recommended that the lower range value stays within the measuring range [M]
- press the push button
- LED will remain green briefly while the lower range value setting is being executed
- once it has been executed successfully, the LED will return to blinking alternately green and red

DIP switch Position	
1 2 3 4 5 6 7 8	
DIP switch settings	description
0 0 0 1 0 0 1 1	lower range value [4mA]; span 0%

#### Figure 15: lower range value [4mA]; span 0%

#### 8.3.2 upper range value [20MA]; span 100%

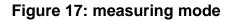
- raise the liquid inside the tank up to the level where you want to position the upper range value [20mA]; span 100%.
   It is recommended that the upper range value stays within the measuring range [M]
- change DIP switch position 3 to on/1
- change DIP switch position 4 to off/0.
- press the push button
- LED will remain green briefly while the upper range value setting is being executed
- once it has been executed successfully, the LED will return to blinking alternately green and red
- set all the DIP switch positions to 0 as indicated in Fig.17on the left; start from position 1 and move towards position 8!
- the LED will change to blinking green

DIP switch Position	
1 2 3 4 5 6 7 8	
DIP switch settings	description
0 0 1 0 0 0 1 1	upper range value [20mA]; span 100%

#### Figure 16: upper range value [20mA]; span 100%

Tighten the housing cover properly by turning it clockwise; make sure the cover safety chain does not tangle up. If desired, tighten the cover locking screw with an allen key size 1,5mm.

DIP switch Position	
1 2 3 4 5 6 7 8	
DIP switch settings	description
0 0 0 0 0 0 0 0	measuring mode



#### 8.4 probe length and measuring range

The reference point for definition of the probe length [L] is always the shoulder of the connection thread. The probe length [L] is an important mechanical dimension which is needed to make sure the probe physically fits into the tank at the anticipated mounting location; it is not equal to the actual measuring range [M] of the sensor!

TDR level sensors have small inactive areas at top [I1] and bottom [I2] of the probe. Those are due to the presence of unavoidable signal disturbances at both ends of the probe. In these inactive areas the measurements are non-linear or have reduced accuracy. Therefore, it is not recommended to actually measure level within those inactive areas. Their length depends on the probe type and the reflectivity (i.e. dielectric constant) of the liquid to be measured.

The measuring range [M] of NGM extends between the top and bottom inactive areas of the probe; this is the area in which NGM will have the specified measurement performance. It is recommended that the maximum and minimum liquid levels to be measured in the tank are actually within the measuring range [M] of the sensor. The span between the lower range value [4mA] and the upper range value [20mA] of the analog current output is equal to 0...100% of your continuous level measurement reading. It is recommended that the span between those two range values stays within the measuring range [M].

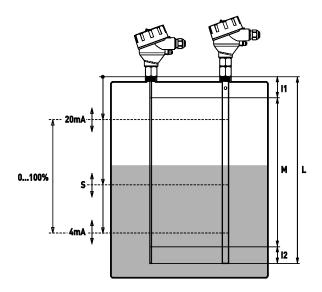


Figure 18: probe length and measuring range

#### 8.5 disturbance signal scan

The disturbance signal scan is a powerful disturbance signal suppression feature of NGM. The sensorscans its entire probe length for any disturbance signals in the application that could potentially be misinterpreted as level readings, memorizes and suppresses them during operation; that way NGM only recognizes the actual level signals caused by the liquid to be measured.

The disturbance signal scan is intended for the single rod probe, since its signal has a wider detection radius around the rod, making it more responsive for measurement signal disturbances.

The disturbance signal scan works most efficiently on stationary interference targets like tall and narrow nozzles or close-by objects. Thus, NGM has to be mounted in its final position and the tank has to be completely empty in order to perform a disturbance signal scan; that will ensure a reliable identification of the actual disturbance signals only. In case that non-stationary interference targets close to the single rod probe, like slowly rotating agitator blades or streams of liquid being filled into the tank, cause problems with the measurement, it is recommended to use the coaxial probe.

Performing a disturbance signal scan is the prerequisite for utilizing this feature of NGM.

#### 8.6 Guide to communicating from a PC to a NGM probe

#### (Configuration of device specific parameters)

#### 8.6.1 Communication with NGM





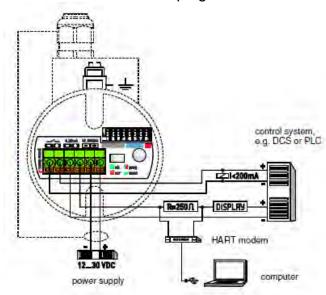
#### **Requirements:**

- PC with Microsoft Office
- Excel file NGM Configuration Tool LA (HART) V172.xls (for serial no. below 335490 (non-Ex) and serial no. below E5048 (Ex))
- Excel file NGM Configuration Tool LA (HART) V175.xls (from serial no. 335490 (non-Ex) and serial no. E5048 (Ex))
   This file enables the customer to configure measuring parameters, analogue output, measuring length and probe/rope shortening/extending.
- HART Modem with USB connector
- Communication resistor approx. 250 Ohm
- NGM level probe
- Power supply 24VDC

#### Connection:

- Connect the NGM probe to the power supply
- The LED at the NGM must start to flash green
- Connect the resistor between + and of the active 4...20mA output.
- Connect in parallel the HART modem to the resistor and plug in the USB connector to the PC

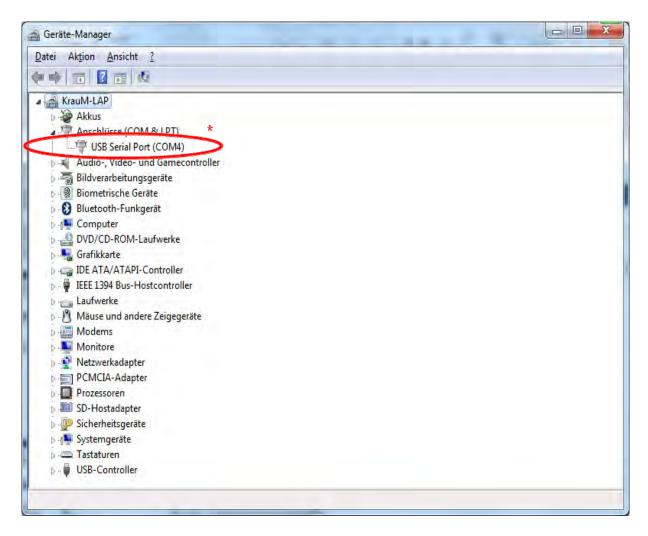




#### 8.6.2 Connection of a NGM Probe to a PC

 Check the COM port assignment of the PC to the USB HART modem with the Device Manager

http://www.computerhope.com/issues/ch000833.htm



\* In this case COM port 4 has been assigned to the HART modem

#### 8.6.3 First Steps with the Excel Tool

- 1. Open the Excel file
- 2. Prerequisite: worksheet is active and the macros are running (*Hint: A restart of the Excel file might help to activate the Macros.*)
- 3. HOME
- 4. Enter the assigned COM port indicated at the device manager.

! Sicherh	Start Einfügen Se	ve Inhalte wurden deaktiviert.	Klicken Sie hier, um	weitere Details a	nzuzeigen.	Inhalt aktivier	n						-
B3	2 • (*	f.x.								_			_
A	В	C D E	F	G	Н	Í.	J	K	L	М	N	0	
1													
2		HOME											
2 3 4 5 6 7 8 9 10		0.5.1.1.1.1.1											
4		Configuration at factor	Y										
5		Configuration for local	accombly										
7		Configuration for focal	assembly										
8		Basic and advanced c	onfiguration and si	onal analysis									
9			3	3									
		PCB testing											
11													
12		Data											
13													
14 15	Manda	4 70											
15	Version	1,70	6-										
17	COM port: 19	7	B Device I	lanager		_ 0							
18	Unit: mm / inch	mm	Eile Action	<u>V</u> iew <u>H</u> elp									
19			~ > B	661		-							
20						~ 20 420							
17 18 19 20 21 22 23 24 25 26 27 28 29 30				/OS10									
22			11 10 B	itteries Jetooth Devices									
23			E Q G										
24			+ 🕹 D				-						
25			🖽 😼 Di	splay adapters									
20				uman Interface De									
28				E ATA/ATAPI cont	rollers								
29				aging devices									
30				ryboards ce and other point	ing devices								
31				anitors	ang devices								
32				etwork adapters									
33			n Go	the (COM & LDT)									
31 32 33 34 35			- 2	Bluetooth Comm	unications Port	(COM3)							
				Bluetooth Comm MicroLink HART I ocessors	Protocol Modem	(COM4)							
36		s / Device with probe ca	1 + 52 Pi	ocessors			1						

For the usage of the Excel tool, a click on the necessary cell activates the communication and/or parameters can be changed. For re-sending the command, click on a free cell elsewhere and move back to the required cell. The OK status has to return for a successful communication.

#### **BASIC CONFIGURATION**

Establishing a HART communication:

• Serial number obtainable by clicking on the light blue SEND button J2 in step 1 "get serial number"

Macros are running

• OK status (H2) disappears and reappears after serial number read out and shown in G2

A1 A	- <u>6</u> B C	D	E	F	G	Ĥ	T	J	-
-			Leste cetter	man only a		status	L and L		
		unit of variable		max. value	variable	and the second second	send		
	1 get serial number	1	0		1000	ok	SEND		
	2 set lower range value [4mA]	mm	-1000	L+1000	2990	0K	SEND		
	3 set upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
	4 get lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
	5 get upper range value [20mA]	mm	-1000	L + 1000	50	ok	SEND		
	6 set response time	0.15	2	100	2	ok	SEND		
	7 get response time	0.15	2	100	2	ok	SEND		
	8 set switching output mode	1	0 = nc	1 = no	0	ok	SEND		
	9 get switching output mode	1	0 ≠ nc	1 = na	0	ok	SEND		
	10 set lower threshold switching output	mm	0	L	600	ok	SEND		
	11 get lower threshold switching output	mm	0	L	500	ok	SEND		
	12 set upper threshold switching output	mm	0	L	500	ok	SEND		
	13 get upper threshold switching output	mm	0	L	600	ok	SEND		
	14 set upper dead band	mm	30	1400	61	ok	SEND		
	15 get upper dead band	mm	30	1400	61	ok	SEND		
	16 set amplitude threshold	ADC values	10	10000	200	ok	SEND		
	17 get amplitude threshold	ADC values	10	10000	200	ok	SEND		
	18 set disturbance signal scan status (T = top, T&B = top + bottom)	/	00 = OFF	01=T: 10=T&B	01	0K	SEND		
	19 get disturbance signal scan status	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	20 perform disturbance signal scan	1	1	- 1	1-1-	ok	SEND		
	21 set probe type	1		1 = single probe	1	ok	SEND		
	22 get probe type	I		1 = single probe	1	0k	SEND		
	23 set probe length [L]	mm	0	20000	3000	ok	SEND		
	24 get probe length [L]	mm	0	20000	3000	0K	SEND		
	25 set delivery configuration	1	1	1	1	ok	SEND		
	26 reset to delivery configuration	1	1	1	1	ok	SEND		
	27 get level reading	mm	0	20000,0	1999,5	DK.	SEND		
	28 get software revision	1	1	32bit	136	ok	SEND		
	29 get device status	1	1	1	011 0100 0000	ok	SEND		
	30 aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	1	DK.	SEND		
	31 set signal range from x1 to x2	x1 [mm]	-1000,0	20000	-1000	ok	SEND		
		x2 [mm]	0	20000	4000	ali	June		
				-	required user				

If OK status does not reappear, check the connection or the COM port settings

Now the HART communication is established and the modification of devicespecific parameter as well as the read-out of the echo curve can be performed.

#### 8.6.4 Upper / Lower Range Value

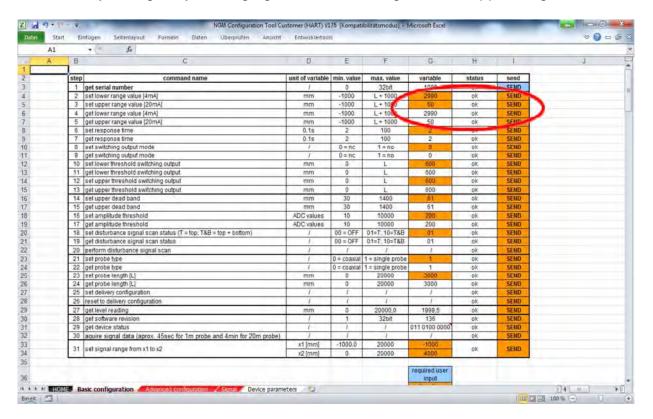
#### **BASIC CONFIGURATION**

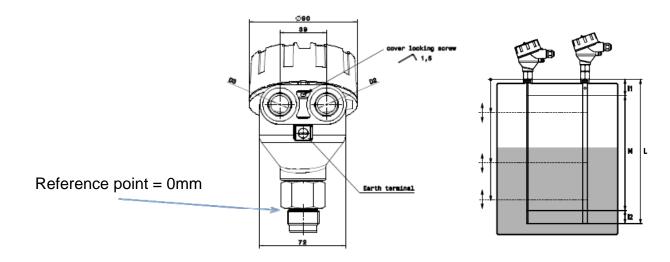
• Read out actual 4...20mA settings by clicking on I6 and I7

With the command "get lower / upper range value", the actual 4...20mA values in mm are shown after the OK status disappeared and is visible again.

• Change actual 4...20mA settings by changing the values in G4 and G5 and clicking on I4 and I5 "set lower / upper range value"

• Verify changes by clicking again on I6 and I7 "get lower / upper range value"





#### 8.6.5 Response Time

#### **BASIC CONFIGURATION**

• Read out actual response time, by clicking on I9.

Field G9 is showing the actual response time multiplied with 0,1ms.

• Change actual response time within a range of 2 ... 100 (0,2 ... 10sec) in field G8 and clicking on I8 "set response time".

Use high response times for storage tanks with slow level movements. Use low response times for buffer and process tanks.

A1		• - fe								
A	В	C	D	E	F	G	н	1	J	
	step	command name	unit of variable	min. value	max. value	variable	status	send		
		get serial number	1	0	32bit	1000	ok	SEND		
-		set lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
		set upper range value [20mA]	mm	-1000	L+1000	50	pk	SEND		
		get lower range value (4mA)	mm	-1000	L+1000	2990	ok	SEND		
-		get upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
		set response time	0.15	2	100		ok	SERV		
-		get response time	0.15	2	100	2	ok	SEND		
		set switching output mode	1	0 = nc	1 = no	8	-06	SEND		
-		get switching output mode	1	0=00	1=00	0	ok	SEND		
_		set lower threshold switching output	mm	0	L	600	ok	SEND		
		get lower threshold switching output	mm	0	E E	600	ok	SEND		
-		set upper threshold switching output	mm	0	L	600	ok	SEND		
-		get upper threshold switching output	mm	0	L	600	ok	SEND		
		set upper dead band	mm	30	1400	61	ok	SEND		
_		get upper dead band	mm	30	1400	61	ok	SEND		
		set amplitude threshold	ADC values	10	10000	200	ok.	SEND		
		get amplitude threshold	ADC values	10	10000	200	ok	SEND		
		set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
		get disturbance signal scan status	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
		perform disturbance signal scan	1	1	1	1	ok	SEND		
		sat probe type	1	0 = coaxial	1 = single probe	1	ok	SEND		
		get probe type	1		1 = single probé	1	ok	SENID		
		set probe length [L]	mm	0	20000	3000	ok	SEND		
		get probe length [L]	mm	0	20000	3000	OK	SEND		
		set delivery configuration	1	1	1	1	ok	SEND		
		reset to delivery configuration	1	1	1	1	ok	SEND		
	_	get level reading	mm	D	20000.0	1999.5	ok	SEND		
		get software revision	1	1	32bit	136	ok	SEND		
-		get device status	1	1		011 0100 0000	ok	SEND		
		aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	1	ok	SEND		
-	11.0		xt [mm]	-1000.0	20000	-1000				
	31	set signal range from x1 to x2	x2 (mm)	0	20000	4000	ok	SEND		
- 1	-		- Se finnit	1 0	20000	4000				
						required user				



Verify changes by clicking again on I9 "get response time"

#### 8.6.6 Switching Output Mode

#### **BASIC CONFIGURATION**

• Read out actual switching output mode by clicking on I11

Field G11 is showing the actual switching output mode.

-0 = nc = normally closed

-1 = no = normally open

Once the probe is powered, the switch output can be open or closed. The standard switch output mode is set to "normally closed", as it would open at a power failure for highest safety.

• Change actual switching output mode 0 or 1 in field G10 and clicking on I10 "set switching output mode"

A1	• (* fe								
A	BC	D	E	F	G	н	1	J	
_	step command name	unit of variable	min, value	max. value	variable	status	send		
	1 get serial number	1	0	32bit	1000	ok	SEND		
	2 set lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
	3 set upper range value [20mA]	mm	-1000	L + 1000	50	ok	SEND		
	4 get lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
	5 get upper range value [20mA]	mm	-1000	L + 1000	50	ok	SEND		
	6 set response time	0.1s	2	100	2	ok	SEND		
	7 get response time	0.1s	2	100	2	ok	SEND		
	8 set switching output mode	1	0 = n¢	1=00	0	ok	SEND		
	9 get switching output mode	1	0=00	1=no		OK.	JERS		
	10 set lower threshold switching output.	mm	0	LC	600	ök	SEND D		
	11 get lower threshold switching output	mm	0	L	800		SENO		
	12 set upper threshold switching output	mm	0	Ĩ.	600	ok	SEND		
	13 get upper threshold switching output	mm	0	L	600	ok	SEND		
	14 set upper dead band	mm	30	1400	61	ak	SEND		
	15 get upper dead band	mm	30	1400	61	ok	SEND		
	16 set amplitude threshold	ADC values	10	10000	200	ok	SEND		
	17 get amplitude threshold	ADC values	10	10000	200	ok	SEND		
	18 set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	19 get disturbance signal scan status	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	20 perform disturbance signal scan	1	1	1	1	ok	SEND		
	21 set probe type	1	0 = coasial	1 = single probe	1	ok	SEND		
	22 get probe type	1		1 = single probe	1	ok	SEND		
	23  set probe length [L]	mm	0	20000	3000	ÓK.	SEND		
	24 get probe length [L]	mm	0	20000	3000	ok	SEND		
	25 set delivery configuration	1	1	1	1	ok	SEND		
	26 reset to delivery configuration	1	1	1	1	ok	SEND		
	27 get level reading	mm	0	20000,0	1999.5	ok	SEND		
	28 get software revision	1	1	32bit	136	ok	SEND		
	29 get device status	1	i	1	011 0100 0000	ok	SEND		
	30 aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	1	ok	SEND		
		xt [mm]	-1000.0	20000	-1000				
	31 set signal range from x1 to x2	12 [mm]	0	20000	4000	ok	SEND		
		- found		20300					
					required user				

Verify changes by clicking again on I11 "get switching output mode"

#### 8.6.7 Threshold switching output

#### **BASIC CONFIGURATION**

• Read out actual lower / upper threshold switching output, by clicking on I13 and I15.

Field G13/15 indicates the actual lower / upper switching threshold.

With the help of the thresholds, a hysteresis can be programmed to avoid output switching at turbulent levels. First, the upper threshold must be passed to activate the output then the lower threshold for deactivation of the output.

• Change actual lower / upper threshold in field G12 / G14 and click on I12 / I14 "set lower / upper threshold switching output mode".

Step         command name         unit of variable         max. value         variable         status         send           1         get serial number         /         0         32bit         1000         ok         SEND           2         set lower range value [2mA]         mm         -1000         L=1000         2998         ok         SEND           3         set upper range value [2mA]         mm         -1000         L=1000         2990         ok         SEND           5         get lower range value [2mA]         mm         -1000         L=1000         2990         ok         SEND           6         set response time         0.15         2         100         2         ok         SEND           7         get response time         0.15         2         100         2         ok         SEND           8         set westhing output mode         /         0 = nc         1 = no         0         ok         SEND           11         get swesthing output mode         /         0 = nc         1 = no         0         ok         SEND           12         set destriction output mode         /         0 = nc         1 = no         0         ok         <	AI	• (* <i>f</i> e								_		
1         pet serial number         /         0         22bit         1000         L + 1000         0 k         SEID           2         set lower range value [20mA]         mm         -1000         L + 1000         2990         0.k         SEID           3         set lower range value [20mA]         mm         -1000         L + 1000         2990         0.k         SEID           5         pet lower range value [20mA]         mm         -1000         L + 1000         2900         0.k         SEID           6         set response time         0.1s         2         100         2         0.k         SEID           7         det response time         0.1s         2         100         2         0.k         SEID           8         set response time         0.1s         2         100         2         0.k         SEID           9         pet smitching output mode         /         0 = nc         1 = no         0         0.k         SEID           10         set lower threshold switching output         mm         0         L         600         0.k         SEID           11         pet lower threshold switching output         mm         0         L	A	BC	D	E	F	G	Н	1	J			
1         0et serial number         I         0         32bit         1000         bit         SEID           2         set lower range value [20mA]         mm         -1000         L + 1000         2990         ok         SEID           3         set lower range value [20mA]         mm         -1000         L + 1000         2990         ok         SEID           5         get lower range value [20mA]         mm         -1000         L + 1000         2990         ok         SEID           6         set response time         0.1s         2         100         2         ok         SEID           7         of response time         0.1s         2         100         2         ok         SEID           9         pet switching output mode         /         0 = nc         1 = no         0         ok         SEID           10         set lower threshold switching output         mm         0         L         600         ok         SEID           11         get lower threshold switching output         mm         0         L         600         ok         SEID           12         set upper threshold switching output         mm         0         L         600	_	sten command name	unit of variable	min value	max value	variable	status	send				
2       set lower range value [20mA]       mm       -1000       L + 1000       2990       ok       SERD         3       set upper range value [20mA]       mm       -1000       L + 1000       2990       ok       SERD         4       get upper range value [20mA]       mm       -1000       L + 1000       2990       ok       SERD         5       get upper range value [20mA]       mm       -1000       L + 1000       50       ok       SERD         6       set specifies lime       0.15       2       100       2       ok       SERD         7       get response lime       0.15       2       100       2       ok       SERD         9       get switching output mode       /       0 = nc       1 = no       0       ok       SERD         10       set lower threshold switching output       mm       0       L       600       ok       SERD         11       get upper range value [2mA]       mm       0       L       600       ok       SERD         12       set upper range value get much switching output       mm       0       L       600       ok       SERD         13       set upper range value get much switching outp												
3         Set upper range value [20mA]         mm         -1000         L + 1000         50         o.k         SER0           4         get lower range value [20mA]         mm         -1000         L + 1000         2990         o.k         SER0           5         get upper range value [20mA]         mm         -1000         L + 1000         20         o.k         SER0           6         set response time         0.15         2         100         2         o.k         SER0           9         get switching output mode         /         0 = nc         1 = no         0         o.k         SER0           10         set ower threshold switching output         mm         0         L         6000         o.k         SER0           11         get upper threshold switching output         mm         0         L         600         o.k         SER0           12         get upper dead band         mm         0         L         600         o.k         SER0           13         get upper dead band         mm         30         1400         61         o.k         SER0           14         set upper dead band         mm         30         1400         61 <t< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></t<>												
4       get lower range value [4mA]       mm       -1000       L + 1000       2990       ok       SEN0         5       get upper range value [20mA]       mm       -1000       L + 1000       50       ok       SEN0         6       set response time       0.15       2       100       2       ok       SEN0         7       get response time       0.15       2       100       2       ok       SEN0         8       pet switching output mode       /       0 = nc       1 = n0       0       ok       SEN0         9       get switching output mode       /       0 = nc       1 = n0       0       ok       SEN0         10       set lower threshold switching output       mm       0       L       600       ok       SEN0         11       get upper threshold switching output       mm       0       L       600       ok       SEN0         12       set upper threshold switching output       mm       0       L       600       ok       SEN0         13       get upper threshold switching output       mm       0       L       600       ok       SEN0         15       set upper thead band       mm       30 <td></td>												
5         get upper range value [20mA]         mm         -1000         L + 1000         50         ok         SEND           6         set response time         0.15         2         100         2         ok         SEND           8         set switching output mode         /         0 = nc         1 = no         0         ok         SEND           9         get switching output mode         /         0 = nc         1 = no         0         ok         SEND           10         set switching output mode         /         0 = nc         1 = no         0         ok         SEND           11         get lower threshold switching output         mm         0         L         800         ok         SEND           12         set upper threshold switching output         mm         0         L         800         ok         SEND           13         get upper threshold switching output         mm         30         1400         61         ok         SEND           15         get upper teshold switching output         mm         30         1400         61         ok         SEND           16         set amplitude threshold         ADC values         10         100000			-			-		the second se				
6         setresponse time         0.1s         2         100         2         0k         SEND           7         get response time         0.1s         2         100         2         0k         SEND           8         set switching output mode         /         0 = nc         1 = n0         0         0k         SEND           9         get switching output mode         /         0 = nc         1 = n0         0         0k         SEND           10         set lower threshold switching output         mm         0         L         600         0k         SEND           11         get upper threshold switching output         mm         0         L         600         0k         SEND           12         set upper threshold switching output         mm         0         L         600         0k         SEND           13         get upper threshold switching output         mm         0         L         600         0k         SEND           14         set upper threshold         mm         30         1400         61         0k         SEND           15         set upper threshold         ADC values         10         100000         200         0k												
7       get response time       0.1s       2       100       2       0k       SEND         8       jed owliching output mode       /       0 = nc       1 = no       0       0k       SEND         10       set lower threshold switching output       mm       0       L       600       0k       SEND         11       get lower threshold switching output       mm       0       L       600       0k       SEND         12       set upper threshold switching output       mm       0       L       600       0k       SEND         13       get upper threshold switching output       mm       0       L       600       0k       SEND         14       set upper threshold switching output       mm       0       L       600       0k       SEND         15       get upper dead band       mm       30       1400       61       0k       SEND         16       set amplitude threshold       ADC values       10       100000       200       0k       SEND         19       get disturbance signal scan status (T = top, T&B = top + bottom)       I       00 = OFF       01 = TOR-TBB       01       0k       SEND         20       perform d												
8         set switching output mode         /         0 = nc         1 = no         0         0k         SEND           9         get switching output mode         /         0 = nc         1 = no         0         0k         SEND           10         set lower threshold switching output         mm         0         L         600         0k         SEND           11         get lower threshold switching output         mm         0         L         600         0k         SEND           12         set upper threshold switching output         mm         0         L         600         0k         SEND           13         get upper threshold switching output         mm         0         L         600         0k         SEND           14         set upper dead band         mm         30         1400         61         0k         SEND           15         get upper dead band         mm         30         1400         61         0k         SEND           16         set amplitude threshold         ADC values         10         100000         200         0k         SEND           19         set disturbance signal scan status         1         00 = OFF         01 = 0.tr												
9       get switching output mode       /       0 = nc       1 = n6       0       0k       SEN0         10       set lower threshold switching output       mm       0       L       800       0k       SEN0         11       get lower threshold switching output       mm       0       L       600       0k       SEN0         12       set upper threshold switching output       mm       0       L       600       0k       SEN0         13       get upper threshold switching output       mm       0       L       600       0k       SEN0         14       set upper dead band       mm       30       1400       61       0k       SEN0         16       set amplitude threshold       ADC values       10       10000       200       0k       SEN0         19       get disturbance signal scan status       (T = top, T&B = top = bottom)       1       00 = 0FF       01 = 0kk       SEN0         20       perform disturbance signal scan       1       0       0 = Cotatal 1 = single probe       1       0k       SEN0         21       set roob length [L]       mm       0       20000       3000       0k       SEN0         23       set probe												
10         set lower threshold switching output         mm         0         L         600         ok         SEND           11         get upper threshold switching output         mm         0         L         600         ok         SEND           12         set upper threshold switching output         mm         0         L         600         ok         SEND           13         get upper dead band         mm         0         L         600         ok         SEND           14         set upper threshold switching output         mm         30         1400         61         ok         SEND           15         get upper dead band         mm         30         1400         61         ok         SEND           16         set astronal threshold         ADC values         10         10000         200         ok         SEND           18         set disturbance signal scan status (T = top; T&B = top = bottom)         1         00 = OFF         01=T; 10=T&B         01         ok         SEND           20         petform disturbance signal scan status         1         00 = OFF         01=T; 10=T&B         01         ok         SEND           21         set storobe type         1												
11         get lower threshold switching output         mm         0         L         600         ok         SEND           12         set upper Threshold switching output         mm         0         L         800         ok         SEND           13         get upper Threshold switching output         mm         0         L         800         ok         SEND           14         set upper Threshold switching output         mm         0         L         600         ok         SEND           14         set upper dead band         mm         30         1400         61         ok         SEND           16         set amplitude threshold         ADC values         10         10000         200         ok         SEND           18         set disturbance signal scan status (T = top, T&B = top + bottom)         I         00 = OFF         01=17, 10=T&B         01         ok         SEND           20         perform disturbance signal scan         I			-				2.0					
12     set upper threshold switching output     mm     0     L     600     ok     SEND       13     get upper threshold switching output     mm     0     L     600     ok     SEND       14     get upper dead band     mm     30     1400     61     ok     SEND       15     get upper dead band     mm     30     1400     61     ok     SEND       16     sat amplitude threshold     ADC values     10     10000     200     ok     SEND       17     get amplitude threshold     ADC values     10     10000     200     ok     SEND       19     get disturbance signal scan status (T = top; T&B = top = bottom)     I     00 = OFF     01 = T, 10=T&B     01     ok     SEND       20     perform disturbance signal scan     I     I     I     I     ok     SEND       21     set robe type     I     0 = coaxial 1 = single probe     1     ok     SEND       22     get robe type     I     0 = coaxial 1 = single probe     1     ok     SEND       23     set robe tength [L]     mm     0     20000     3000     ok     SEND       24     get robe length [L]     mm     0     20000     30												
13         get upper threshold switching output         mm         0         L         600         ok         SEND           14         set upper dead band         mm         30         1400         61         ok         SEND           15         get upper dead band         mm         30         1400         61         ok         SEND           16         sat amplitude threshold         ADC values         10         10000         200         ok         SEND           17         get amplitude threshold         ADC values         10         10000         200         ok         SEND           18         set disturbance signal scan status (T = top, T&B = top = bottom)         1         00 = 0FF         01=0T; 10=T&B         01         ok         SEND           20         pefform disturbance signal scan status         1         00 = 0FF         01=0T; 10=T&B         01         ok         SEND           21         set probe type         1         0         coal         1 = single probe         1         ok         SEND           22         pet probe trops (Liptic)         mm         0         20000         3000         ok         SEND           23         set probe trops (Liptic)												
14       set upper dead band       mm       30       1400       61       ok       SEND         15       get upper dead band       mm       30       1400       61       ok       SEND         16       get amplikude threshold       ADC values       10       10000       200       ok       SEND         17       get amplikude threshold       ADC values       10       10000       200       ok       SEND         18       set disturbance signal scan status (T = top. T&B = top + boltom)       I       D0 = OFF       D1=T; 10=T&B       01       ok       SEND         19       get disturbance signal scan status       I       00 = OFF       D1=T; 10=T&B       01       ok       SEND         20       perform disturbance signal scan       IIII       IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII				-								
15       get upper dead band       mm       30       1400       61       Dix       SERD         16       set amplitude threshold       ADC values       10       10000       200       Dix       SERD         17       get amplitude threshold       ADC values       10       10000       200       Dix       SERD         18       set disturbance signal scan status (T = top. T&B = top + boltom)       1       D0 = OFF       D1=T; 10=T&B       D1       Dix       SERD         20       petrom disturbance signal scan status       1       00 = OFF       D1=T; 10=T&B       D1       Dix       SERD         20       petrom disturbance signal scan status       1       00 = OFF       D1=T; 10=T&B       D1       Dix       SERD         21       set probe type       1       01 = coaxial       1 = single probe       1       Dix       SERD         23       set probe length [L]       mm       0       20000       3000       Dix       SERD         24       get probe length [L]       mm       0       20000       3000       Dix       SERD         25       set devery configuration       1       1       1       Dix       SERD         26							100 C	and the second division of the second divisio				
16         aet amplitude threshold         ADC values         10         10000         200         0K         SEND           17         get amplitude threshold         ADC values         10         10000         200         0K         SEND           18         set disturbance signal scan status (T = top, T&B = top = bottom)         1         00 = OFF         01 = 0.7         01 = 0.4K         SEND           20         perform disturbance signal scan status         1         00 = OFF         01 = 1.7         10 = 0.4K         SEND           20         perform disturbance signal scan status         1         01 = 0.4K         SEND         02         02         04 & SEND           21         set probe type         1         1         1         0k         SEND           22         per toot type         1         0 = coaxial 1 = single probe         1         0k         SEND           23         set probe tright [L]         mm         0         20000         3000         0k         SEND           24         get probe tength [L]         mm         0         20000         3000         0k         SEND           25         set probe tingth [L]         mm         0         200000         3000												
17       get amplitude threshold       ADC values       10       10000       200       0K       SEND         18       set disturbance signal scan status       1       00 = OFF       01=7, 10=78B       02       0K       SEND         20       perform disturbance signal scan status       1       00 = OFF       01=7, 10=78B       01       0k       SEND         20       perform disturbance signal scan       1       1       1       1       0k       SEND         21       set probe type       1       0 = coaxial       1 = single probe       1       0k       SEND         22       get probe type       1       0 = coaxial       1 = single probe       1       0k       SEND         23       set probe tength [L]       mm       0       20000       3000       0k       SEND         24       get probe tength [L]       mm       0       20000       3000       0k       SEND         25       set delivery configuration       1       1       1       0k       SEND         25       set delivery configuration       1       1       1       0k       SEND         26       resetsion       1       1       1 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>												
18       set disturbance signal scan status (T = top, T&B = top + bottom)       1       00 = OFF       01=7, 10=T&B       01       0k       SEND         19       get disturbance signal scan status       1       00 = OFF       01=7, 10=T&B       01       0k       SEND         20       perform disturbance signal scan status       1       00 = OFF       01=7, 10=T&B       01       0k       SEND         21       set proce signal scan status       1       0       0 = coaxial       1 = single probe       1       0k       SEND         22       get probe type       1       0 = coaxial       1 = single probe       1       0k       SEND         23       set probe length [L]       mm       0       20000       3000       0k       SEND         24       get probe length [L]       mm       0       20000       3000       0k       SEND         25       set delivery configuration       1       1       1       0k       SEND         26       reset to delivery configuration       1       1       1       0k       SEND         26       get software revision       1       1       1       0k       SEND         29       get device status												
19       get disturbance signal scan status       /       00 = 0FF       01=T; 10=T&B       01       ok       SEND         20       perform disturbance signal scan       /       /       /       /       /       /       /       0         21       set probe type       /       0 = coaxial       1 = single probe       1       ok       SEND         22       get probe type       /       0 = coaxial       1 = single probe       1       ok       SEND         23       set probe trope       /       0 = coaxial       1 = single probe       1       ok       SEND         24       get probe trope flype       //       0 = coaxial       1 = single probe       1       ok       SEND         23       set probe tropf fly1       mm       0       20000       3000       ok       SEND         24       get probe tropf fly1       mm       0       20000       3000       ok       SEND         25       set set to delivery configuration       //       //       //       //       ok       SEND         26       reset to delivery configuration       //       //       //       //       ok       SEND         28			1									
20         perform disturbance signal scan         / <th <="" th=""> <th <="" th="">         /         <th< td=""><td></td><td></td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th<></th></th>	<th <="" th="">         /         <th< td=""><td></td><td></td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th<></th>	/ <th< td=""><td></td><td></td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th<>			1							
21       set probe type       /       0 = coaxial       1 = single probe       1       ok       SEND         22       get probe type       /       0 = coaxial       1 = single probe       1       ok       SEND         23       set probe length [L]       mm       0       20000       3000       ok       SEND         24       get probe length [L]       mm       0       20000       3000       ok       SEND         25       set devicey configuration       /       /       /       /       ok       SEND         25       set devicey configuration       /       /       /       /       ok       SEND         26       resetto delivery configuration       /       /       /       /       ok       SEND         27       get software revision       /       /       /       /       /       ok       SEND         28       get software revision       /       /       /       /       /       0       SEND         29       get device status       /       /       /       1       0110100.0000       ok       SEND         30       aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe) <td></td> <td></td> <td>1</td> <td>1</td> <td>1</td> <td></td> <td></td> <td></td> <td></td> <td></td>			1	1	1							
22         get probe type         /         0 = coaxial         1 = single probe         1         0k         SER0           23         set probe tength [L]         mm         0         20000         3000         ok         SER0           24         get probe tength [L]         mm         0         20000         3000         ok         SER0           25         set probe tength [L]         mm         0         20000         3000         ok         SER0           26         reset to delivery configuration         /         /         /         /         0k         SER0           27         get eval reading         mm         0         20000,0         1993,5         ok         SER0           28         get software revision         /         1         32bit         136         ok         SER0           29         get device status         /         /         /         /         0         1010 100 00000         ok         SER0           30         aguire signal data (aprox, 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         /         /         /         /         /         /         /         /			1	0 = coatial	1 = single probe							
23         set probe length [L]         mm         0         20000         3000         ok         SEND           24         get probe length [L]         mm         0         20000         3000         ok         SEND           25         set delivery configuration         1         1         1         ok         SEND           26         resetto delivery configuration         1         1         1         ok         SEND           27         get robe length [L]         mm         0         20000         1999.5         ok         SEND           27         get software revision         1         1         1         ok         SEND           28         get software revision         1         1         32000         1999.5         ok         SEND           29         get device status         1         1         1         1010.00.000         ok         SEND           30         aguire signal data (aprox, 45sec for 1m probe and 4min for 20m probe)         1         1         1         ok         SEND           31         set signal range from x1 to x2         x2 (mm)         0         20000         -0000         ok         SEND			1									
24         get probe length [L]         mm         0         20000         3000         ok;         SEND           25         set delivery configuration         /         /         /         /         /         /         /         //         //         //         0k;         SEND           26         resetto delivery configuration         //         /         /         /         //         //         0k;         SEND           27         get level reading         mm         0         20000,0         1999,5;         0k;         SEND           28         get software revision         //         1         32bit         136;         0k;         SEND           29         get device status;         //         /         1         0110100.0000;         0k;         SEND           30         aquire signal data (aprox: 45sec for 1m probe and 4min for 20m probe)         //         //         //         //         //         //         //         0k;         SEND           31         set signal range from x1 to x2         x1 (min)         -1000,0         20000         -1000,0         ok;         SEND			mm									
25         set delivery configuration         / <th <="" th="">         /<!--</td--><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th>	/ </td <td></td>											
26         reset to delivery configuration         I         Diversion         SEND         SEND         SEND         20000.0         1999.5         Ock         SEND         SEND         29         get software revision         I         1         32bit         136         Ock         SEND         29         get device status         I         I         11         10101000000         ock         SEND         30         aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         I         I         I         I         ock         SEND         31         set signal range from x1 to x2         x1 (min)         -1000.0         20000         -1000         ock         SEND           31         set signal range from x1 to x2         x2 (mm)         0         20000         -0000         ock         SEND			1	1		1	ok	SEND				
27         get level reading         mm         0         20000,0         1999,5         ok         SEND           28         get software revision         //         1         32bit         136         ok         SEND           29         get device status         //         //         1         0100000         ok         SEND           30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         //         //         //         //         //         //         //         //         //         //         SEND           31         set signal range from x1 to x2         x1 (min)         -1000,0         20000         -1000         ok         SEND			1	1		1						
28         get software revision         /         1         32bit         136         ok         SEND           29         get device status         / <td< td=""><td></td><td></td><td>-</td><td>0</td><td></td><td>1999.5</td><td></td><td>the second se</td><td></td><td></td></td<>			-	0		1999.5		the second se				
29         get device status         /         /         /         /         /         011 0100 0000         ok         SEND           30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         /         /         /         /         /         /         /         /         /         SEND           31         set signal range from x1 to x2         x1 (min)         -1000,0         20000         -1000         ok         SEND				-								
30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         I         I         I         I         Ok         SEND           31         set signal range from x1 to x2         x1 (min)         -1000,0         20000         -1000         ok         SEND			1				713					
31         set signal range from x1 to x2         x1 [mm]         -1000,0         20000         -1000,0         SEND           31         set signal range from x1 to x2         x2 [mm]         0         20000         4000         ok         SEND			1	-		0110100000						
31 set signal range from x1 to x2 x2 (mm) 0 20000 4000 0K SENO			v1 Imml			-1000	UN.	JEND				
		31 set signal range from x1 to x2					ok	SEND				
required inter			1 A2 (min)	1 0	20000	4000	-					
						required user						



Verify changes by clicking again on I13 / I15 "get lower / upper threshold switching output"

#### 8.6.8 Upper Dead Band

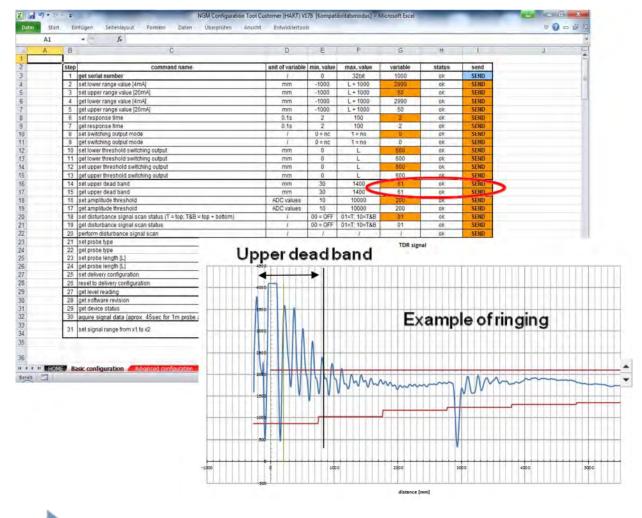
#### **BASIC CONFIGURATION**

• Read out actual upper dead band, by clicking on I17.

Field G17 indicates the actual upper dead band.

With the upper dead band, noisy signals or ringing caused by the installation can be blocked. Increase the value for cutting signals left to the dead band, whose position is indicated by a green line. Any signal left to the green line will not be analyzed by the software. Entered values are in mm and are visible at the echo curve.

• Change actual upper dead band in field G16 and click on I16 "set upper dead band".



Verify changes by clicking again on I17 "get upper dead band"

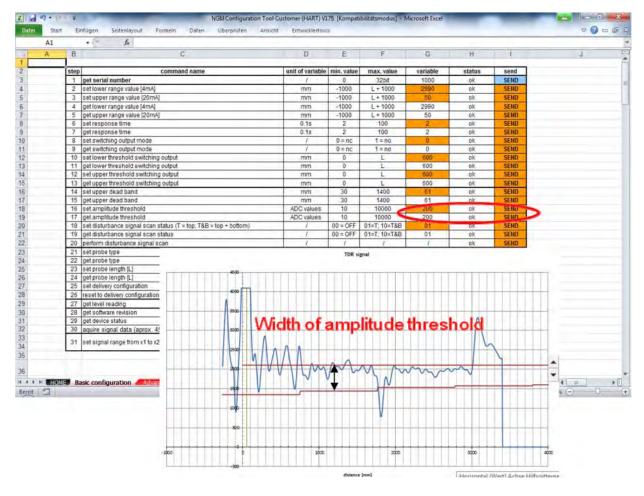
#### 8.6.9 Amplitude threshold

#### **BASIC CONFIGURATION**

• Read out actual amplitude threshold, by clicking on I19

Field G19 indicates the actual amplitude threshold. Dynamic noise or ringing can be blocked if it is within the amplitude threshold band. The level reflection should be always 1/3 bigger than the width of the amplitude threshold band.

• Change actual amplitude threshold in field G18 and click on I18 "set amplitude threshold".





Verify changes by clicking again on I19 "get amplitude threshold"

#### 8.6.10 Disturbance Signal Scan Status

#### **BASIC CONFIGURATION**

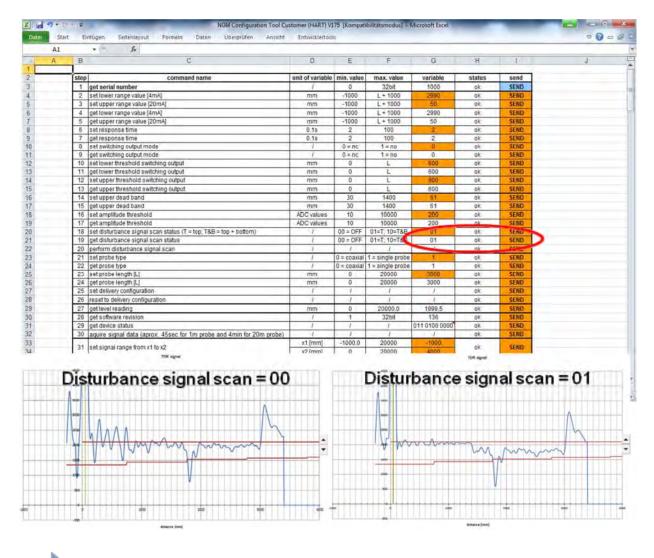
• Read out actual disturbance signal scan status by clicking on I21

Field G21 indicates the actual disturbance scan signal status.

- 00=off, raw echo curve
- -01=disturbance signal active on top
- 10=disturbance signal active on top and bottom

• Change actual disturbance signal scan status in field G20 and click on I20 "set disturbance signal scan status"

• Once changing it to "10" or "01" a disturbance signal scan must be performed with I22.



Verify changes by clicking again on I21 "get disturbance signal scan status"

#### 8.6.11 Probe Type

#### **BASIC CONFIGURATION**

• Read out actual probe type status, by clicking on I24.

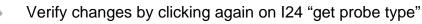
Field G24 indicates the actual probe type status.

- 0= coaxial probe
- 1= single probe rod or rope

Thresholds are adapted automatically by changing this parameter.

• Change actual probe type in field G23 and click on I23 "set probe type".

A1		• - L								
A	B	C	D	E	F	G	н	J.	J	1
-	ste	p command name	unit of variable	min value	max. value	variable	status	send		
	1		unit of valiable	0	32bit	1000	ok	SEND		
		set lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
		set upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
	4			-1000	L+1000	2990	ok	SEND		
			mm	-1000	L+1000	50		SEND		
		get upper range value [20mA]	mm			2	ok			
	6		0.1s	2	100		ok	SEND		
	7		0.15	2 0 = nc	100 1=no	2	ok	SEND		
	8		1		1 = no 1 = no	0	ok	SEND		
	9		-	0 = nc		600	1611	SEND		
		set lower threshold switching output	mm	0	L	600	ok	SEND		
		get lower threshold switching output	mm	0		600	ok			
		set upper threshold switching output	mm		L		ok	SENID		
		get upper threshold switching output	mm	0	L	600	ok	SEND		
		set upper dead band	mm	30	1400	65	ok	SEND		
		get upper dead band	mm	30	1400	61	0k	SEND		
		set amplitude threshold	ADC values	10	10000	200	0K	SEND		
	17		ADC values	10	10000	200	ok	SEND		
		set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
		get disturbance signal scan status	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
		perform disturbance signal scan	1	1	1	1	OF	SEND		
		set probe type	1		1 = single pr		ok	SEND		
		get probe type	1		1 = single pr	1	ok	SEND	, · · · · · · · · · · · · · · · · · · ·	
		set probe length [L]	mm	0	20000	3000	WR.	SEND.		
		get probe length [L]	mm	0	20000	3000	0k	SEND		
		set delivery configuration	1	1	1	1	ok	SEND		
		reset to delivery configuration	1	1	1	1	ok	SEND		
		get level reading	mm	0	20000,0	1999,5	ok	SEND		
	28	get software revision	1	1	32bit	136	0k	SEND		
	29	get device status	1.	1	1	011 0100 0000	0K	SEND		
	30	aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe).	1	1	1	1	ok	SEND		
	1	set signal range from x1 to x2	xt [mm]	-1000.0	20000	-1000	ok	SEND		
	3	set signal range from k) to k2	x2 (mm)	0	20000	4000	96	SEND		
	-		-	-						
						required user				
						input				



#### 8.6.12 Probe Length

#### **BASIC CONFIGURATION**

• Read out actual probe length, by clicking on I26.

Field G26 indicates the actual probe length in mm.

• Change actual probe length in field G25 and click on I25 "set probe length".

step         command name         unit of variable         max. value         variable         status         send           1         get serial number         /         0         320t         1000         ok         SEND           2         set lower range value [AnA]         mm         -1000         L + 1000         590         ok         SEND           3         set upper range value [AnA]         mm         -1000         L + 1000         50         ok         SEND           5         get upper range value [20mA]         mm         -1000         L + 1000         50         ok         SEND           6         set response time         0.1s         2         100         2         ok         SEND           8         set response time         0.1s         2         100         2         ok         SEND           9         get switching output mode         /         0 = nc         1 = no         0         ok         SEND           11         get lower threshold switching output         mm         0         L         800         ok         SEND           12         set ower threshold switching output         mm         0         L         800         ok	A	В	C	D	E	F	G	H	1		J		
2       set upper range value [AmA]       mm       -10000       L + 10000       2980       ok       SERD         3       set upper range value [AmA]       mm       -10000       L + 10000       2980       ok       SERD         4       get lower range value [AmA]       mm       -10000       L + 10000       2980       ok       SERD         5       get upper range value [Z0mA]       mm       -10000       L + 10000       2000       ok       SERD         6       set response time       0.15       2       100       2       ok       SERD         7       pet response time       0.15       2       100       2       ok       SERD         8       zet switching output mode       /       0 = nc       1 = no       0       ok       SERD         10       set lower threshold switching output       mm       0       L       8000       ok       SERD         11       get upper threshold switching output       mm       0       L       8000       ok       SERD         12       set upper dead band       mm       30       1400       61       ok       SERD         13       get upper threshold       subper dead band </th <th>-</th> <th>step</th> <th>command name</th> <th>unit of variable</th> <th>min. value</th> <th>max. value</th> <th>variable</th> <th>status</th> <th>send</th> <th></th> <th></th>	-	step	command name	unit of variable	min. value	max. value	variable	status	send				
3       set upper range value [20mA]       mm       -1000       L + 1000       59       ok       SERD         4       get lower range value [20mA]       mm       -1000       L + 1000       2900       ok       SERD         5       get upper range value [20mA]       mm       -1000       L + 1000       2900       ok       SERD         7       get response time       0.15       2       100       2       ok       SERD         8       set syntching output mode       /       0 = nc       1 = no       0       ok       SERD         9       get switching output mode       /       0 = nc       1 = no       0       ok       SERD         10       set tower threshold switching output       mm       0       L       600       ok       SERD         11       get upper Threshold switching output       mm       0       L       600       ok       SERD         12       set upper Threshold switching output       mm       0       L       600       ok       SERD         13       get upper dead band       mm       30       1400       61       ok       SERD         14       set upper threshold       ADC values		1	get serial number	1	0	32bit	1000	ok	SEND				
4       get lower range value [4mA]       mm       -1000       L + 1000       2980       ok       SEN0         5       get upper range value [20mA]       mm       -1000       L + 1000       50       ok       SEN0         6       set response time       0.1s       2       100       2       ok       SEN0         7       get response time       0.1s       2       100       2       ok       SEN0         8       set switching output mode       /       0 = nc       1 = no       0       ok       SEN0         10       set ower threshold switching output       mm       0       L       600       ok       SEN0         11       get upper fineshold switching output       mm       0       L       600       ok       SEN0         12       set upper fineshold switching output       mm       0       L       600       ok       SEN0         13       get upper fead band       mm       30       1400       61       ok       SEN0         15       get amplitude threshold       ADC values       10       100000       200       ok       SEN0         16       set amplitude threshold       ADC values       10 </td <td></td> <td>2</td> <td>set lower range value [4mA]</td> <td>mm</td> <td>-1000</td> <td>L+1000</td> <td>2990</td> <td>ok</td> <td>SEND</td> <td></td> <td></td>		2	set lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND				
5       get upper range value [20m4]       mm       -1000       L + 1000       50       ok       SEND         6       set response time       0.15       2       100       2       ok       SEND         7       get response time       0.15       2       100       2       ok       SEND         8       get response time       0.15       2       100       2       ok       SEND         9       get switching output mode       /       0 = nc       1 = na       0       ok       SEND         10       set lower threshold switching output       mm       0       L       800       ok       SEND         11       get upper threshold switching output       mm       0       L       800       ok       SEND         13       get upper threshold switching output       mm       0       L       600       ok       SEND         14       set upper threshold switching output       mm       30       1400       61       ok       SEND         15       get upper deab band       mm       30       1400       61       ok       SEND         16       set anglitude threshold       ADC values       10       100		3	set upper range value [20mA]	mm	+1000	L+1000	50	ok.	SEND				
6         set response time         0.1s         2         100         2         0k         SEND           7         get response time         0.1s         2         100         2         0k         SEND           8         set switching output mode         /         0 = nc         1 = no         0         0k         SEND           10         set lower threshold switching output         mm         0         L         600         0k         SEND           11         get lower threshold switching output         mm         0         L         600         0k         SEND           13         get upper threshold switching output         mm         0         L         600         0k         SEND           14         set upper dead band         mm         30         1400         B1         0k         SEND           15         get amplitude threshold         ADC values         10         10000         200         0k         SEND           16         set amplitude threshold         ADC values         10         10000         200         0k         SEND           17         get amplitude threshold         ADC values         10         10000         200 <td< td=""><td></td><td>4</td><td>get lower range value [4mA]</td><td>mm</td><td>-1000</td><td>L+1000</td><td>2990</td><td>ok</td><td>SEND</td><td></td><td></td></td<>		4	get lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND				
7       gef response time       0.15       2       100       2       0k       SEND         8       set switching output mode       /       0 = nc       1 = no       0       0k       SEND         9       gef switching output mode       /       0 = nc       1 = no       0       0k       SEND         10       set lower threshold switching output       mm       0       L       600       0k       SEND         11       get upper threshold switching output       mm       0       L       600       0k       SEND         12       set upper threshold switching output       mm       0       L       600       0k       SEND         13       get upper dead band       mm       30       1400       B1       0k       SEND         14       set upper threshold       ADC values       10       10000       200       0k       SEND         15       get amplitude threshold       ADC values       10       10000       200       0k       SEND         16       set amplitude threshold       ADC values       10       100000       200       0k       SEND         17       get disturbance signal scan status (T = top; T&B = top + botto		5	get upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND				
8         set switching output mode         /         0 = nc         1 = no         0         ok         SEND           9         get switching output mode         /         0 = nc         1 = no         0         ok         SEND           10         set lower threshold switching output         mm         0         L         600         ok         SEND           11         get lower threshold switching output         mm         0         L         600         ok         SEND           12         set upper threshold switching output         mm         0         L         600         ok         SEND           13         get upper threshold switching output         mm         0         L         600         ok         SEND           14         set upper dead band         mm         30         1400         61         ok         SEND           16         set amplitude threshold         ADC values         10         10000         200         ok         SEND           19         get disturbance signal scan status (T = top: T&B = top + bottom)         /         00 = coaxial 1 = single probe         1         ok         SEND           20         perform disturbance signal scan         / <td< td=""><td></td><td>6</td><td>set response time</td><td>0.1s</td><td>2</td><td>100</td><td>2</td><td>ok</td><td>SEND</td><td></td><td></td></td<>		6	set response time	0.1s	2	100	2	ok	SEND				
9       pet switching output mode       /       0 = nc       1 = no       0       0k       SER0         10       setiover threshold switching output       mm       0       L       600       0k       SER0         11       get lover threshold switching output       mm       0       L       600       0k       SER0         12       set upper threshold switching output       mm       0       L       600       0k       SER0         13       get upper threshold switching output       mm       0       L       600       0k       SER0         14       set upper dead band       mm       30       1400       61       0k       SER0         15       get amplitude threshold       MDC values       10       10000       200       0k       SER0         16       set amplitude threshold       ADC values       10       10000       200       0k       SER0         19       get disturbance signal scan status (T = top: T&B = top + bottom)       /       00 = OFF       01=T; 10=T&B       0t       0k       SER0         20       petform disturbance signal scan status (T = top: T&B = top + bottom)       /       00 = OFF       01=T; 10=T&B       0t       0k       SE		7	get response time	0.15	2	100	2	ok	SEND				
10       setLower threshold switching output       mm       0       L       800       0K       SEHD         11       getLower threshold switching output       mm       0       L       600       0K       SEHD         12       set upper threshold switching output       mm       0       L       600       0K       SEHD         13       getLower threshold switching output       mm       0       L       600       0K       SEHD         14       set upper threshold switching output       mm       0       L       600       0K       SEHD         14       set upper dead band       mm       30       1400       61       0K       SEHD         15       getLower threshold       ADC values       10       10000       200       0K       SEHD         16       set disturbance signal scan status (T = top, T&B = top + bottom)       /       00 = 0FF       01 = 10000       200       0K       SEHD         19       get disturbance signal scan       /       /       00 = 0FF       01 = 0K       SEHD         20       perform disturbance signal scan       /       /       00 = 0CFF       01 = 0K       SEHD         21       set probe trype						1 = no							
11     get lower threshold switching output     mm     0     L     600     0k     SEND       12     set upper threshold switching output     mm     0     L     600     0k     SEND       13     get upper threshold switching output     mm     0     L     600     0k     SEND       14     set upper dead band     mm     30     1400     S1     0k     SEND       15     get upper threshold switching output     mm     30     1400     S1     0k     SEND       16     set amplitude threshold     ADC values     10     10000     200     0k     SEND       17     get amplitude threshold     ADC values     10     10000     200     0k     SEND       19     get disturbance signal scan status (T = top, T&B = top + bottom)     /     00 = OFF     01 = T, 10 = T&B     01     0k     SEND       20     perform disturbance signal scan     /     /     /     /     0k     SEND       21     set not bude threshold     NM     0     00 = OFF     01 = T, 10 = T, 8B     01     0k     SEND       22     get nobe type     /     0 = coaxial 1 = single probe     1     0k     SEND       23     set nobe length				1	0 = nc	1 = no	0	0K					
12     set upper threshold switching output     mm     0     L     500     ok     SEND       13     get upper threshold switching output     mm     0     L     600     ok     SEND       14     set upper dead band     mm     30     1400     51     ok     SEND       15     get upper dead band     mm     30     1400     61     ok     SEND       16     set amplitude threshold     ADC values     10     10000     200     ok     SEND       17     get amplitude threshold     ADC values     10     10000     200     ok     SEND       18     set disturbance signal scan status (T = top, T&B = top + bottom)     /     00 = OFF     01=T; 10=T&B     01     ok     SEND       20     perform disturbance signal scan status     (T = top, T&B = top + bottom)     /     00 = OFF     01=T; 10=T&B     01     ok     SEND       20     perform disturbance signal scan status     (T = top, T&B = top + bottom)     /     00 = OFF     01=T; 10=T&B     01     ok     SEND       21     set grobe tippe     /     00 = coaxial     1 = single probe     1     ok     SEND       23     set probe tippe     /     0 = coaxial     1 = single probe				mm		L		ok:					
13     get upper threshold switching output     mm     0     L     600     ok     SEND       14     set upper dead band     mm     30     1400     B1     ok     SEND       15     get upper dead band     mm     30     1400     B1     ok     SEND       16     set amplitude threshold     ADC values     10     10000     200     ok     SEND       17     get amplitude threshold     ADC values     10     10000     200     ok     SEND       18     set disturbance signal scan status (T = top, T&B = top + bottom)     /     00 = OFF     01 = 00K     SEND       20     perform disturbance signal scan     /     /     00 = OFF     01 = 0K     SEND       21     set probe type     /     00 = OFF     01 = 0K     SEND       22     get probe type     /     0 = coaxial 1 = single probe     1     0K     SEND       23     set probe type     /     0 = coaxial 1 = single probe     1     0K     SEND       24     get probe tength [L]     mm     0     20000     3000     0K     SEND       25     set delivery configuration     /     /     /     /     /     x     SEND       25<				mm		L		ok:					
14     set upper dead band     mm     30     1400     51     ok     SEND       15     pet upper dead band     mm     30     1400     61     ok     SEND       16     set amplitude threshold     ADC values     10     10000     200     ok     SEND       17     pet amplitude threshold     ADC values     10     10000     200     ok     SEND       18     set disturbance signal scan status (T = top, T&B = top + bottom)     /     00 = OFF     01=T, 10=T&B     01     ok     SEND       20     petform disturbance signal scan status     /     00 = OFF     01=T, 10=T&B     01     ok     SEND       20     petform disturbance signal scan     /     /     /     /     /     0k     SEND       21     set probe type     /     0 = coaxial 1 = single probe     1     ok     SEND       23     set probe type     /     0 = coaxial 1 = single probe     1     ok     SEND       25     set delivery configuration     /     /     /     /     ac     SEND       25     set delivery configuration     /     /     /     /     ac     SEND       26     set delivery configuration     /     /				mm	0	L	500	ok	SEND				
15       get upper dead band       mm       30       1400       61       ok       SEND         16       set amplitude threshold       ADC values       10       10000       200       ok       SEND         17       get amplitude threshold       ADC values       10       10000       200       ok       SEND         18       set disturbance signal scan status (T = top; T&B = top + bottom)       /       00 = OFF       01=T; 10=T&B       01       ok       SEND         20       perform disturbance signal scan status       /       00 = OFF       01=T; 10=T&B       01       ok       SEND         20       perform disturbance signal scan status       /       00 = OFF       01=T; 10=T&B       01       ok       SEND         21       set probe tippe       /       0 = coaxial       1 = single probe       1       ok       SEND         22       pet probe tength [L]       mm       0       20000       3000       ok       SEND         23       set probe tength [L]       mm       0       20000       3000       ok       SEND         24       get probe length [L]       mm       0       20000       3000       ok       SEND         2		13	get upper threshold switching output	mm	0		600	ok	SEND				
16       set amplifude threshold       ADC values       10       10000       200       ok       SEND         17       get amplifude threshold       ADC values       10       10000       200       ok       SEND         18       set disturbance signal scan status (T = top, T&B = top + bottom)       /       00 = OFF       01 = 10000       200       ok       SEND         19       get disturbance signal scan status (T = top, T&B = top + bottom)       /       00 = OFF       01 = 100 = Top, T&B = top + bottom)       //       00 = OFF       01 = 100 = Top, T&B = top + bottom)         20       perform disturbance signal scan status       /       00 = OFF       01 = 100 = Top, T&B = top + bottom)       //       00 = OFF       01 = Top, T&B = Top, T&B = Top, T&B = Top + bottom)       //       00 = OFF       01 = Top, T&B				mm				ok					
17       get amplitude thrieshold       ADC values       10       10000       200       0k       SEND         18       set disturbance signal scan status (T = top, T&B = top + bottom)       /       00 = OFF       01=T, 10=T&B       04       0k       SEND         19       get disturbance signal scan status       /       00 = OFF       01=T, 10=T&B       01       0k       SEND         20       perform disturbance signal scan       /       /       /       /       0k       SEND         21       set probe type       /       0 = coaxial 1 = single probe       1       0k       SEND         22       get probe type       /       0 = coaxial 1 = single probe       1       0k       SEND         23       set probe length [L]       mm       0       20000       2000       0k       SEND         24       get probe length [L]       mm       0       20000       3000       0k       SEND         25       set delivery configuration       /       /       /       /       ac       SEND         26       get probe length [L]       mm       0       20000       1995.       0k       SEND         27       get level reading       mm				mm		1400		0k:	SEND				
18       set disturbance signal scan status (T = top; T&B = top + bottom)       /       00 = OFF       01=T, 10=T&B       01       0K       SEND         19       get disturbance signal scan status       /       00 = OFF       01=T, 10=T&B       01       0K       SEND         20       perform disturbance signal scan status       /       00 = OFF       01=T, 10=T&B       01       0K       SEND         20       perform disturbance signal scan status       /       /       /       /       0k       SEND         21       set probe type       /       0 = coaxial 1 = single probe       1       0k       SEND         22       get probe length [L]       mm       0       20000       3000       0k       SEND         23       set probe length [L]       mm       0       20000       3000       0k       SEND         24       get probe length [L]       mm       0       20000       3000       0k       SEND         25       set delivery configuration       /       /       /       /       ok       SEND         26       resetto delivery configuration       /       /       /       /       ok       SEND         27       get software				ADC values				OK.					
19       get disturbance signal scan status       /       00 = OFF       01 = 7; 10 = 78B       01       ok       SEND         20       perform disturbance signal scan       /       /       /       /       0       ok       SEND         21       set probe type       /       0       = coaxial 1 = single probe       1       ok       SEND         22       get probe type       /       0 = coaxial 1 = single probe       1       ok       SEND         23       set probe type       /       0 = coaxial 1 = single probe       1       ok       SEND         24       get probe type       /       0       = coaxial 1 = single probe       1       ok       SEND         25       set delivery configuration       /       /       /       /       ok       SEND         26       resetto delivery configuration       /       /       /       /       ok       SEND         27       get twelf eading       mm       0       20000,0       1999,5       ok       SEND         28       get software revision       /       /       1       32bit       136       ok       SEND         29       get device status       / <t< td=""><td></td><td></td><td></td><td>ADC values</td><td></td><td></td><td></td><td>0K</td><td></td><td></td><td></td></t<>				ADC values				0K					
20         perform disturbance signal scan         / <th <="" th=""> <th <="" th="">         /         <th< td=""><td></td><td></td><td></td><td>1</td><td></td><td></td><td></td><td>ok</td><td></td><td></td><td></td></th<></th></th>	<th <="" th="">         /         <th< td=""><td></td><td></td><td></td><td>1</td><td></td><td></td><td></td><td>ok</td><td></td><td></td><td></td></th<></th>	/ <th< td=""><td></td><td></td><td></td><td>1</td><td></td><td></td><td></td><td>ok</td><td></td><td></td><td></td></th<>				1				ok			
21         set probe type         /         0 = coasial         1 = single probe         1         ok         SEND           22         get probe type         /         0 = coasial         1 = single probe         1         ok         SEND           23         set probe length [L]         mm         0         20000         3000         ok         SEND           24         get probe length [L]         mm         0         20000         3000         ok         SEND           25         set delivery configuration         /         /         /         /         /         set ND           26         reset to delivery configuration         /         /         /         /         /         ok         SEND           27         get twelr cading         mm         0         20000,0         1999,5         ok         SEND           28         get software revision         /         1         32bit         136         ok         SEND           29         get device status         /         /         /         /         /         /         /         /         /         /         /         /         /         /         /         / <t< td=""><td></td><td></td><td></td><td>1</td><td>00 = OFF</td><td>01=T; 10=T&amp;B</td><td>01</td><td>ok</td><td>SEND</td><td></td><td></td></t<>				1	00 = OFF	01=T; 10=T&B	01	ok	SEND				
22         get probe type         /         0 = coasial         1 = single probe         1         24         SERD           23         set probe tength (L)         mm         0         20000         3000         ok         SERD           24         get probe tength (L)         mm         0         20000         3000         ok         SERD           25         set delivery configuration         /         /         /         /         .         SERD           26         reset to delivery configuration         /         /         /         /         .         SERD           26         reset to delivery configuration         /         /         /         /         .         .         SERD           27         get tevel reading         mm         0         20000,0         1995,5         ok         SERD           28         get software revision         /         1         . <t< td=""><td></td><td></td><td></td><td>1</td><td></td><td>1</td><td>1</td><td>0K</td><td></td><td></td><td></td></t<>				1		1	1	0K					
23         set probe length [L]         mm         0         20000         3000         ok         SER0           24         get probe length [L]         mm         0         20000         3000         ok         SER0           25         set delivery configuration         /         /         /         /         /         /         set 00           26         reset to delivery configuration         /         <													
24         get probe length [L]         mm         0         20000         3000         ok         SEHD           25         set delivery configuration         /         /         /         /         /         set delivery configuration           26         reset to delivery configuration         /         /         /         /         ok         SEHD           26         reset to delivery configuration         /         /         /         ok         SEHD           27         get level reading         mm         0         20000,0         1999,5         ok         SEHD           28         get software revision         /         1         32bit         136         ok         SEHD           29         get device status         /         /         1         /         /         /         SEHD           30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         0         SEHD           31         set signal most from 11 or 2         /         /         /         /         /         /         /         /         /         /         /         /         /         /								n¥					
25         set delivery configuration         /            /         /         /         /         /         /         /         /         /         /         /         /         /         /         / <th <="" th=""> <th <="" t<="" td=""><td></td><td></td><td></td><td></td><td>-</td><td></td><td></td><td></td><td></td><td></td><td></td></th></th>	<th <="" t<="" td=""><td></td><td></td><td></td><td></td><td>-</td><td></td><td></td><td></td><td></td><td></td><td></td></th>	<td></td> <td></td> <td></td> <td></td> <td>-</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>					-						
26         reset to delivery configuration         / <th <="" th=""> <th <="" th="">         /         <th< td=""><td></td><td></td><td></td><td></td><td>0</td><td></td><td>3000</td><td>0k</td><td></td><td>-</td><td></td></th<></th></th>	<th <="" th="">         /         <th< td=""><td></td><td></td><td></td><td></td><td>0</td><td></td><td>3000</td><td>0k</td><td></td><td>-</td><td></td></th<></th>	/ <th< td=""><td></td><td></td><td></td><td></td><td>0</td><td></td><td>3000</td><td>0k</td><td></td><td>-</td><td></td></th<>					0		3000	0k		-	
27         get level reading         mm         0         20000,0         1999,5         ok         SEND           28         get admare revision         /         1         32bit         136         ok         SEND           29         get device status         /         /         1         011 0100 0000         ok         SEND           30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         /         0k         SEND           31         set signal most from 11 to 20         x1 (mm)         -1000,0         20000         -1000         ok         SEND				-	1		1	540					
28         get software revision         /         1         32bit         136         ock         SEND           29         get device status         /         /         /         /         /         /         /         SEND           30         aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         ok         SEND           31         set signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         ok         SEND           31         set signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         ok         SEND				1	1		/	ok	and the second division of the second divisio				
29         get device status         /         /         /         /         /         011 0100 0000         ok         SEND           30         aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         /         /         /         /         0k         SEND           31         set signal range from r1 to r2         x1 (mm)         -1000,0         20000         -1000         ok         SEND				mm	-								
30         aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)         /         /         /         /         /         ok         SEND           31         set signal range from r1 to r2         x1 (mm)         -1000,0         20000         -1000         ok         SEND				· · · · · · · · · · · · · · · · · · ·									
31 set singl range from vt to v2 x1 (mm) -1000,0 20000 -1000 ok SEM				1	1		011 0100 0000						
31 set singal range from r1 to r2		30	aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)					ok	SEND				
1 Set signal range norm v 10 x2 (mm) 0 20000 4000 00 3600		21	sat signal range from st to so	[mm] tx	-1000,0			ak	SEND				
		20	set signal range norm x no x2.	k2 [mm]	0	20000	4000	04	SLIND				
required user		1						-					

Verify changes by clicking again on I26 "get probe length"

#### 8.6.13 Set Delivery Configuration

#### **BASIC CONFIGURATION**

• Set actual parameters as delivery configuration by clicking on I27

Former delivery configuration parameters will be overwritten! No reset to factory conditions is possible anymore.

A	BC	D	E.	F	G	H	1	J	
-	step command name	unit of variable	min. value	max. value	variable	status	send		
	1 get serial number	1	0	32bit	1000	ok	SEND		
	2 set lower range value [4mA]	mm	-1000	L+1000	2990	0K	SENI)		
	3 set upper range value [20mA]	mm	-1000	L+1000	50	ok.	SEND		
	4 get lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
	5 get upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
	6 set response time	0.1s	2	100	2	ok	SEND		
	7 get response time	0.15	2	100	2	ok	SEND		
	8 set switching output mode	1	0 = nc	1 = no	0	ok	SEND		
	9 get switching output mode	1	0 = nc	1 = no	0	0K	SEND		
	10 set lower threshold switching output	mm	0	L	600	ok:	SEND		
	11 get lower threshold switching output	mm	0	L	600	0K	SEND		
	12 set upper threshold switching output	mm	0	L	500	OK	SEND		
	13 get upper threshold switching output	mm	0	1	600	ok	SEND		
	14 set upper dead band	mm	30	1400	61	ok	SEND		
	15 get upper dead band	mm	30	1400	61	0)k	SEND		
	16 set amplitude threshold	ADC values	10	10000	200	OK	SEND		
	17 get amplitude threshold	ADC values	10	10000	200	0K	SEND		
	18 set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	19 get disturbance signal scan status	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
	20 perform disturbance signal scan	/	1	1	1	0K	SEND		
	21 set probe type	1	0 = coaxial	1 = single probe	1	0X	SEND		
	22 get probe type	1	0 = coaxial	1 = single probe	1	25	SEND		
	23 set probe length [L]	mm	0	20000	3090	QK.	SEND		
	24 get probe length [L]	mm	0	20000	3000	0K	SEND		
	25 set delivery configuration	1	1	1	1	100	SEND		
	26 reset to delivery configuration	1	1	1	1	ok	SEND		
	27 get level reading	mm	0	20000,0	1999,5	ok	SEND		
	28 get software revision	1	1	32bit	136	ok	SEND		
	29 get device status	1	1	1	011 0100 0000	0K	SEND		
	30 aquire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	- /	ok	SEND		
	31 set signal range from x1 to x2	x1 [mm]	-1000,0	20000	-1000	ok	SEND		
	31 Set signal range from x1 to x2	x2 [mm]	0	20000	4000	OK.	SERU		
					Anna in the				



#### 8.6.14 Reset to Delivery Configuration

#### **BASIC CONFIGURATION**

Reset unit back to delivery configuration, by clicking on I28.

4...20mA, response time, switching mode and thresholds, upper dead band, amplitude threshold, disturbance scan, probe type, and probe length will be set back to delivery configuration.

A1 A	1	A 3)•	D	E	F	G	н	T	J
	7								
		ep command name	unit of variable		max. value	variable	status	send	
		get serial number	1	0	32bit	1000	ok	SEND	
		2 set lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND	
		3 set upper range value (20mA)	mm	-1000	L+1000	50	ok	SEND	
		get lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND	
		5 get upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND	
		3 set response time	0.1s	2	100	2	ok	SEND	
		7 get response time	0.1s	2	100	2	ok	SEND	
		3 set switching output mode	1	0 = nc	1 = no	0	ok	SEND	
		get switching output mode	1	0 = nc	1 = no	D	ok	SEND	
		0 set lower threshold switching output	mm	0	L	600	oK	SEND	
		1 get lower threshold switching output	mm	0	L	600	ok	SEND	
		2 set upper threshold switching output	mm	0	L	600	ok	SEND	
		3 get upper threshold switching output	mm	0.	L	600	ok	SEND	
		4 set upper dead band	mm	30	1400	61	ok	SEND	
		5 get upper dead band	mm	30	1400	61	ok	SEND	
		6 set amplitude threshold	ADC values	10	10000	200	ok	SEND	
		7 get amplitude threshold	ADC values	10	10000	200	ok	SEND	
		8 set disturbance signal scan status (T = top; T&B = top + bottom)	4	00 = OFF	01=T; 10=T&B	01	ok	SEND	
	1	9 get disturbance signal scan status	1	00 = OFF	01=T, 10=T&B	01	ok	SEND	
	- 2	0 perform disturbance signal scan	1	1	I	1	ok	SEND	
	1	1 set probe type	1	0 = coaxial	1 = single probe	1	ok	SEND	
		2 get probe type	1	0 = coaxial	1 = single probe	1	ok	SEND	
	1	3 set probe length [L]	mm	0	20000	3000	ok	SEND	
		4 get probe length [L]	mm	0	20000	3000	ok.	SEND	
	1	5 set delivery configuration	1	1	1. <	1	ok	SEND D	1
	12	6 reset to delivery configuration		1	1		05	SEND	
	12	7 get level reading	mm	0	20000,0	1999,5	ok	SEND	
	12	8 get software revision	T	1	32bit	136	ok	SEND	
	12	9 get device status	1	1	1	011 0100 0000	ok	SEND	
	3	0 aquire signal data (aprox: 45sec for 1m probe and 4min for 20m probe)	1	1	1	1	ok	SEND	
			[mm] fx	-1000.0	20000	-1000			
	1.2	1 set signal range from x1 to x2	x2 [mm]	0	20000	4000	ok	SEND	
	-							-	
					1	required user input			

UNDO NOT POSSIBLE!

#### 8.6.15 Level Reading

#### **BASIC CONFIGURATION**

• Get actual level reading, by clicking on I29.

If you do not measure the current output in series with a Multimeter, it is recommended to read out the level 3 - 5 times to recognize potential current fluctuations.

If a fluctuating current can be observed, the amplitude threshold or dead band needs to be adjusted.

A	8 C	D	E	F	G	н	1	J	
	step command name	unit of variable	min. value	max. value	variable	status	send		
	1 get serial number	1	0	32bit	1000	ok	SEND		
	2 set lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
	3 set upper range value (20mA)	mm	-1000	L + 1000	50	ok	SEND		
	4 get lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
	5 get upper range value (20mA)	mm	-1000	L+1000	50	ok	SEND		
	6 set response time	0.15	2	100	2	ok	SEND		
	7 get response time	0.1s	2	100	2	ok	SEND		
	8 set switching output mode	1	0 = nc	1 = no	Q	ok	SEND		
	9 get switching output mode	1	0 = nc	1 = no	Q	OK	SEND		
	10 set lower threshold switching output	mm	0	L	600	ok	SEND		
	11 get lower threshold switching output	mm	0	L	600	ok	SEND		
	12 set upper threshold switching output	mm	0	L	600	ok	SEND		
	13 get upper threshold switching output	mm	0	L	600	OK	SEND		
	14 set upper dead band	mm	30	1400	61	ok	SEND		
	15 get upper dead band	mm	30	1400	61	ok	SEND		
	16 set amplitude threshold	ADC values	10	10000	:200	ok	SEND		
	17 get amplitude threshold	ADC values	10	10000	200	ok	SEND		
	18 set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	19 get disturbance signal scan status	1	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	20 perform disturbance signal scan	1	1	1	1	ok	SEND		
	21 set probe type	1	0 = coaxial	1 = single probe	1	ok	SEMD		
	22 get probe type	1	0 = coaxial	1 = single probe	1	ok	SEND		
	23  set probe length [L]	mm	0	20000	3000	ok	SEND		
	24 get probe length [L]	mm	0	20000	3000	ok	SEND		
	25 set delivery configuration	1	1.	1	1	ok	SEND		
	26 reset to delivery configuration	1	1	1	1	nk	SEND		
	27 get level reading	mm	D	20000.0	1999.5	ok	SEND D		
	28 get software revision	1	1	32bit	135	UK	SEND		
	29 get device status	1	1	1	011 0100 0000	ok	SEND		
	30 aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	T	1	1	1	ok	SEND		
		x1 [mm]	-1000,0	20000	-1000				
	31 set signal range from x1 to x2	x2 [mm]	0	20000	4000	ok	SEND		
	hand a second se	see frinnel							

#### 8.6.16 Software Revision

#### **BASIC CONFIGURATION**

• Get actual software revision, by clicking on I30.

As of April 30, 2013, the actual software revision is V150. For an upgrade please contact KOBOLD.

A1		• _ fe							
A		B C	D	E	F	G	Н	1	J
-		command name	unit of variable	min. value	max, value	variable	status	send	
		1 get serial number	1	0	32bit	1000	ok	SEND	
		2 set lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND	
		3 set upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND	
		4 get lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND	
	_	5 get upper range value (20mA)	mm	-1000	L + 1000	50	ok	SEND	
	- H	5 setresponse time	0.1s	2	100	2	ok	SEND	
	-	7 get response time	0.1s	2	100	2	ok	SEND	
		8 set switching output mode	1	0 = nc	1 = no	0	ok	SEND	
		9 get switching output mode	1	0 = nc	1 = no	0	OK	SEND	
	15	10 set lower threshold switching output	mm	0	L	600	0k	SEND	
		11 get lower threshold switching output	mm	0	L	600	ok	SEND	
		12 set upper threshold switching output	mm	0	L	600	ok	SEND	
		13 get upper threshold switching output	mm	0	L	600	ok	SEND	
		14 set upper dead band	mm	30	1400	61	ok	SEND	
		15 get upper dead band	mm	30	1400	61	ok	SEND	
		16 set amplitude threshold	ADC values	10	10000	200	ok	SEND	
		17 get amplitude threshold	ADC values	10	10000	200	ok.	SEND	
		18 set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T: 10=T&B	01	DK.	SEND	
		19 get disturbance signal scan status	1	00 = OFF	01=T: 10=T&B	01	ok	SEND	
		20 perform disturbance signal scan	1	1	1	1	ok	SEND	
		21 set probe type	1	0 = coaxial	1 = single probe	1	ok	SEND	
		22 get probe type	1	0 = coaxial	1 = single probe	1	ok	SEND	
		23 set probe length [L]	mm	0	20000	3000	ok	SEND	
		24 get probe length [L]	mm	0	20000	3000	ok	SEND	
		25 set delivery configuration	1	1	1	1	ok.	SEND	
	10	26 reset to delivery configuration	1	1	1	1	ok	SEND	
	- 12	27 get level reading	mm	0	20000.0	1999.5	nk	SEND	
		28 get software revision	7	1	32bit	136	0K	SEND	>
		29 get device status	1	1	1	011010000000	UK.	SCHU	
		aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	T	1	1	1	ok	SEND	
		and all and a second data and	x1 [mm]	-1000,0	20000	-1000	de	(CENID)	
		set signal range from x1 to x2	x2 [mm]	0	20000	4000	ok	SEND	
	-			-					
						required user			
						input			

## 8.6.17 Device Status

# **BASIC CONFIGURATION**

• Get actual devise status, by clicking on I31.

Important probe status information can be communicated.

Click on the small red upper right corner for more details.

A1		+ (* Je								
A	В	C	D	E	F	G	Ĥ	- f.	٦	
_	step	command name	unit of variable	min, value	max. value	variable	status	send		
		get serial number	1	0	32bit	1000	ok	SEND		
		set lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
		set upper range value [20mA]	mm	-1000	L + 1000	50	ok	SEND		
		get lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
		get upper range value (20mA)	mm	-1000	L+1000	50	ok	SEND		
		set response time	0.15	2	100	2	ok	SEND		
	7	get response time	0.15	2	100	2	ok	SEND		
		set switching output mode	1	0 = nc	1 = no	0	ok	SEND		
		get switching output mode	1	0 = nc	1 = no	D	ok	SEND		
		set lower threshold switching output	mm	0	L	600	ok	SEND		
		get lower threshold switching output	mm	0	L	600	ok	SEND		
		set upper threshold switching output	mm	0	L	600	ok	SEND		
	13	get upper threshold switching output	mm	0	L	600	ok	SEND		
		set upper dead band	mm	30	1400	őt	ok	SEND		
		get upper dead band	mm	30	1400	61	ok	SEND		
	16	set amplitude threshold	ADC values	10	10000	200	ok.	SEND		
		get amplitude threshold	ADC values	10	10000	200	ok	SEND		
		set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
	19	get disturbance signal scan status	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
		perform disturbance signal scan	1	1	1	1	ok	SEND		
		set probe type	1.	0 = coaxial	1 = single probe	1	ok	SEND		
		get probe type	1		1 = single probe	1	ok	SEND		
		set probe length [L]	mm	0	20000	3000	ok	SEND		
	24	get probe length (L)	mm	0	20000	3000	ok	SEND		
	25	set delivery configuration	1	1	1	1	ok	SEND		
	26	reset to delivery configuration	1	1	1	1	ok	SEND		
		get level reading	mm	0	20000.0	1999.5	OK	SEND		
		get software revision	1	1	32bit	136	ok	SEND		
	29	get device status	1	1	1.	011 0100 0000	ok	SEND		
		aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	7	UK	SEND		
			x1 [mm]	-1000.0	20000	-1000				
	31	set signal range from x1 to x2	x2 [mm]	0	20000	4000	ok	SEND		
	-		1	1	-		-			
						required user input				

### 8.6.18 Signal Data – Echo Curve

### **BASIC CONFIGURATION**

• Acquire actual signal data or also called echo curve by clicking on I32

Once the OK status in field H32 does not disappear anymore, the echo curve can be visualized by clicking on worksheet SIGNAL.

Reading out the echo curve from the electronics can take several seconds, as all data must be communicated via the serial HART protocol to the PC.

A	BC	D	ε	F	G	н	- I	J	
-	step command name	unit of variable	min, value	max. value	variable	status	send		
	1 get serial number	1	0	32bit	1000	ok	SEND		
	2 set lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
	3 set upper range value (20mA)	mm	-1000	L + 1000	50	0K	SEND		
	4 get lower range value [4mA]	mm	-1000	L + 1000	2990	ok	SEND		
	5 get upper range value (20mA)	mm	-1000	L+1000	50	0k	SEND		
	6 set response time	0.1s	2	100	2	ok	SEND		
	7 get response time	0.1s	2	100	2	ok	SEND		
	8 set switching output mode	1	0 = nc	1 = no	0	ok	SEND		
	9 get switching output mode	1	0 = nc	1 = no	0	ok	SEND		
	10 set lower threshold switching output	mm	0	L	600	ok	SEND		
	11 get lower threshold switching output	mm	0	L	600	ok	SEND		
	12 set upper threshold switching output	mm	0	L	600	ok	SEND		
	13 get upper threshold switching output	mm	0	L	600	ok	SEND		
	14 set upper dead band	mm	30	1400	51	0k	SEND		
	15 get upper dead band	mm	30	1400	61	ok	SEND		
	16 set amplitude threshold	ADC values	10	10000	200	ok	SEND		
	17 get amplitude threshold	ADC values	10	10000	200	ok.	SEND		
	18 set disturbance signal scan status (T = top; T&B = top + bott	1 (mo	00 = OFF	01=T; 10=T&B	01	ok	SEND		
	19 get disturbance signal scan status	t	00 = OFF	01=T; 10=T&B	01	0k	SEND		
	20 perform disturbance signal scan	1	1	1	1	OK	SEND		
	21 set probe type	1	0 = coaxial	1 = single probe	1	ok	SEND		
	22 get probe type	1	0 = coaxial	1 = single probe		ok	SEND		
	23 set probe length [L]	mm	0	20000	3000	ok	SEND		
	24 get probe length [L]	mm	0	20000	3000	ok	SEND		
	25 set delivery configuration	1	1	1	1	ok	SEND		
	26 reset to delivery configuration	1	1	t	1	ok	SEND		
	27 get level reading	mm	0	20000,0	1999,5	ok	SEND		
	28 get software revision	1	1	32bit	136	ok	SEND		
	29 get device status	4:	1	1	011 0100 0000	0k	SEND		
	30 aquire signal data (aprox. 45sec for 1m probe and 4min f	or 20m probe) /	1	1	1	ok	SEND	>	
	21 autoing lange from a face of the sig	x1 [mm]	-1000,0	20000	- forest		COND.		
	31 set signal range from x1 to x2	x2 [mm]	0	20000	4000	ok	SEND		
			-						

## 8.6.19 Signal Range

### **BASIC CONFIGURATION**

• Set signal range, by entering values in field G33/34 and clicking on I33/34

Depending on the probe length, the range within the echo curve in worksheet SIGNAL can be adapted.

A negative X1 range of -1000 is always recommended and standard. With this the microwave generation and coupling can be verified.

1	В	* * * * C	D	E	F	G	н	1	J	
	step	command name	unit of variable	min value	max. value	variable	status	send		
		get serial number	J	0	32bit	1000	ok	SEND		
		set lower range value [4mA]	mm	-1000	L+1000	2990	ok	SEND		
- 7		set upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
-		get lower range value (4mA)	mm	-1000	L+1000	2990	ok	SEND		
		get upper range value [20mA]	mm	-1000	L+1000	50	ok	SEND		
-		set response time	0.15	2	100	2	ok	SEND		
	7	get response time	0.15	2	100	2	ok	SEND		
-1	8	set switching output mode	0.13	0 = nc	1=no	0	ok	SEND		
		get switching output mode	1	0 = nc	1 = no	0	ok	SEND		
		set lower threshold switching output	mm	0	L	500	ok	SEND		
- 1		get lower threshold switching output	mm	0	L	500	ok	SEND		
		set upper threshold switching output	mm	0	L	600	ok	SEND		
		get upper threshold switching output	mm	0	L	600	ok	SEND		
		set upper dead band	mm	30	1400	61	ok	SEND		
		gel upper dead band	mm	30	1400	61	ok	SEND		
	-	set amplitude threshold	ADC values	10	10000	200	ok	SEND		
		get amplitude threshold	ADC values	10	10000	200	ok	SEND		
		set disturbance signal scan status (T = top; T&B = top + bottom)	1	00 = OFF	01=T: 10=T&B	01	ok	SEND		
		get disturbance signal scan status	1	00 = OFF	01=T: 10=T8B	01	ok	SEND		
		perform disturbance signal scan	1	1	1	1	ok	SEND		
		set probe type	T	0 = coaxial	1 = single probe	1	ok	SEND		
		get probe type	1		1 = single probe	1	ok	SEND		
_		set probe length [L]	mm	0	20000	3000	ok	SEND		
	24	get probe length [L]	mm	0	20000	3000	ok	SEND		
		set delivery configuration	1	1	1	1	ok	SEND		
	26	reset to delivery configuration	1	1	1	1	ok	SEND		
- 11		get level reading	mm	0	20000,0	1999,5	ok	SEND		
		get software revision	1	1	32bit	136	0R	SEND		
		get device status	1	1	1	011 0100 0000	ok	SEND		
- 7		aguire signal data (aprox. 45sec for 1m probe and 4min for 20m probe)	1	1	1	1	ok	SEND		
			x1 [mm]	-1000.0	20000	-1000				
	31	set signal range from x1 to x2	x2 [mm]	0	20000	\$000	ok	SEND	>	
-	-						_			
						required user				

### 8.6.20 Signal

### SIGNAL

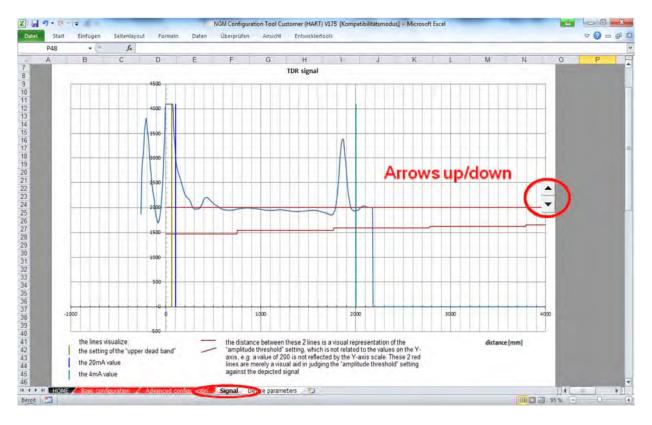
- Visualization of the actual echo curve, where the level calculation is based on.
- The NGM gets 70 echo curves every second for calculating the level.

The most important parameters (4...20mA; dead band and amplitude threshold) are visualized.

With the arrows up/down, the amplitude threshold can be positioned properly on the average zero line of the echo curve as a means to evaluate the correct value.

- x-axis: length in mm

y-axis : voltage according to factory-specific scales



# 8.6.21 More Parameters...

### ADVANCED CONFIGURATION

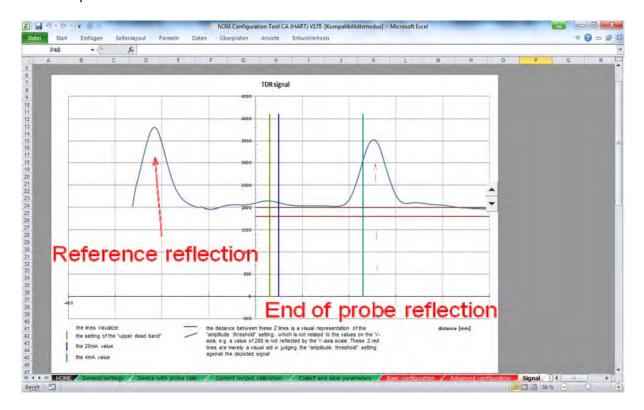
• Parameters within the worksheet ADVANCED CONFIGURATION are only recommended to change by experts.

C47 - Je MEASURE_PROBE_LENGTH (boot of	levice after ru	n)						
C	D	E	F	G	н	1	J.	K
command name	unit of variable	min, value	max. value	variable	status	send	remarks	DIP functio
GET SERIAL NUMBER	1	0	32bit	1000	OR	SEND	in case other commands do not reply	
SET LOWER CURRENT CALIB	0.001mA	4000	8000	6000	ok	SEND	analog current output	
SET_UPPER_CURRENT_CALIB	0.001mA	16000	20000	18000	ok	SEND	analog current output	
GET LOWER CURRENT CALIB	0.001mA	4000	8000	6000	ok	SEND	analog current output	
GET UPPER CURRENT CALIB	0.001mA	16000	20000	18000	ok	SEND	analog current output	
GO LOWER CALIBRATION POINT	Í.	1	I	1	ok	SEND	analog current output	1
GO UPPER CALIBRATION POINT	1	1	1	1	0k	SEND	analog current output	
SET 4MA LEVEL (lower range value [4mA])	mm	-1000	L+1000	2990	Ok	SEND	analog current output	0001 001
SET_20MA_LEVEL (upper range value [20mA])	mm	-1000	L = 1000	50	ok	SEND	analog current output	0010 001
GET_4MA_LEVEL (lower range value (4mA))	mm	-1000	L + 1000	2990	ok	SEND	analog current output	
GET_20MA_LEVEL (upper range value [20mA])	៣៣	-1000	L + 1000	50	0k	SEND	analog current output	11.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1
SET_LOWPASS_TIME (response time)	0.15	2	100	2	ok	SEND	analog current output	010 001
GET_LOWPASS_TIME (response time)	0.1s	2	100	2	ok	SEND	analog current output	
DS SET CURRENT	0.001mA	0	20000	20000	ok	SEND	analog current output	
SET_SWITCH_MODE (switching output mode)	1	0 = nc	1 = no	0	ok	SEND	switching output	010x 010
GET_SWITCH_MODE (switching output mode)	1	0 = nc	1 = no	0	ok	SEND	switching output	1
SET_SWITCH_THRESHOLD (lower threshold switching output)	mm	0	L	500	ok	SEND	switching output	0010 010
GET_SWITCH_THRESHOLD (lower threshold switching output)	mm	0	L	500	ok	SEND	switching output	1
SET_SWITCH_DEACTIVATION_LEVEL (upper threshold switching output	mm	0	1	600	ok	SEND	switching output	0011 010
GET_SWITCH_DEACTIVATION_LEVEL (upper threshold switching output	mm	0	L	600	ok	SEND	switching output	1
DS_SET_SWITCH	1	0	1	1	ok	SEND	switching output	11
DS RELEASE OUTPUT	1	1	1	1	ok	SEND	both outputs	11
SET_MEASUREMENT_PULSE_START (upper dead band)	index	50	300	70	ok	SEND	application	01xx011
GET MEASUREMENT PULSE START (upper dead band)	index	50	300	70	ok	SEND	application	
SET_AMPLITUDE_FACTOR (amplitude threshold)	ADC values	10	10000	200	ok	SEND	application	10xx 011
GET_AMPLITUDE_FACTOR (amplitude threshold)	ADC values	10	10000	200	ok	SEND	application	11.
MEASURE_EMPTY_SCAN (perform disturbance signal scan)	1	1	1	1	ok	SEND	application	0001011
SET_TL_LINE_SLOPE_COAX	m/s	2000	10000	2609	ok	SEND	calibration	1
GET TL LINE SLOPE COAX	m/s	2000	10000	2609	ok	SEND	calibration	
SET_TL_LINE_OFFSET_COAX	mm	-1000,0	1000,0	-390.0	ok	SEND	calibration	
GET_TL_LINE_OFFSET_COAX	mm	-1000,0	1000,0	-390,0	0k	SEND	calibration	
SET_TL_LINE_SLOPE_MONO	m/s	2000	10000	2620	ok	SEND	calibration	
GET_TL_LINE_SLOPE_MONO	m/s	2000	10000	2620	0k	SEND	calibration	1
SET_TL_LINE_OFFSET_MONO	mm	-1000.0	1000,0	-359,5	ok	SEND	calibration	1
GET TL LINE OFFSET MONO	mm	-1000.0	1000,0	-359.5	ok	SEND	calibration	04
SET_PROBE_END_OFFSET_COAX	1/1000 index	-5000	5000	0	ok	SEND	calibration	
GET_PROBE_END_OFFSET_COAX	1/1000 index	-5000	5000	0	ok	SEND	calibration	1
SET PROBE END OFFSET MONO	1/1000 index	-5000	5000	n	ok	SEND	calibration	

## 8.6.22 Signal Discussion 1

### **Empty Coaxial Probe**

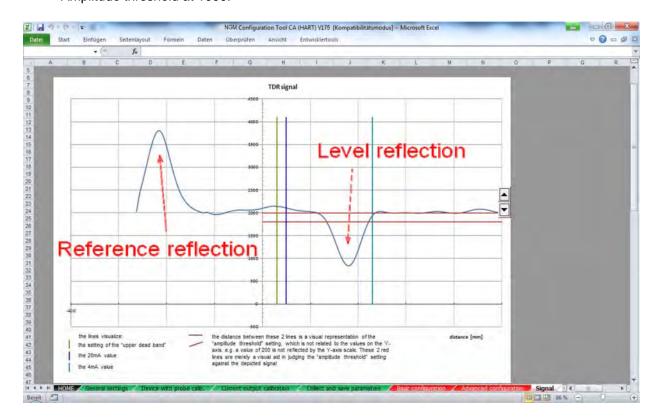
- Nice reference reflection at the beginning
- Perfect coupling into the coaxial probe
- Positive end of probe reflection which corresponds to the physical end of probe



### 8.6.23 Signal Discussion 2

### **Level Coaxial Probe**

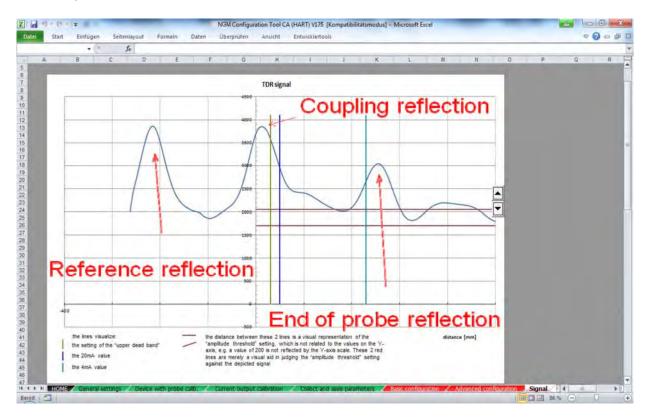
- Stable reference reflection at the beginning
- Negative level reflection at 168mm
- No end of probe reflection as energy is completely reflected at water surface



## 8.6.24 Signal Discussion 3

### **Empty Rod Probe**

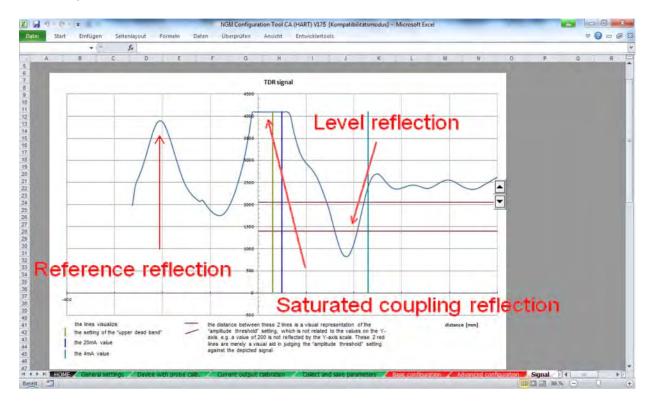
- Nice reference reflection at the beginning
- Strong positive impulse at the transition of coupling to the single rod
- Reflection can change with mounting conditions.
- Positive end of probe reflection which corresponds to the physical end of probe



## 8.6.25 Signal Discussion 4

### **Level Rod Probe**

- Stable reference reflection at the beginning
- Negative level reflection at 168mm
- No end of probe reflection as energy is completely reflected at water surface
- Positive coupling reflection in saturation as amplification factor increased



# 9. Technical Information

	Single rod	Wire rope	Coaxial
Probe diameter	6 mm	4 mm	17.2 mm
Max. Load	Lateral: 6 Nm = 0,2 kg at 3	Tensile: 5 kN	Lateral: 100 Nm = 4.67 kg at
	m		6 m
Probe length L	1003000 mm	100020,000 mm	1006000 mm (standard) 1001000 mm (high temperature)
Dielectric Constant (ε <sub>r</sub> )	> 1.8	> 1.8	> 1.4
Viscosity (cP)	< 5000	< 5000	< 500
Medium temperature,	-40+150°C (without	-40+150°C	-40+130°C (EPDM O-ring)
standard version	PTFE)		-15+150°C (FKM O-ring)
	-15+100°C (PTFE lining)		
High temperature	-200+250°C (NBR O-ring)	Not available	-200+250°C (NBR O-ring)
version	-150+250°C (FKM O-ring)		-150+250°C (FKM O-ring)
Materials exposed to tank atmosphere	1.4571/316 Ti, PEEK Standard version PTFE, O-ring (see order code), (PTFE lining) 1.4571/316 Ti, PEEK, PTFE O-ring (see order code), (high temperature version) In all cases, in addition, a Klinger SIL <sup>®</sup> C-4400 gasket at connection thread, 2 mm thick	1.4401/316, PEEK In addition, a Klinger SIL <sup>®</sup> C-4400 gasket at connection thread, 2 mm thick	1.4404/316 L, PEEK, O-ring (see order code), (standard version) 1.4404/316 L, PEEK, PTFE, O-ring (see order code), (high temperature version) In all cases, in addition, a Klinger SIL <sup>®</sup> C-4400 gasket at connection thread, 2 mm thick

Measuring principle: Installation position: Ambient temperature: Storage temperature: Max. Pressure: Accuracy*:	Guided Wave Radar (GWR) Vertical -25+80°C -40+85°C -1+40 bar (except NGM-19:04 bar) ±3 mm or 0.03 % of measured distance, whichever is greater
Repeatability*:	< 2 mm
Resolution*:	< 1 mm
*Reference condition: $\mathcal{E}_r = 80$ , water,	•
Velocity of level change:	< 1000 mm/s
Medium conductivity:	No restrictions
Medium density:	No restrictions
Process connection: Interface	Thread or flange, see ordering code
	An oil layer of < 70 mm thickness on top of water
	n this case the sensor will detect only the water
level at a slightly lower position	•
	0 mm onwards, the sensor detects the total level,
including the oil layer, accordin	
<b>C</b>	

Materials Housing:	Aluminium alloy, epoxy coated, with safety chain and tin plated 1.4301/SS304 external earth screw
O-ring:	Option: Stainless steel 1.4401/SS316 NGM Rod/Rope: None NGM Coaxial: FKM or EPDM NGM high temperature: NBR or FKM
Weights Housing incl. electronics: Stainless steel housing incl. electronics: Connection ¾ (Coaxial): 1 m Rod probe: 1 m Rope probe: 1 m Coaxial probe: Cooling extension for high temperature:	720 g 1340 g 350 g 230 g 66 g + 380 g ballast weight 540 g + 130 g (attachment kit) 900 g
Electrical data Supply voltage: Output: Total load: Response time: Temperature drift: Switching output DC PNP (active): Load current: Signal voltage HIGH: Signal voltage LOW: Response time: Current consumption: Start-up time: Cable terminals: Cable entry: Protection:	1230 $V_{DC}$ (reverse-polarity protected < 50 mA) 4 wire-system 420 mA (programmable by HART <sup>®</sup> modem) < 500 $\Omega$ + load resistance approx. 250 $\Omega$ 0.5 s [default], 2 s, 5 s (selectable) < 0.2 mm/K change in ambient temperature NC [default] or NO (short-circuit protected) < 200 mA Supply voltage – 2 V 0 V1 V < 100 ms < 50 MA at 24 V <sub>DC</sub> (no burden) < 6 s Clamp terminal block for cable 0.52 mm <sup>2</sup> 2 x M20 x 1.5 IP68

# **10. Order Codes**

Model		Material	Connection	Output	Option
		(Probe/O-ring)		_	
NGM-1	Rod probe	<b>200</b> = stainless steel, PEEK/without O-ring <b>900</b> <sup>5)</sup> = stainless steel, PEEK/FKM PTFE coating	<b>G5</b> = G ¾ male <b>N5</b> = ¾ NPT male <b>F8</b> = DN40 / PN 40 B1, 1.4404/316L flange EN1092-1 <b>F9</b> = DN 50 / PN 40 B1, 316L		$\begin{array}{l} \textbf{00} = \text{without} \\ \textbf{B3}^{1)} = \text{mounted in Bypass} \\ \text{with DIN-flange DN10} \\ \textbf{B4}^{1)} = \text{mounted in Bypass} \\ \text{with DIN-flange DN15} \end{array}$
NGM-8	Rod probe, high temperature	<b>210</b> = stainless steel, PEEK/NBR <b>220</b> = stainless steel, PEEK/FKM	flange EN1092-1 <b>FB</b> = DN 80 / PN 40 B1, 1.4404/316L flange EN1092-1 <b>FC</b> = DN 100 / PN16 B1,	<b>A4</b> = 420 mA, PNP	$B5^{1)}$ = mounted in Bypass with DIN-flange DN20 $B6^{1)}$ = mounted in Bypass with DIN-flange DN25
NGM-2	Coaxial probe	230 = stainless steel, PEEK/EPDM 220 = stainless steel, PEEK/FKM	1.4404/316L flange EN1092-1 <b>A8</b> = 1 ½" ASME B 16.5 CL 150, 1.4404/316L <b>A9</b> = 2" ASME B 16.5	<b>E4</b> <sup>4)</sup> = 420 mA, PNP, ATEX- version	<b>BB</b> <sup>1)</sup> = mounted in Bypass with ANSI-flange ½" <b>BC</b> <sup>1)</sup> = mounted in Bypass with ANSI-flange ¾"
NGM-9	Coaxial probe, high temperature	<b>210</b> = stainless steel, PEEK/NBR <b>220</b> = stainless steel, PEEK/FKM	CL 150, 1.4404/316L <b>AA</b> = 2½ " ASME B 16.5 CL 150, 1.4404/316L <b>AB</b> = 3" ASME B 16.5		<b>BD</b> <sup>1)</sup> = mounted in Bypass with ANSI-flange 1" $S1^{2)}$ = mount. in stilling well DIN-flange DN40/PN40
NGM-4	Wire rope ø 4 mm (liquids and light solids only)	200 = stainless steel, PEEK/without O-ring	CL 150, 1.4404/316L AC = 4" ASME B 16.5 CL 150, 1.4404/316L XX = special (please specify in clear text)		$\begin{split} &\textbf{S2}^{2)} = \textbf{mount. in stilling well} \\ &\textbf{DIN-flange DN50/PN40} \\ &\textbf{S3}^{2)} = \textbf{mount. in stilling well} \\ &\textbf{DIN-flange DN80/PN40} \\ &\textbf{S4}^{2)} = \textbf{mount. in stilling well} \\ &\textbf{DIN-flange DN100/PN16} \\ &\textbf{SA}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 11/2"} \\ &\textbf{150 lbs} \\ &\textbf{SB}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 2" 150 lbs} \\ &\textbf{SC}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 2" 150 lbs} \\ &\textbf{SD}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 21/2"} \\ &\textbf{150 lbs} \\ &\textbf{SD}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 3" 150 lbs} \\ &\textbf{SE}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 3" 150 lbs} \\ &\textbf{SE}^{2)} = \textbf{mount. in stilling} \\ &\textbf{well ANSI-flange 4" 150 lbs} \\ &\textbf{K0}^{3)} = \textbf{mounted in bypass} \\ &\textbf{with roller/ball display} \\ &\textbf{YY} = \textbf{special} \\ \end{split}$

Ordering Data (Example: NGM-1200 G5 A40)

<sup>1)</sup> Bypass specification, see NBK-M data sheet

<sup>2)</sup> Please specify probe length L and stilling well length (when different from standard, see drawing dimensions) in clear text while ordering

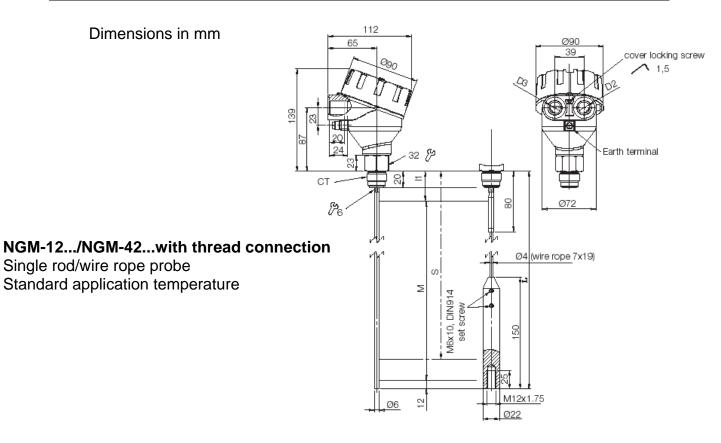
<sup>3)</sup> Bypass specification, see NBK data sheet. Max. possible measuring length ML = 5500 mm. Not possible with NGM-2/-9/-4. Max. medium viscosity 500 cP.

<sup>4)</sup> Not possible with NGM-19..., NGM-8..., and NGM-9

<sup>5)</sup> Not possible for flange sizes <DN50/PN40 and <2½" ASME CL 150

Note: Please specify probe length L in clear text while ordering

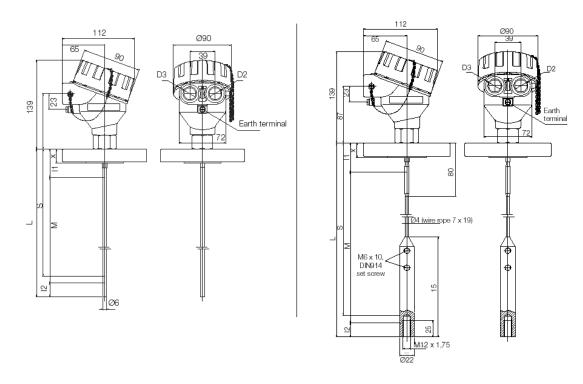
# 11. Dimensions

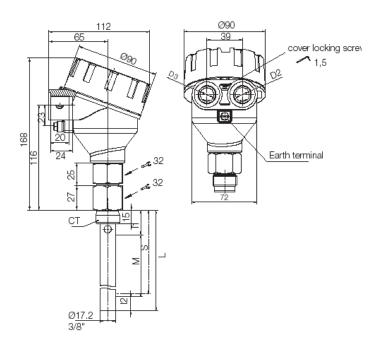


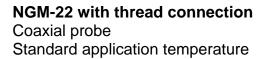
# NGM-12.../NGM-42...with flange connection

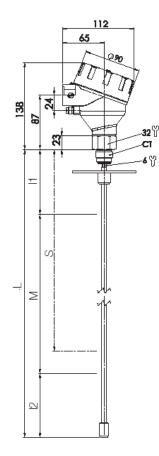
Single rod version

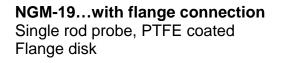
Wire rope version

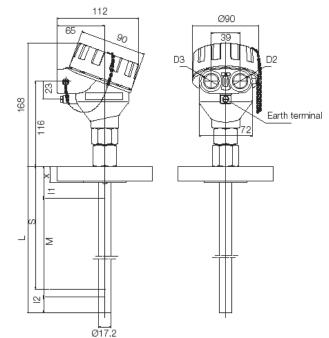




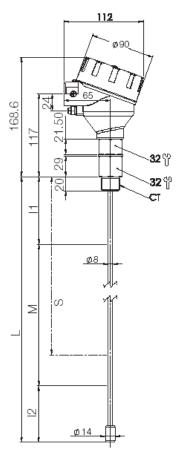




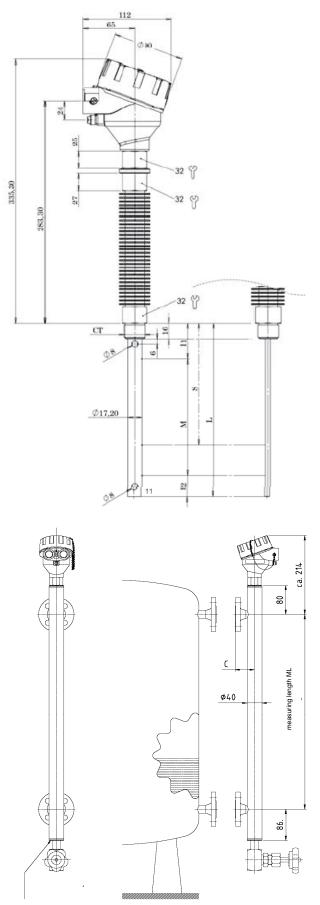


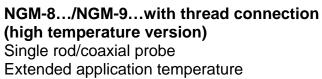


NGM-22...with flange connection



**NGM-19...with thread connection** Single rod probe, PTFE coated Connection thread

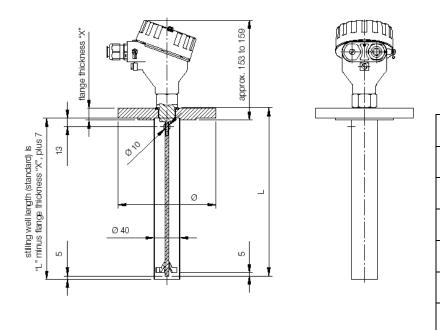




NGM assembled in a bypass tube option B

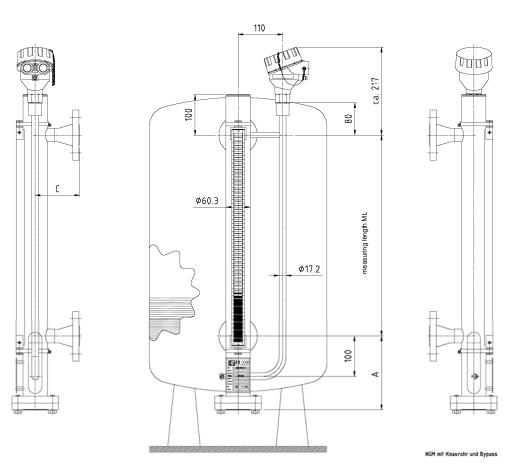
#### NBK-M

Bottom cover with G¼ (DIN flanges) or ¼" NPT (ASME flanges) drain plug or optional needle valve



Connectio n	Flange	"X"	ø
F8	DN40/PN40	18	15 0
F9	DN50/PN40	20	16 5
FB	DN80/PN40	24	20 0
FC	DN100/PN1 6	20	22 0
<b>A</b> 8	1½"/CL 150	17.9	12 5
A9	2"/CL 150	19.5	15 0
AA	21⁄2"/CL 150	22.7	18 0
option S	3"/CL 150	24.3	19 0
AC	4"/CL 150	24.3	21 5

NGM with "Top Mounting in Stilling Well" option S



NGM assembled in a bypass tube with roller/ball display (redundant measurement) option K

# **12. Safety Instructions for Ex-Versions Model NGM**

# NGM

4-wire TDR-Sensor with single rod or coaxial probe for continuous level measurement and point level detection in liquids, with analog and switching output.

## **DOCUMENT DESCRIPTION**

These safety instructions are part of the NGM Quick Installation Guide and give instructions regarding to proper installation and operation of NGM in hazardous areas.

### **GENERAL DESCRIPTION**

NGM is suitable for applications with hazardous gas or dust atmospheres, for applications requiring instruments of category 1/2G, 1/2D or 2G, 2D. If NGM is installed and operated in hazardous areas, the general hazardous area installation regulations IEC 60079-14, all relevant national, regional and local regulations and standards, as well as these safety instructions must be observed. The installation of electrical equipment in hazardous areas must always be carried out by qualified personnel.

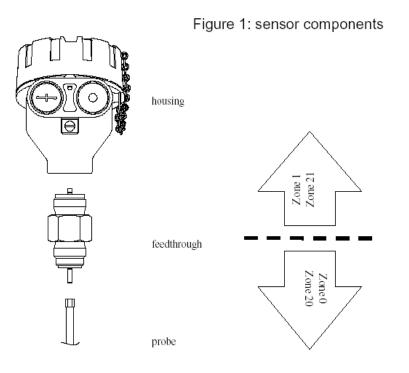
## **APPROVAL DETAILS**

**CE** 0158 SEV 13 ATEX 0108 X

- 🔄 🛛 II 1/2G Ex ia/db IIC T6 Ga/Gb
- II 1/2D Ex ia/tb IIIC T86°C IP68 Da/Db
- 🔄 🛛 II 2G Ex ia db IIC T6 Gb
- 🖾 II 2D Ex ia tb IIIC T86°C IP68 Db

## SENSOR COMPONENTS

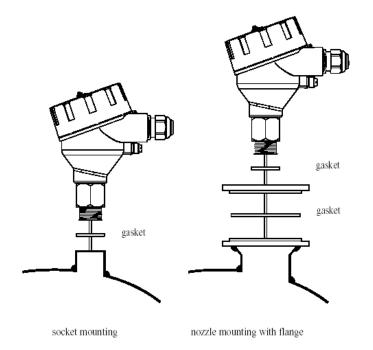
NGM consists of three major components: housing, feedthrough, and probe. The only components that are exposed to the atmosphere inside the tank are probe and the part of the feedthrough below the hexagon. NGM has a flameproof metal housing that contains the sensor s electronics and input/output terminals and has no contact to the atmosphere inside the tank. For hazardous applications that require category 1/2G, 1/2D devices, the housing is installed in hazardous areas requiring devices of category 2G, 2D (zone 1, zone 21). The feedthrough of the sensor (acting as separation barrier between zones 0/1, zone 20/21) is installed in the wall which separates areas requiring devices of category 2G, 2D from 1G, 1D. The probe is installed in hazardous areas requiring devices of category 2G, 2D devices, all components of NGM are installed in hazardous areas requiring devices of category 2G, 2D (zone 1, zone 21).



## MOUNTING

NGM is mounted vertically to the tank via its connection thread, which is screwed directly into a standard threaded tank connection, i.e. weld-in socket, or it can be screwed into a flange, which is then connected to a tank nozzle. NGM should not be welded directly into the tank. Neither should flanges be welded onto NGM. Welding on the metal parts of NGM will cause serious damage to the sensor. Do not lift or handle NGM by its probe; this can cause excessive stress on the probe connection. NGM should be handled by the hexagon or the lower section of the housing. Do not screw in NGM by its housing; it should be tightened only via its hexagon (wrench size 32mm for connection thread G3/4A). Tighten the coaxial probe only at its lower hexagon; the upper hexagon of the coaxial probe is not needed for mounting. The customer has to ensure suitability of all materials exposed to the tank atmosphere as well as proper sealing of the sensor connection; based on his process conditions like temperature, pressure and resistance against his process liquids and atmosphere. G thread connections require a suitable gasket for pressure-tight joints. The G3/4A connection thread of NGM is supplied with a gasket made of Klingersil C-4400, thickness 2mm. The suggested tightening torque for this thread size, this type of gasket, and a process pressure of max. 40bar is 25Nm (maximum permissible torque: 45 Nm). For NPT thread connections, pressure-tight joints require a sealant directly on the threads.

Figure 2: mounting



# MOUNTING CONSIDERATIONS

The probes should be installed so that they are not directly impacted by liquids flowing out of the filling inlet. They should neither touch nor sway towards other objects inside the tank or the tank/nozzle walls; e.g. by agitator swirls. In applications with very strong fluid movements, which can also cause excessive lateral force on the probe, it is recommended to fix the probe. The anchoring fixtures are customer supplied.

The customer is not permitted to disassemble the feedthrough from the housing or perform any mechanical repairs/alterations on either the feedthrough or the enclosure. If the NGM requires service or repair, please contact Kobold.

## TEMPERATURE CLASSES

For applications in hazardous gas atmospheres, the maximum permissible application and ambient temperatures, depending on the temperature classes, are specified in figure 3. For applications in hazardous dust atmospheres, the maximum permissible surface temperature is +86°C and the ambient temperature range is -40 +70°C. For hazardous areas that require category 1/2G devices, the application pressure must be between 0,8 1,1 bar. If NGM is operated at temperatures higher than those specified in figure 3, please make sure through appropriate measures that there is no danger of ignition from the hot surfaces. The maximum permissible ambient temperature should not exceed the values specified in figure 3. For application conditions in non-hazardous area, please refer to the data sheet.

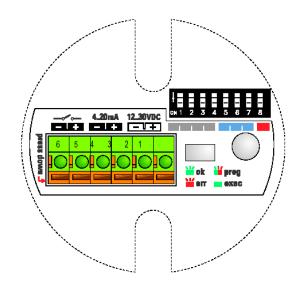
### Figure 3: temperature classes

	CATEGORY 1/2G						
Temperature	Application	Ambient					
class	temperature	temperature					
T1T6	-20+60°C	-40+70°C					
CATEGORY 2G							
T6	-40+85°C	-40+70°C					
T5	-40+100°C	-40+70°C					
T4	-40+135°C	-40+70°C					
T1T3	-40+150°C	-40+70°C					
CAT	EGORY 1/2D AND	) 2D					
Max. surface ten	nperature: +86°C	-40+70°C					

### ELECTRICAL DATA

Supply voltage (terminals 1+2): U = 12 30V DCUm = 250V AC Analog output (terminals 3+4): I = 4 20mA Um = 250V AC Switching output (terminals 5+6): Us = 0 U Um = 250V AC

Figure 4: electrical data

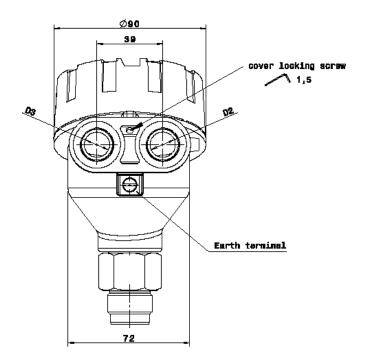


### CABLE ENTRIES AND CABLE GLANDS

The housing has two cable entries. For installation in hazardous areas, only cable glands certified according to IEC 60079-1 or certified conduit systems are permitted. The tightening torque specified by the manufacturer of the certified cable glands or conduit systems has to be observed. The torque mentioned on the sensor electronic only applies to standard cable glands/conduits, which are not permitted for installation in hazardous areas. Both cable entries can be fitted with cable glands/conduits. If only one cable gland/conduit is fitted, it is recommended to use cable entry D2 (see Fig. 5).

Then cable entry D3 has to be sealed with a certified screw plug. The cable entries have to be properly sealed and cable glands have to be properly tightened around cable of suitable type and diameter to ensure the IP68 rating of the housing. The seals for mounting the cable glands/conduits, the cable glands/conduits themselves and the cable used for wiring have to be rated for a temperature of +86 °C. When wiring with shielded or armoured cable, suitable cable glands have to be used. The contact between the metal housing and the shielding of the cable is made by using a suitable EMC-type cable gland. Ground the shielding of the cable only on the sensor side; not on the supply side.

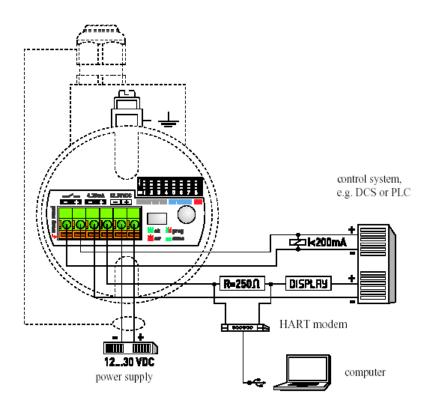
Figure 5: cable entries



### WIRING

Before opening the housing cover for any reason, verify that the power supply for the sensor has been switched off for at least 6 minutes or no explosive atmosphere is present. After wiring NGM, tighten the housing cover properly by turning it clockwise (make sure the cover safety chain does not tangle up) and properly tighten the cover locking screw with an allen key size 1,5mm (see Fig. 5). Only when the cover is tightened and secured it is permitted to power up NGM. The housing cover of NGM features a thread acting as a flameproof gap and a caution message; it must not be exchanged for any other cover. Establish an equipotential connection (potential equalization) between the external earth terminal of NGM and the closest ground potential terminal of the tank.

Figure 6: wiring



# **13. EU Declaration of Conformance**

We, KOBOLD Messring GmbH, Hofheim-Ts, Germany, declare under our sole responsibility that the product:

Guided Wave Radar Level Model: NGM

to which this declaration relates is in conformity with the standards noted below:

**EN 61326-1:2013** Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 1: General requirements

Also the following EC guidelines are fulfilled:

2014/30/EU	EMC Directive
2011/65/EU	RoHS

Hofheim, 21. March 2017

### 2014/34/EU

Equipment and Protective systems intended for use in potentially Explosive Atmospheres Quality Management Production Certificate number: DMT 03 ATEX ZQS / E 110 Notified body: Deutsche Montan Technologie Identification number: 0158

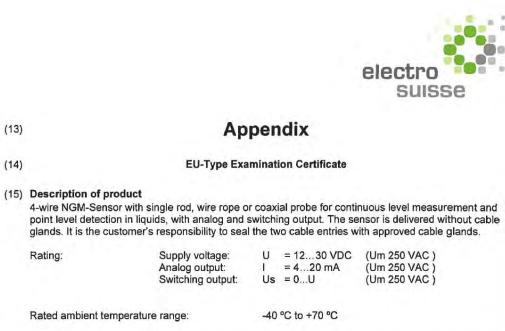
pper. Willing

H. Peters General Manager

M. Wenzel Proxy Holder

# **14. ATEX Certificate**

			electro suisse
		(Ex)	
(1)	EU-	Type Examination	n Certificate
(2)	Equipment or protective sy explosive atmospheres - D	stem intended for use in potential irective 2014/34/EU	У
(3)	Certificate number:	SEV 13 ATEX 0108 X	
	Product:	Level Sensor NGM-xxx	
	Manufacturer:	KOBOLD Messring Gm	ЬН
	Address:	Nordring 22-24, 65719	
(7)	The equipment and any ac the documents therein refe	ceptable variation thereto is spec	ified in the schedule to this certificate
(8)	the European parliament been found to comply with	and of the council, dated 26 Feb the essential health and safety	with article 17 of Directive 2014/34/E ruary 2014, certifies that this product requirements relating to the design sive atmospheres given in Annex II to
		esults are recorded in confidential	report no 09-IK-0358.40 incl. ext1
(9)	Compliance with the essen	tial health and safety requirement	s has been assured by compliance wi
	EN 60079-0:12 + A11:13 EN 60079-26:15	EN 60079-1:14 EN 60079-31:14	EN 60079-11:12
		requirements listed at item 18 of t	
(10)		after the certificate number, it in use specified in the schedule to the	ndicates that the product is subjecte is certificate
(11)		is directive apply to the manufact	and construction of the specified pro- turing process and supply of this pro-
(12)	The marking of the product	shall include the following:	
			II 2G Ex ia db IIC T6 Gb II 2D Ex ia tb IIIC T86 °C IP68 D
Notif Marti	n Plüss uct Certification	Mes .	



The temperature class depends on ambient temperature and application temperature on the sensor. This relations are shown in the following tables:

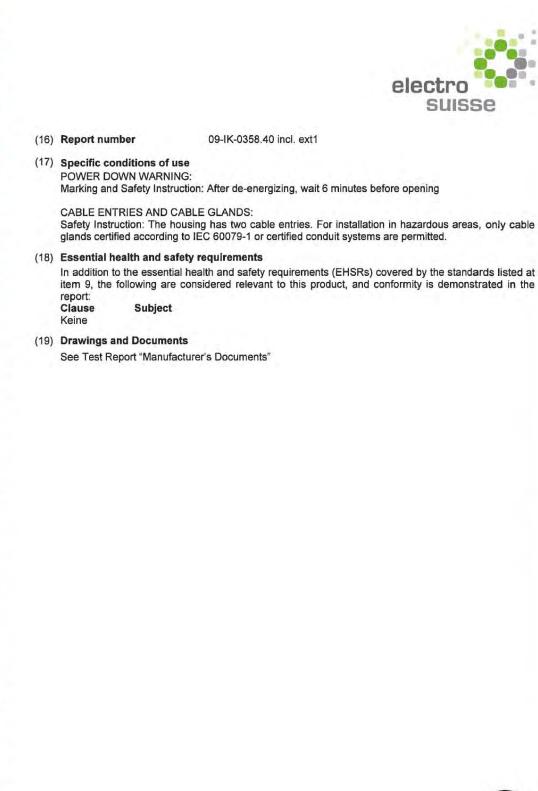
	CATEGORY 1/2G	
Temperature class	Application temperature	Ambient temperature
T1T6	-20+60 °C	-40+70 °C
	CATEGORY 2G	
T6	-40+85 °C	-40+70 °C
T5	-40+100 °C	-40+70 °C
T4	-40+135 °C	-40+70 °C
T1T3	-40+150 °C	-40+70 °C
(	CATEGORY 1/2D and 2D	
max. surface temperature: +86 °C		-40+70 °C



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Fehraltorf, 2016-04-26





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